

# TFT DISPLAY SPECIFICATION



**WINSTAR Display Co.,Ltd.**  
**華凌光電股份有限公司**



# Winstar Display Co., LTD

## 華凌光電股份有限公司



WEB: <https://www.winstar.com.tw> E-mail: [sales@winstar.com.tw](mailto:sales@winstar.com.tw)

### SPECIFICATION

**CUSTOMER :** \_\_\_\_\_

**MODULE NO.:** **WF35RTIACDNNB#**

<b>APPROVED BY:</b>  ( FOR CUSTOMER USE ONLY )	<b>PCB VERSION:</b>	<b>DATA:</b>
--	---------------------	--------------

SALES BY	APPROVED BY	CHECKED BY	PREPARED BY
			葉虹蘭
<b>ISSUED DATE: 2021/09/03</b>			

TFT Display Inspection Specification: <https://www.winstar.com.tw/technology/download.html>

Precaution in use of TFT module: <https://www.winstar.com.tw/technology/download/declaration.html>



**RECORDS OF REVISION**

**DOC. FIRST ISSUE**

VERSION	DATE	REVISED PAGE NO.	SUMMARY
0	2018/04/30		First issue
A	2019/10/17		Modify Optical Characteristics
B	2020/06/08		Modify AC Characteristics
C	2021/09/03		Add Initial Code Modify Interface

# Contents

- 1.Module Classification Information
- 2.Summary
- 3.General Specifications
- 4.Absolute Maximum Ratings
- 5.Electrical Characteristics
- 6.AC Characteristics
- 7.Optical Characteristics
- 8.Interface
- 9.Block Diagram
- 10.Reliability
- 11.Contour Drawing
- 12.Initial Code For Reference

# 1.Module Classification Information

W F 35 R T I A C D N N B #  
 ① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨ ⑩ ⑪ ⑫ ⑬

①	Brand : WINSTAR DISPLAY CORPORATION											
②	Display Type : F→TFT Type, J→Custom TFT											
③	Display Size : 3.5” TFT											
④	Model serials no.											
⑤	Backlight Type :	F→CCFL, White S→LED, High Light White					T→LED, White Z→Nichia LED, White					
⑥	LCD Polarize Type/ Temperature range/ Gray Scale Inversion Direction	A→Transmissive, N.T, IPS TFT C→Transmissive, N. T, 6:00 ; F→Transmissive, N.T,12:00 ; I→Transmissive, W. T, 6:00 K→Transflective, W.T,12:00 L→Transmissive, W.T,12:00 N→Transmissive, Super W.T, 6:00					Q→Transmissive, Super W.T, 12:00 R→Transmissive, Super W.T, O-TFT V→Transmissive, Super W.T, VA TFT W→Transmissive, Super W.T, IPS TFT X→Transmissive, W.T, VA TFT Y→Transmissive, W.T, IPS TFT Z→Transmissive, W.T, O-TFT					
⑦	A : TFT LCD B : TFT+SCREW HOLES+CONTROL BOARD C : TFT+ SCREW HOLES +A/D BOARD D : TFT+ SCREW HOLES +A/D BOARD+CONTROL BOARD E : TFT+ SCREW HOLES +POWER BOARD					F : TFT+CONTROL BOARD G : TFT+ SCREW HOLES H : TFT+D/V BOARD I : TFT+ SCREW HOLES +D/V BOARD J : TFT+POWER BD						
⑧	Resolution:											
	A	128160	B	320234	C	320240	D	480234	E	480272	F	640480
	G	800480	H	1024600	I	320480	J	240320	K	800600	L	240400
	M	1024768	N	128128	P	1280800	Q	480800	R	640320	S	480128
	T	800320	U	8001280	V	176220	W	1280398	X	1024250	Y	1920720
	Z	800200	2	1024324	3	7201280	4	19201200	5	1366768	6	1280320
⑨	D: Digital L : LVDS M:MIPI											
⑩	Interface:											
	N	Without control board			A	8Bit		B	16Bit		H	HDMI
	I	I2C Interface			R	RS232		S	SPI Interface		U	USB
⑪	TS:											
	N	Without TS			T	Resistive touch panel			C	Capacitive touch panel (G-F-F)		
	G	Capacitive touch panel (G-G)					C1	Capacitive touch panel (G-F-F)+OCA				
	C2	Capacitive touch panel (G-F-F)+OCR					G1	Capacitive touch panel (G-G)+OCA				
	G2	Capacitive touch panel (G-G)+OCR					B	CTP+GG+USB				
⑫	Version: X:Raspberry pi											
⑬	Special Code #:Fit in with ROHS directive regulations											

--	--	--

WINSTAR DISPLAY CO., LTD

## **2.Summary**

TFT 3.5" is a TN transmissive type color active matrix TFT liquid crystal display that use amorphous silicon TFT as switching devices. This module is a composed of a TFT\_LCD module, It is usually designed for industrial application and this module follows RoHs.

WINSTAR DISPLAY CO., LTD

### **3.General Specifications**

<b>Item</b>	<b>Dimension</b>	<b>Unit</b>
Size	3.5	inch
Dot Matrix	320 x RGBx240(TFT)	dots
Module dimension	76.84(W) x 63.84(H) x 3.27(D)	mm
Active area	70.08 x 52.56	mm
Dot pitch	0.073 x 0.219	mm
LCD type	TFT, Normally White, Transmissive	
View Direction	12 o'clock	
Gray Scale Inversion Direction	6 o'clock	
TFT Interface	8-bit/16-bit CPU or SPI+RGB or SPI (build in controller)	
Aspect Ratio	4:3	
Backlight Type	LED, Normally White	
IC	SSD2119 or Equivalent	
With /Without TP	Without TP	
Surface	Anti-Glare	

\*Color tone slight changed by temperature and driving voltage.



