



RHT-WM-485-LCD, RHT-DM-485-LCD and RHT-P10-485-LCD

TEMPERATURE AND HUMIDITY TRANSMITTER USER GUIDE V2.0x B





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1. SAFETY ALERTS

The symbols below are used in the device and throughout this manual to draw the user's attention to essential information related to device safety and use.



All safety recommendations appearing in this manual must be followed to ensure personal safety and prevent damage to the instrument or system. If the instrument is used in a manner other than that specified in this manual, the device's safety protections may not be effective.

2. INTRODUCTION

RHT-WM-485-LCD, RHT-DM-485-LCD, and RHT-P10-485-LCD transmitters include high accuracy and stability sensors for measuring temperature and relative humidity. They are microprocessed devices and, therefore, allow being entirely configured through a RS485 interface, using the Modbus RTU commands. DigiConfig allows the configuration of all transmitters features as well as its diagnostic procedure.

The transmitter can be configured or displaying the values of measured temperature and **Relative Humidity** or the values of measured temperature and **Dew Point**.

2.1 IDENTIFICATION

The identification label is fixed on the transmitter body. Check if the features described on this label are in accordance with your order.

The RHT-WM-485-LCD and RHT-P10-485-LCD models intended for wall mounting, while the RHT-DM-485-LCD model comes with a probe tip rod for installation in ducts or through walls.

The following elements are located at the front side of the transmitter:



Figure 1 – Transmitter main screen

Communication Indicator (COM): Indicates when the device is receiving data from the Modbus network.

Button (Programming): Button used for configuration of the communication parameters and for screen changing.

Temperature: Value of measured temperature.

Relative Humidity: Value of measured relative humidity.

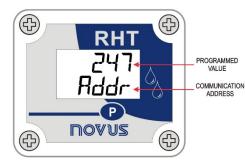


Figure 2 – Transmitter second screen

Communication Address: Value programmed for identifying the transmitter of the Modbus network. Programmable between I and 247.

3. MECHANICAL INSTALLATION

3.1 RHT-DM-485-LCD

The **RHT-DM-485-LCD** (*Duct Mount*) model transmitter must be installed with a flange. This flange is first screwed onto the duct wall, and the transmitter probe is then inserted into the flange central hole and locked. The figure below shows flange dimensions and holes. Available in stainless steel or polyamide 6.6.

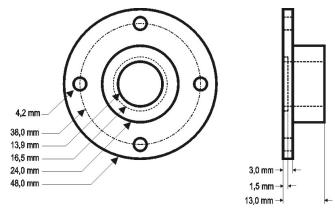


Figure 3 – Flange for fixation of the RHT-DM-485-LCD model

The probe is made in stainless steel, with standard lengths of **150 mm** or **250 mm**.

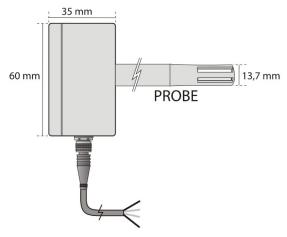


Figure 4 – Dimensions of the RHT-DM-485-LCD model

3.2 RHT-WM-485-LCD

The RHT-WM-485-LCD (*Wall Mount*) model is designed for wall mounting. Removing the transmitter cover gives the user access to two bores for fixing the base, as shown in the figure below.

The transmitter must be fixed with the sensor capsule directed downwards to assure the specific accuracy and protection level.

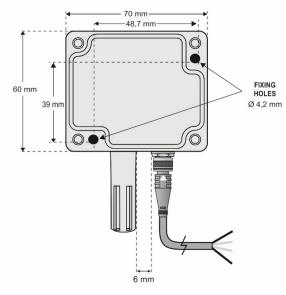


Figure 5 - Fixing bores and dimensions of the RHT-WM-485-LCD model

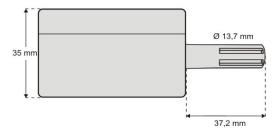


Figure 6 – Dimensions of the RHT-WM-485-LCD model

3.3 RHT-P10-485-LCD

The RHT-P10-485-LCD electronic housing is designed for wall mounting, while its remote sensor probe is intended for inserting and screwing in a flange.

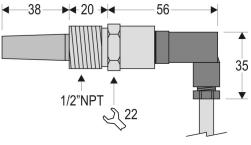
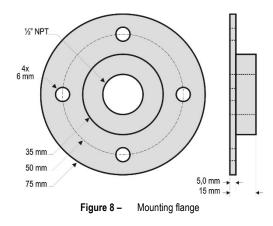


Figure 7 – Remote sensor dimensions





The flange is not bundled with the transmitter. It must be ordered separately.