## 4. Absolute Maximum Ratings

Item	Symbol	Min	Typ	Max	Unit
Operating Temperature	TOP	-20	—	+70	°C
Storage Temperature	TST	-30	—	+80	°C

Note: Device is subject to be damaged permanently if stresses beyond those absolute maximum ratings listed above

1. Temp. 60°C, 90% RH MAX. Temp. > 60°C, Absolute humidity shall be less than 90% RH at 60°C

# 5. Electrical Characteristics

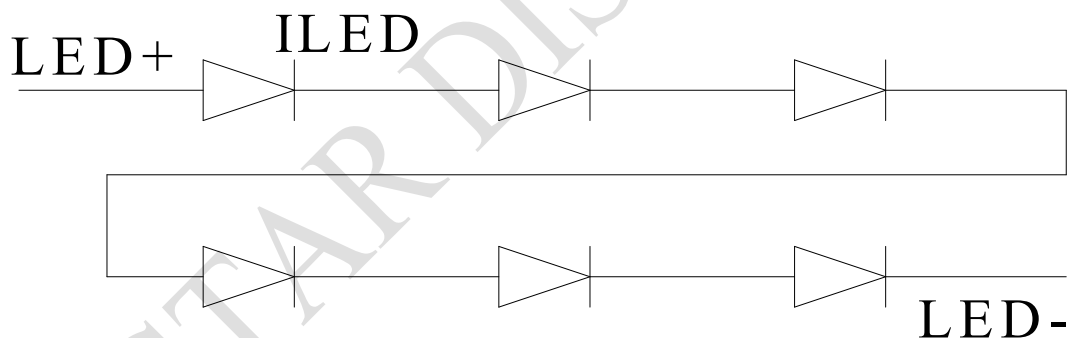
## 5.1. Operating conditions:

Item	Symbol	MIN	TYP	MAX	Unit	Remark
Power supply voltage	VCI	2.5	3.3	3.6	V	
Power supply pin of IO pins	VDDIO	1.4	3.3	3.6	V	
Current consumption	IVCI+IVDDIO	-	6	-	mA	
Dot clock	DCK	-	5.5	8.2	MHz	

## 5.2. LED driving conditions

Parameter	Symbol	Min.	Typ.	Max.	Unit	Remark
LED current		-	20	-	mA	
Power Consumption		348	384	408	mW	
LED voltage	LED+	17.4	19.2	20.4	V	Note 1
LED Life Time		-	50,000	-	Hr	Note 2,3,4

Note 1 : There are 1 Groups LED



Note 2 :  $T_a = 25\text{ }^\circ\text{C}$

Note 3 : Brightness to be decreased to 50% of the initial value

Note 4 : The single LED lamp case

# 6.AC Characteristics

## 6.1. Parallel 6800-series Interface Timing Characteristics

(TA = -40 to 85°C, VDDIO = 1.4V to 2.4)

Symbol	Parameter	Min	Typ	Max	Unit
t <sub>cycle</sub>	Clock cycle time (write cycle)	75	-	-	ns
t <sub>cycle</sub>	Clock cycle time (read cycle) (Based on VOL/VOH = 0.3*VDDIO/0.7*VDDIO)	1000	-	-	ns
t <sub>AS</sub>	Address setup time (R/W)	0	-	-	ns
t <sub>AH</sub>	Address hold time (R/W)	0	-	-	ns
t <sub>DSW</sub>	Data setup time(D0~D7,WRITE)	5	-	-	ns
t <sub>DHW</sub>	Data hold time(D0~D7,WRITE)	5	-	-	ns
t <sub>ACC</sub>	Data access time(D0~D7,READ)	250	-	-	ns
t <sub>OH</sub>	Output hold time(D0~D7,READ)	100	-	-	ns
PW <sub>CSL</sub>	Pulse width/CS low(write cycle)	40	-	-	ns
PW <sub>CSH</sub>	Pulse width/CS high(write cycle)	25	-	-	ns
PW <sub>CSL</sub>	Pulse width/CS low(read cycle)	500	-	-	ns
PW <sub>CSH</sub>	Pulse width/CS high(read cycle)	500	-	-	ns
t <sub>R</sub>	Rise time(/CS)	-	-	15	ns
t <sub>F</sub>	Fall time(/CS)	-	-	15	ns

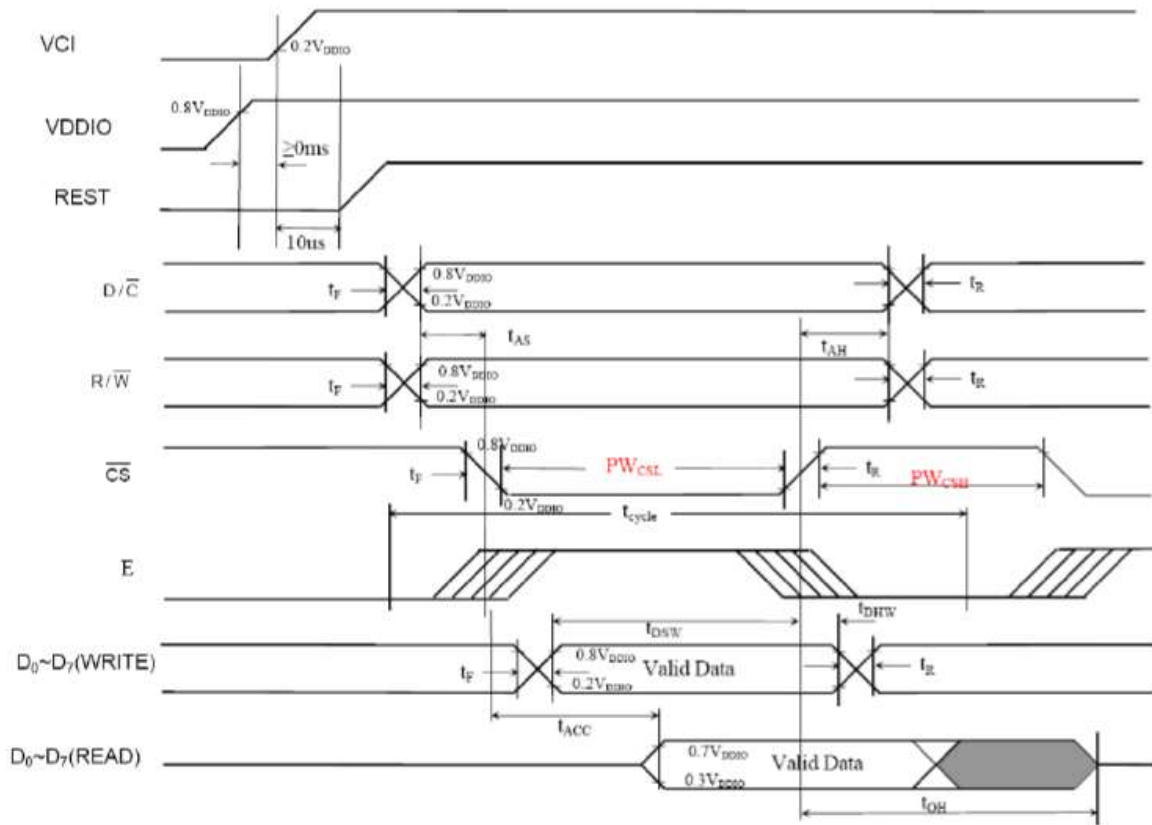
(TA = -40 to 85°C, VDDIO = 2.4V to 3.6V)

Symbol	Parameter	Min	Typ	Max	Unit
t <sub>cycle</sub>	Clock cycle time (write cycle)	75	-	-	ns
t <sub>cycle</sub>	Clock cycle time (read cycle) (Based on VOL/VOH = 0.3*VDDIO/0.7*VDDIO)	450	-	-	ns
t <sub>AS</sub>	Address setup time (R/W)	0	-	-	ns
t <sub>AH</sub>	Address hold time (R/W)	0	-	-	ns
t <sub>DSW</sub>	Data setup time(D0~D7,WRITE)	5	-	-	ns
t <sub>DHW</sub>	Data hold time(D0~D7,WRITE)	5	-	-	ns
t <sub>ACC</sub>	Data access time(D0~D7,READ)	200	-	-	ns
t <sub>OH</sub>	Output hold time(D0~D7,READ)	100	-	-	ns
PW <sub>CSL</sub>	Pulse width/CS low(write cycle)	40	-	-	ns
PW <sub>CSH</sub>	Pulse width/CS high(write cycle)	25	-	-	ns
PW <sub>CSL</sub>	Pulse width/CS low(read cycle)	225	-	-	ns
PW <sub>CSH</sub>	Pulse width/CS high(read cycle)	225	-	-	ns
t <sub>R</sub>	Rise time(/CS)	-	-	15	ns
t <sub>F</sub>	Fall time(/CS)	-	-	15	ns

Note: CS can be pulled low during the write cycle, only /RW is needed to be toggled