3.4 TYPES OF TIPS

NOVUS offers 3 types of tips, which can be purchased from authorized distributors:

• **Polyamide tip** (see figure beside): It has side openings that allow the sensor to be more exposed to the environment in which it was installed, having a shorter response time. This tip comes with **RHT**. Order code: 8803900120



• High Density Polyethylene (PE) tip (see figure beside): Made of a porous material, it protects the sensor from dust and other solid particles. However, by reducing contact with the environment to be measured, the response time of this tip tends to be longer than that of the Polyamide tip (see Note 1). Order code: 8803900110

• Sintered Bronze Tip (see figure beside): Made of a porous material, it protects the sensor from dust and other solid particles. It has more mechanical robustness than the Polyethylene tip. However, by reducing contact with the environment to be measured, the response time of this tip tends to be longer (see Note 1). Order code: 8803900100



Note 1: This increase in response time depends, among other things, on the speed of the air (or gas) where the sensor is inserted.

3.4.1 INSTALLATION

- 1. Remove the tip from RHT by slowly unscrewing it. When removing it, take care that only the tip rotates in the equipment.
- 2. The sensor circuit board will be exposed. It must not be touched!
- 3. Screw in the new tip carefully. It is not necessary to force the thread at the end.

4. ELECTRICAL INSTALLATION

The figure below below shows the necessary electrical connection. The terminals 1, 2, 3 and 4 are intended for connection.

1	- VCC			Power supply	Black wire	
2	2 + VCC			Power supply	White wire	
3	3 D1 D D+ A		Α	Bidirectional data line.	Blue wire	
4	D0	D	D-	В	Bidirectional inverted data line.	Brown wire

Table 1 - Electrical connections

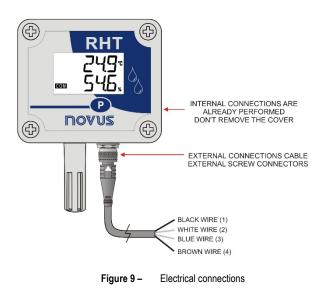




Figure 10 - M8 connector pins



Be careful when connecting the power supply wires to the RHT-WM-485-LCD, RHT-DM-485-LCD and RHT-P10-485-LCD Transmitter.

If the positive wire from the power source is connected, even momentarily, to one of the communication connection terminals, the transmitter may be damaged.

4.1 INSTALLATION RECOMMENDATIONS

- Small electric signal conductors must pass through the system plant separated from the actuating conductors or from high current or voltage lines. If possible, inside grounded conduits.
- The power supply of the instruments must be provided from a proper network for instrumentation.
- In control and monitoring applications it is essential to consider what can happen if any part of the system should fail.
- We recommend the use of RC FILTERS (47Ω and 100nF, series) in parallel with contactor and solenoid coils etc.

5. CONFIGURATION / OPERATION

The user will receive the transmitter perfectly calibrated, without the need for any adjustments. The configuration performed at the factory has the following features:

Rddr (Communication Address) = 247 bRud (Communication speed) = 115200 PRr (Parity) = Par

Stop Bit = 1

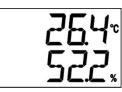
DigiConfig for Windows is a software used for configuration of the RHT-WM-485-LCD, RHT-DM-485-LCD and RHT-P10-485-LCD transmitters. For its installation, run the *DigiConfigSetup.exe* and follow the instructions as shown.

DigiConfig comes with an unabridged help tutorial, containing all the necessary information for you to use it. If you want to use help tutorial, start the application, and select the Help menu or press F1.

Access the site www.novusautomation.com to obtain the installer for DigiConfig and the additional manuals.

5.1 SCREENS OF THE TRANSMITTER

Indication screen for the measured values in the transmitter:



Screen No. 1: Main screen

For configuring the communication parameters, press the \mathbf{P} button (± 5 seconds) until the screen starts blinking, then release the button and press it again to increment. When the desired value appears, release the button, and wait until the screen stops blinking (± 10 seconds). To access the next screens, press the \mathbf{P} button.

Configuration screen for the Modbus Address: Defines the address of the module within the Modbus network. Values between 1 and 247



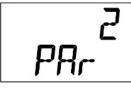
Screen No. 2: Modbus address

Configuration screen for the **Baud Rate**: Defines the Modbus communication speed. Valid values: 1,200, 2,400, 4,800, 9,600, 19,200, 38,400, 57,600 and 115,200.



Screen No. 3: Baud Rate

Configuration screen for the Parity: Defines the parity code used for Modbus communication. Value 0 (none), 1 (odd) and 2 (even).