WINSTAR DISPLAY CO., LTD

### Parallel 6800-series interface timing characteristics

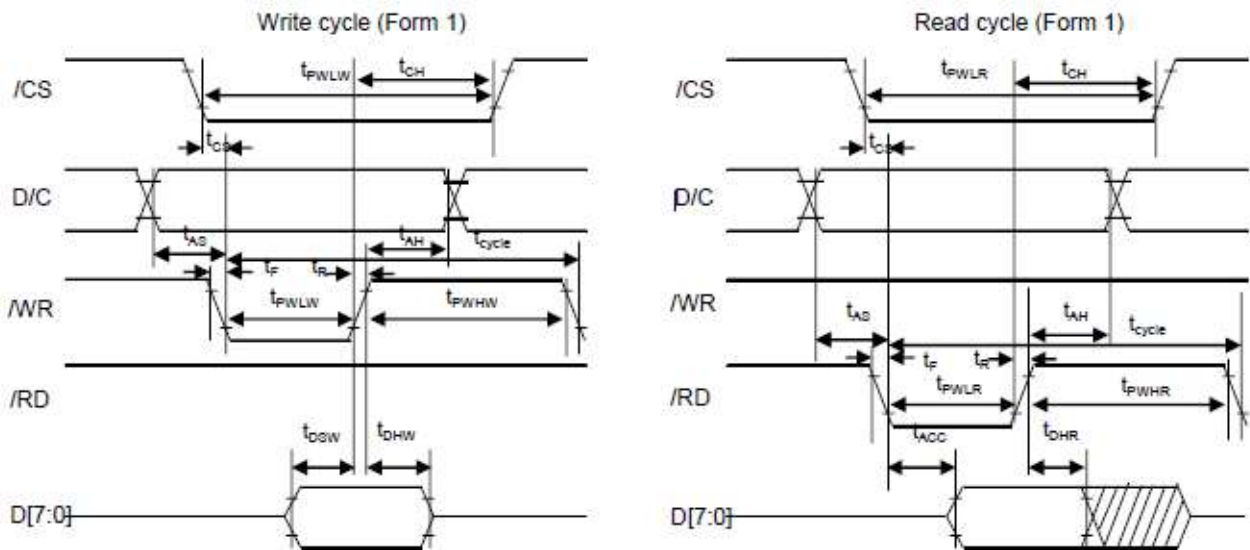


## 6.2. Parallel 8080 Timing Characteristics

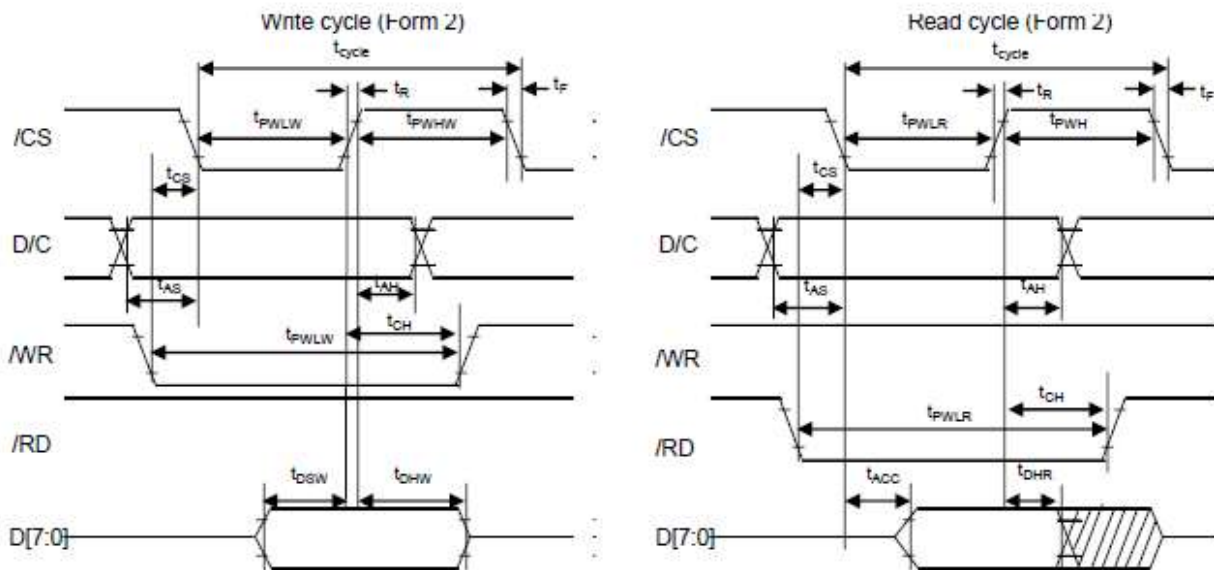
Symbol	Parameter	Min	Typ	Max	Unit
$t_{cycle}$	Clock cycle time (write cycle)	100	-	-	ns
$t_{AS}$	Address setup time	10	-	-	ns
$t_{AH}$	Address hold time	0	-	-	ns
$t_{CS}$	Chip select time	0	-	-	ns
$t_{CH}$	Chip select hold time	0	-	-	ns
$t_{DSW}$	Write Data setup time	10	-	-	ns
$t_{DHW}$	Write Data hold time	10	-	-	ns
$t_{DHR}$	Read Data hold time	100	-	-	ns
$t_{ACC}$	Access time(RAM)	250	-	-	ns
	Access time(command)	250	-	-	ns
$t_{PWLR}$	Chip select low pulse width(read RAM)	500	-	-	ns
$t_{PWLR}$	Chip select low pulse width(read command)	500	-	-	ns
$t_{PWLW}$	Chip select low pulse width(write)	50	-	-	ns
$t_{PWHR}$	Chip select high pulse width(read)	500	-	-	ns
$t_{PWHR}$	Chip select high pulse width(write)	50	-	-	ns
$t_R$	Rise time	-	-	15	ns
$t_F$	Fall time	-	-	15	ns

Note: all timings are based on 20% to 80% of  $V_{DDIO}-V_{SS}$

8080-series parallel interface characteristics (Form 1: /CS low pulse width > W/ R low pulse width)



8080-series parallel interface characteristics (Form 2: /CS low pulse width < W/ R low pulse width)

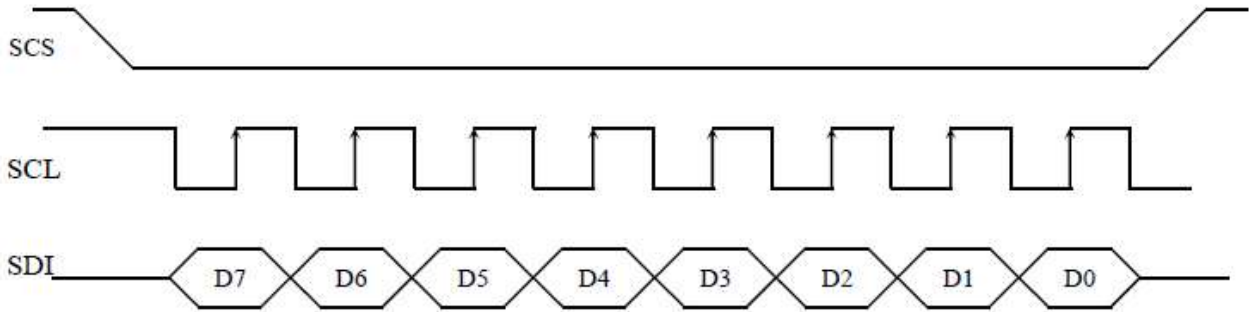
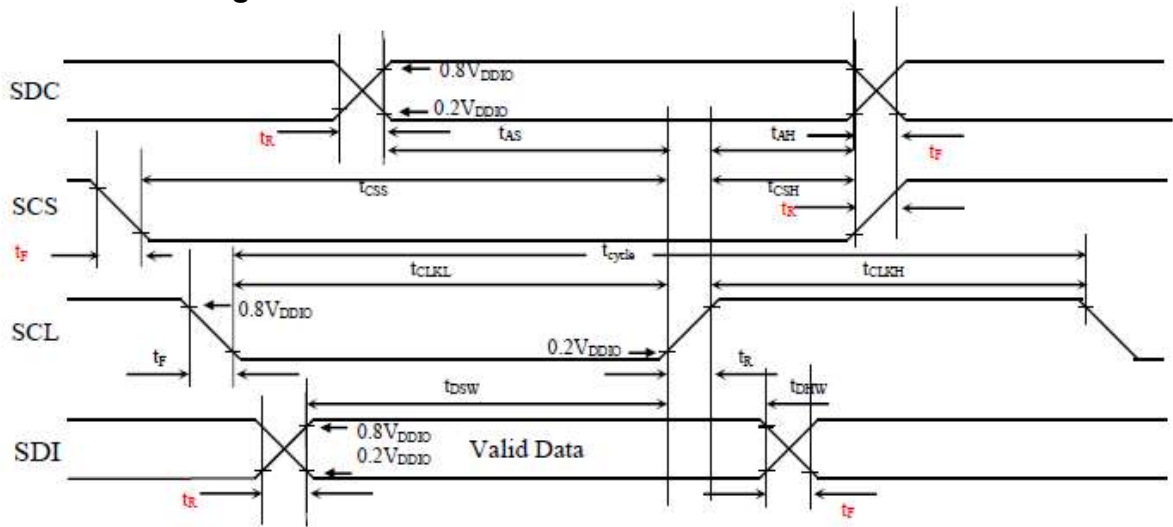


### 6.3. Serial Timing Characteristics

( $T_a = -40$  to  $85^\circ\text{C}$ ,  $V_{DDIO} = 1.4\text{V}$  to  $3.6\text{V}$ )