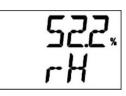


Screen No. 4: Parity

Read-only screens of the values measured by the transmitter:



Screen No. 5: Temperature



Screen No. 6: Relative humidity

1 <u>E</u> L	 ℃
dР	

Screen No. 7: Dew point

6. SERIAL COMMUNICATION

The transmitter is provided with RS485 serial communication, operating as a slave within the Modbus RTU network. The configuration of the transmitter is performed through the serial (RS485) interface. For configuring the communication parameters, you can use the programming putton.

In this section you will find the instructions necessary to perform the data reading without using the **DigiConfig** software. To assure correct configuration of the transmitter, always use the **DigiConfig** software. After being configured, the input data may be accessed by any other software capable for Modbus RTU communication.

6.1 MODBUS COMMANDS

The Modbus RTU commands (functions) listed in the table below are implemented. For further information with respect to each of these commands and the Modbus protocol in general, please access the site <u>www.modbus.org</u>.

READ HOLDING REGISTERS – 0X03

This command can be used for reading the value of one or several holding registers, according to the Holding Registers Table.

WRITE HOLDING REGISTERS - 0X06

This command can be used for writing in a holding register, according to the Holding Registers Table.

6.2 DESCRIPTION OF SOME REGISTERS

6.2.1 REGISTER 2 - BAUD RATE

Defines the Modbus communication speed.

The transmitter comes factory-configured with a Baud Rate of 115200.

CODE	BAUD RATE
0	1.200
1	2.400
2	4.800
3	9.600
4	19.200
5	38.400
6	57.600
7	115.200

Table 2 - Baud Rate

6.2.2 REGISTER 3 – MODBUS ADDRESS

Defines the address of the transmitter within the Modbus network. Values between 1 and 247. The transmitter comes factory-configured with address 247.

6.2.3 REGISTER 4 – PARITY

Defines the parity code used for Modbus communication. The transmitter comes factory-configured with parity even.

CODE	PARITY
0	None
1	Odd
2	Even

Table 3 – Parity

6.2.4 REGISTER 6 – INDICATION MODE

Defines the indication mode on the display of the sensor values readout.

The transmitter comes factory-configured with indication of temperature and relative humidity.

CODE	DESCRIPTION		
0	Indicates temperature and relative humidity.		
1	Indicates temperature and dew point.		
2	Indicates relative humidity and dew point.		
3	Indicates temperature only.		

Table 4 - Indication mode

6.2.5 REGISTER 7 – TEMPERATURE VALUE (°C OR °F)

6.2.6 REGISTER 8 – RELATIVE HUMIDITY VALUE (%)

6.2.7 REGISTER 9 – DEW POINT VALUE (°C OR °F)

Shows the measured value in engineering units. The decimal point is fixed at one place, the value is exhibited without the decimal point and must be considered by the reading software.

6.2.8 REGISTER 10 – CONFIGURATION OF MEASUREMENT UNIT

Defines the measurement unit for the temperature and the dew point.

The transmitter comes factory-configured for degrees Celsius (°C).

CODE	UNITY
0	٥°
1	°F

Table 5 – Unity	Tab	le	5 –	Unity
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6.2.9 REGISTER 11 – DISABLED CONFIGURATION VIA BUTTON

Defines the changes of configuration via button.

CODE	DESCRIPTION			
0	Factory-configured default value.			
1	Disables the configuration change of communication parameters via button.			

Table 6 - Button

6.2.10 REGISTER 12 - USER OFFSET FOR TEMPERATURE

Defines the user Offset value in engineering units for the temperature. The transmitter comes factory-configured with the Offset value equal to 0 (zero).

6.2.11 REGISTER 14 – USER OFFSET FOR HUMIDITY

Defines the user Offset value in engineering units for the relative humidity. The transmitter comes factory-configured with the Offset value equal to 0 (zero).

6.2.12 REGISTER 16 - ERROR VALUE

Shows the error value which is transmitted when the sensor has a problem. The transmitter comes factory-configured with the value -9999.

6.3 HOLDING REGISTERS TABLE

The specified addresses correspond to the low-level physical addresses, where zero (0) corresponds to the PLC 40001 address.

The $\ensuremath{\textbf{Minimum}}$ and $\ensuremath{\textbf{Maximum}}$ columns show the range of values valid for each parameter.

The **R/W** column indicates if the parameter is for reading and writing (R/W) or for reading only (R).