Symbol	Parameter	Min	Typ	Max	Unit
$t_{\text{cycle}}$	Clock cycle time	77	-	-	ns
$f_{\text{CLK}}$	Serial clock cycle time SPI clock tolerance = +/- 2 ppm	-	-	15	MHz
$t_{\text{AS}}$	Register select setup time	4	-	-	ns
$t_{\text{AH}}$	Register select hold time	5	-	-	ns
$t_{\text{CSS}}$	Chip select setup time	2	-	-	ns
$t_{\text{CSH}}$	Chip select hold time	10	-	-	ns
$t_{\text{DSW}}$	Write Data setup time	5	-	-	ns
$t_{\text{OHW}}$	Write Data hold time	10	-	-	ns
$t_{\text{CLKL}}$	Clock low time	38	-	-	ns
$t_{\text{CLKH}}$	Clock high time	38	-	-	ns
$t_{\text{R}}$	Rise time	-	-	15	ns
$t_{\text{F}}$	Fall time	-	-	15	ns

#### 4 wire serial timing characteristics



WINSTAR DIS



## 6.4. RGB Timing Characteristics

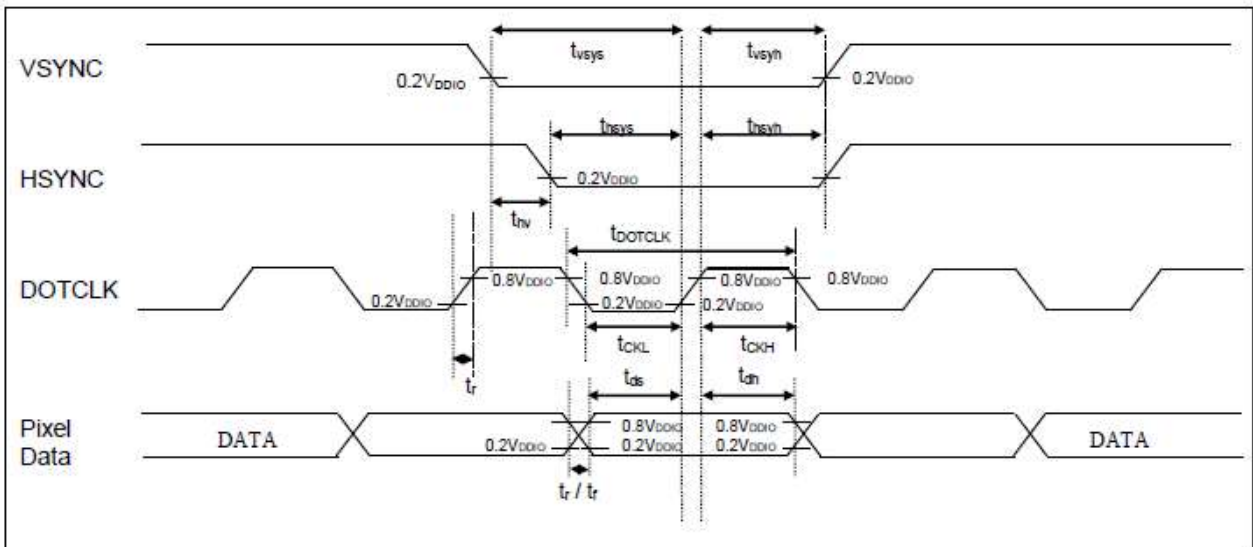
( $T_a = -40$  to  $85^\circ\text{C}$ ,  $V_{DDIO} = 1.4\text{V}$  to  $3.6\text{V}$ )

Symbol	Parameter	Min	Typ	Max	Unit
fDOTCLK	DOTCLK frequency (70Hz frame rate)	1	5.5	8.2	MHZ
tDOTCLK	DOTCLK period	122	182	1000	ns
tVSYN	Vertical sync setup time	20	-	-	ns
tVSYH	Vertical sync hold time	20	-	-	ns
tHSYS	Horizontal sync setup time	20	-	-	ns
tHSYH	Horizontal sync hold time	20	-	-	ns
tHV	Phase difference of sync signal falling edge	0	-	HFP-1	$t_{\text{DOTCLK}}$
tCLK	DOTCLK low period	61	-	-	ns
tCKH	DOTCLK high period	61	-	-	ns
tDS	Data setup time	25	-	-	ns
tDH	Data hold time	25	-	-	ns

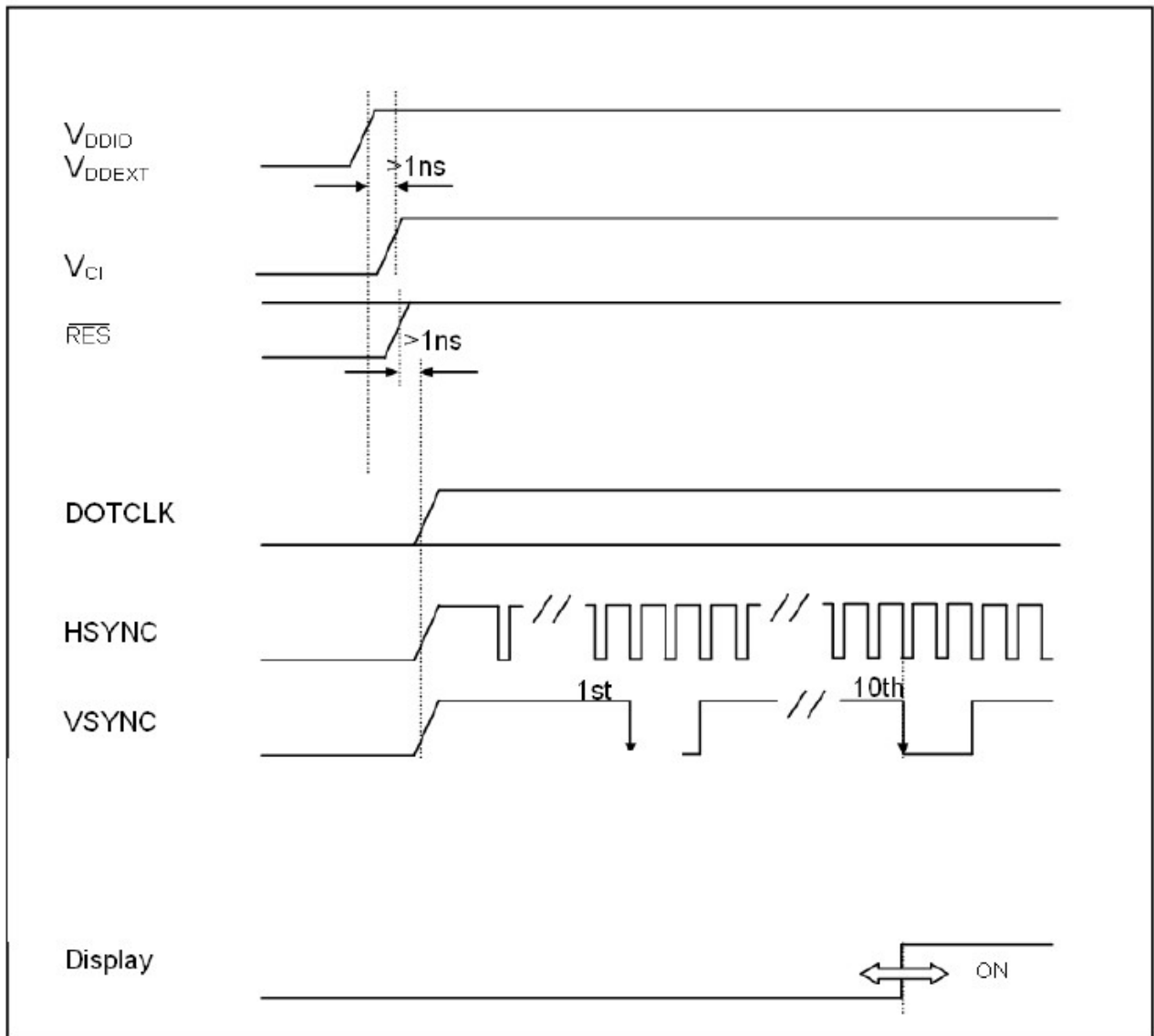
Note: External clock source must be provided to DOTCLK pin of SSD2119M1. The driver will not operate in absence of the clocking signal.