ADDRESS	DESCRIPTION	MINIMUM	MAXIMUM	R/W
0	Serial number (word high)	0	65535	R
1	Serial number (word low)	0	65535	R
2	Baud-Rate	0	7	R/W
3	Modbus Address	1	247	R/W
4	Parity	0	2	R/W
5	Firmware release	0	999	R
6	Indication mode	0	3	R/W
7	Temperature value (°C or °F)*	-400	1000	R
8	Relative humidity value (%)*	0	1000	R
9	Dew point value (°C or °F)*	-400	1000	R
10	Configuration of measurement unit	0	1	R/W
11	Disables configuration via button	0	1	R/W
12	User offset for temperature*	-100	100	R/W
13	Reserved	0	0	R
14	User offset for humidity*	-100	100	R/W
15	Reserved			
16	Error value	-9999	9999	R/W
17	Title	-	-	R/W
18	Title	-	-	R/W
19	Title	-	-	R/W
20	Title	-	-	R/W
21	Title	-	-	R/W
62	Model	0	11	R

Table 7 – Registers

* For the ranges indicated above consider with one decimal place. Example: -100 means -10.0.

7. SPECIAL CARE

The transmitter is an electronic module and, therefore, will need some particular care when handling it:

- When you open the transmitter to fix it, avoid any contact with the electronic circuit due to the risk of damage caused by static electricity.
- Take maximum care when connecting the wires.
- When you close the case, the cover must be replaced correctly, thus assuring the sealing quality of this model.

7.1 CARE WITH SENSORS

The calibration of the humidity sensor may be changed if it is exposed to contaminant vapors or extreme humidity and temperature conditions for long time periods. For accelerating the calibration recovery follow the procedure as described below:

- Remove the sensor from the capsule.
- If there are solid particles on the sensor, wash it with deionized water.
- Place the sensor within 80 °C (+/- 10 °C) oven for 24 hours.
- Keep the sensor in a place at a temperature between 20 and 30 °C and humidity over 75 % RH for 48 hours.
- Place the sensor back in the capsule.

IMPORTANT

The sensor used in this transmitter may be damaged or become out of calibration if it is exposed to chemical agents contaminated atmosphere. Hydrochloric Acid, Nitric Acid, Sulfuric Acid, and Ammonia in high concentrations may damage the sensor. Acetone, Ethanol and Propylene Glycol may cause a reversible measurement error.

8. SPECIFICATIONS

5. SPECIFICATIONS					
FEATURES	RHT-WM-485-LCD	RHT-DM-485-LCD	RHT-P10-485-LCD		
ransmitter emperature operating • WM Model: From -40 °C to 70 °C. • DM Model: From -40 °C to 100 °C. • Sensor and Rod (RHT-DM): See Figure 11.					
Sensor measuring range	Temperature: -40 °C to 100°C. Relative Humidity (RH): 0 to 100 % RH (No Condensing). Dew Point: -40 °C and 100 °C.				
Electromagnetic compatibility	EM 61326:2000				
Measurement accuracy Measurement resolution	See Figure 11. Note: a small measurement error can be eliminated adjusting the OFFSET parameter of the software. Temperature: 0.1 °C. 14 bits (16383 levels) Relative Humidity (RH): 0.1 %. 12 bits (4095 levels)				
Response time	Temperature: Up to 30 s in slow air movement. Humidity: Up to 8 s in smooth air movement (20 to 80 % RH).				
Sampling interval 3 seconds					
Power supply	12 Vdc to 30 Vdc, consumption < 1	6 mA			
Housing	Polycarbonate				
Protection index	Product suitable for applications which require protection class up to IP65 . Electronic module case: IP65. Sensor capsule: IP40.				
Dimensions	60 x 70 x 35 mm				
Configuration software	Configuration software DigiConfig . Menus in Portuguese, English, or Spanish.				
Accessories	Accessories 1.5 m long communication cable (PN: 8813099999).				

Table 8 – Specifications

8.1 MEASUREMENT ACCURACY AND OPERATIONAL LIMITS OF THE SENSORS

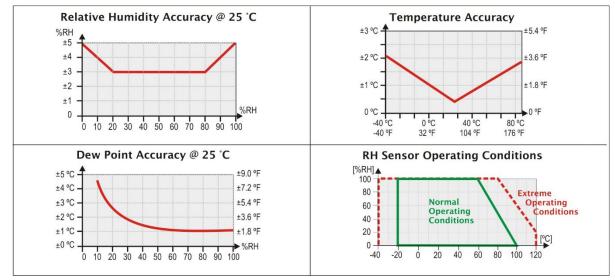


Figure 11 - Accuracy of humidity and temperature measurement

9. WARRANTY

Warranty conditions are available on our website www.novusautomation.com/warranty.