\*HFP: Horizontal Front Porch setting in customers' setup

### RGB timing characteristics



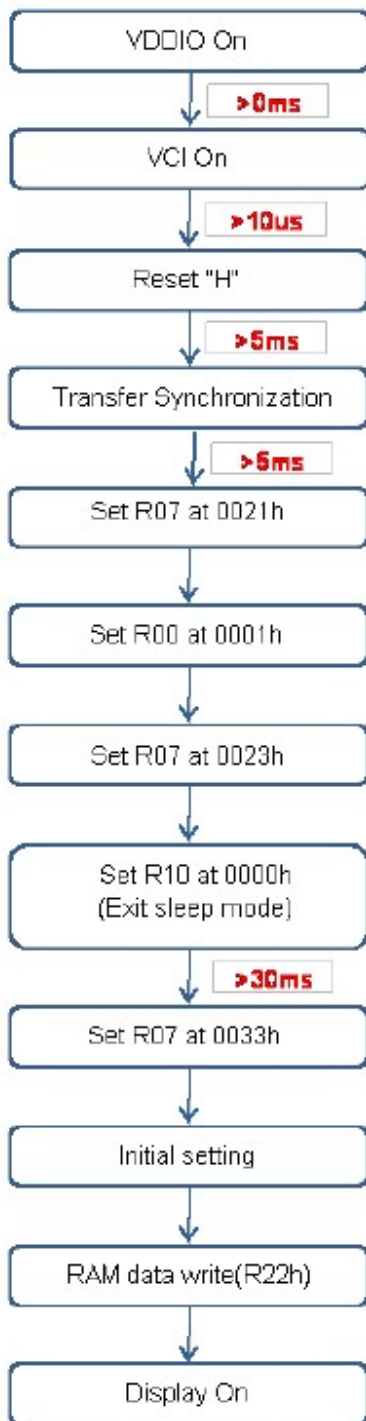
### 6.5. Power Up Sequence for RGB mode



WINSTAR

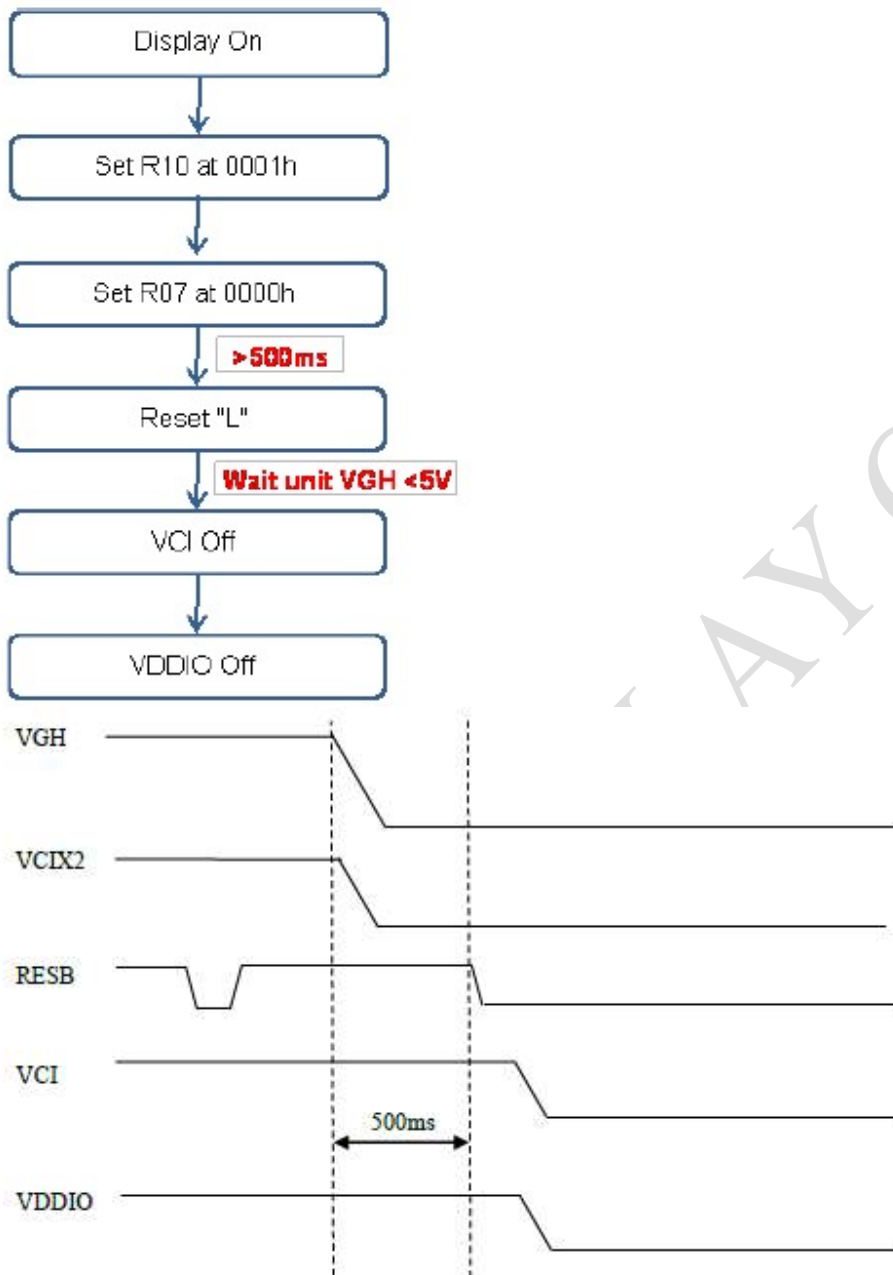
## 6.6. Display on sequence

Note: To prevent potential damage to the device, all capacitors must be discharged to below 0.5V before the driver is removed from, or before the driver is attached to those components.



### 6.7. Display off sequence

Note: To prevent potential damage to the device, all capacitors must be discharged to below 0.5V before the driver is removed from, or before the driver is attached to those components.



Note:

1. VDDIO should be the last to fall, or VCI/VDDIO could be power off at the same time
2. If OTP is active in the application, the OTP programming voltage should be turned off and cap discharged before VCI/VDDIO are turned off.

# 7. Optical Characteristics

Item	Symbol	Condition.	Min	Typ.	Max.	Unit	Remark	
Response time	Tr+ Tf	$\theta=0^\circ \cdot \Phi=0^\circ$	-	25	-	ms	Note 3	
Contrast ratio	CR	At optimized viewing angle	300	-	-	-	Note 4	
Color Chromaticity	White	Wx	$\theta=0^\circ \cdot \Phi=0$	0.26	0.31	0.36	-	Note 2,6,7
		Wy		0.28	0.33	0.38	-	
Viewing angle (Gray Scale Inversion Direction)	Hor.	$\Theta_R$	CR 10	-	60	-	Deg.	Note 1
		$\Theta_L$		-	60	-		
	Ver.	$\Phi_T$		-	50	-		
		$\Phi_B$		-	60	-		
Brightness	-	-	350	400	-	cd/m <sup>2</sup>	Center of display	
Uniformity	(U)	-	75	-	-	%	Note5	

Ta=25±2°C, IL=20mA

Note 1: Definition of viewing angle range

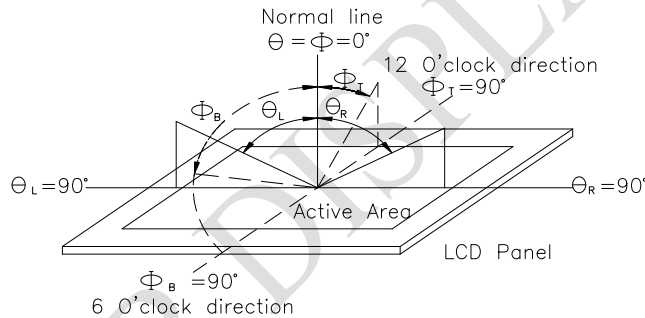


Fig 7.1. Definition of viewing angle

Note 2: Test equipment setup:

After stabilizing and leaving the panel alone at a driven temperature for 10 minutes, the measurement should be executed. Measurement should be executed in a stable, windless, and dark room. Optical specifications are measured by Topcon BM-7 or BM-5 luminance meter 1.0° field of view at a distance of 50cm and normal direction.

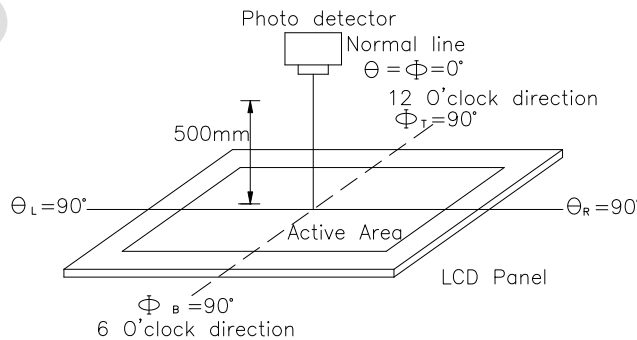
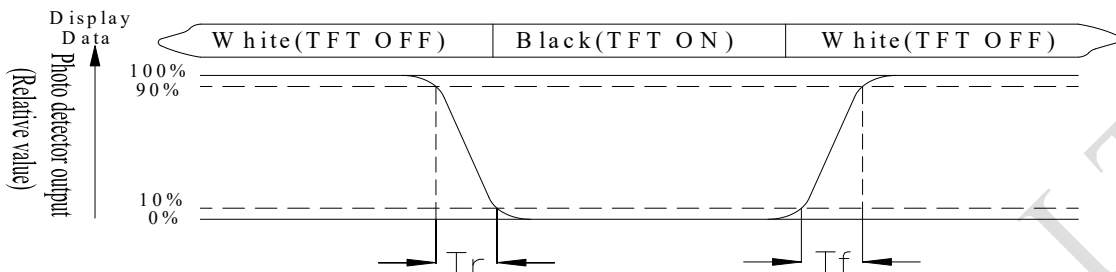


Fig 7.2. Optical measurement system setup

Note 3: Definition of Response time:

The response time is defined as the LCD optical switching time interval between “White” state and “Black” state. Rise time,  $T_r$ , is the time between photo detector output intensity changed from 90% to 10%. And fall time,  $T_f$ , is the time between photo detector output intensity changed from 10% to 90%



Note 4: Definition of contrast ratio:

The contrast ratio is defined as the following expression.

$$\text{Contrast ratio (CR)} = \frac{\text{Luminance measured when LCD on the "White" state}}{\text{Luminance measured when LCD on the "Black" state}}$$

Note 5: Definition of Luminance Uniformity

Active area is divided into 9 measuring areas (reference the picture in below). Every measuring point is placed at the center of each measuring area.

$$\text{Luminance Uniformity (U)} = \text{Lmin/Lmax} \times 100\%$$

L = Active area length

W = Active area width

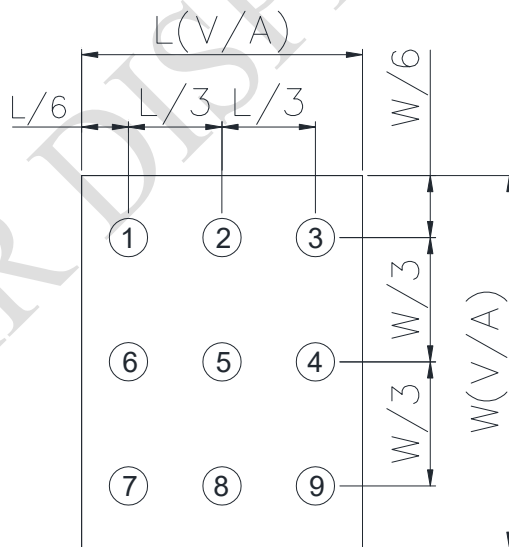


Fig 7.3. Definition of uniformity

Note 6: Definition of color chromaticity (CIE 1931)

Color coordinates measured at the center point of LCD

Note 7: Measured at the center area of the panel when all the input terminals of LCD panel are electrically opened.

WINSTAR DISPLAY CO., LTD

# 8.Interface

## 8.1. LCM PIN Definition

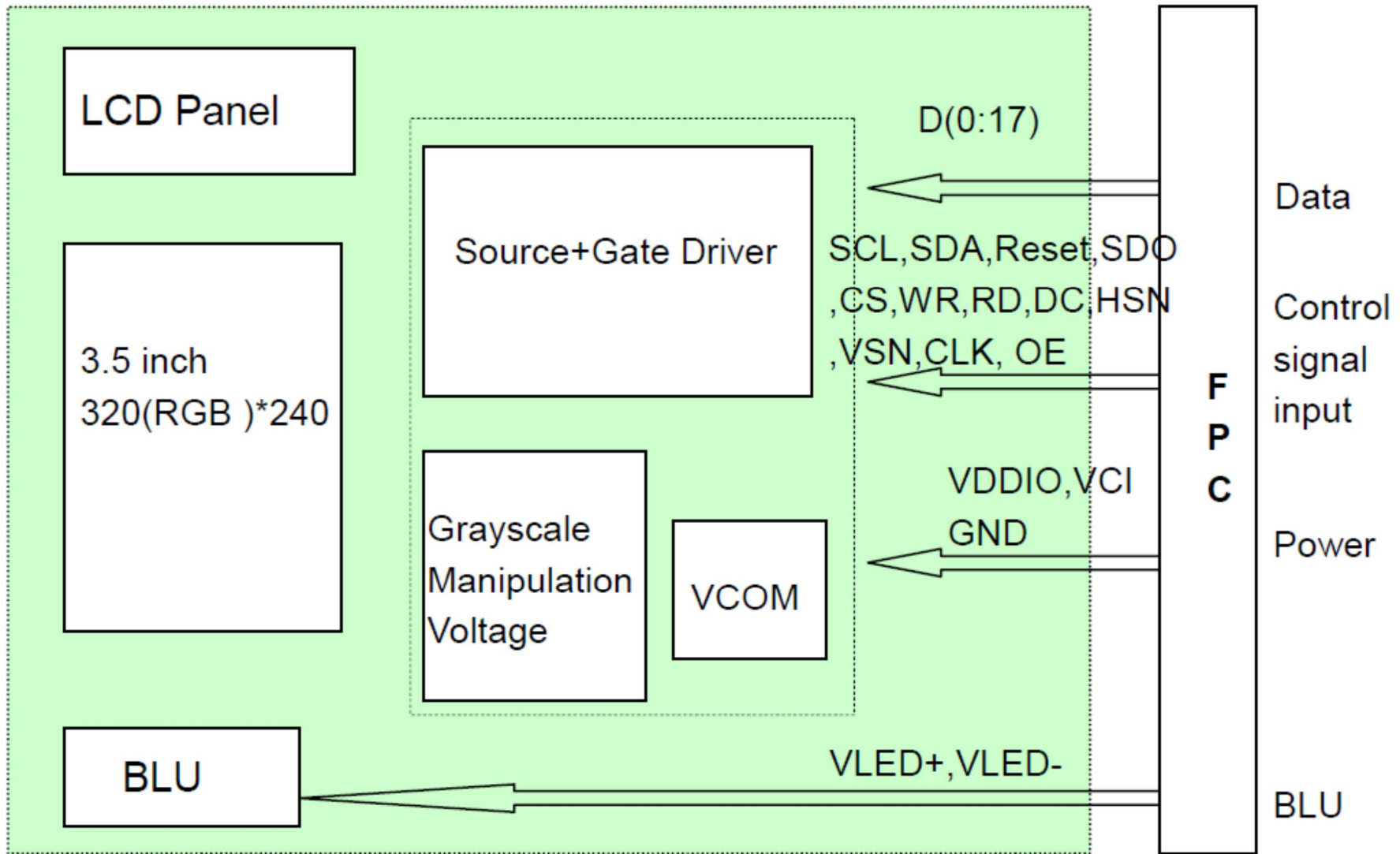
No.	Symbol	Description
1	VCI	Booster input voltage pin
2	VCI	Booster input voltage pin
3	VSS	Ground
4	VDDIO	Voltage input pin for logic
5	VSS	Ground
6	RESET	Reset Signal pin ("Low" is enable)
7	DC/SDC	Data or Command select PIN.
8	E/RD	6800 system: E(enable signal) 8080 system : RD(read strobe signal) Serial mode: Not use and should be connected to VDDIO or VSS
9	WR	6800 system : RW (indicates read cycle when high ,write cycle when low) 8080 system : WR (write strobe signal)
10	CS	Chip select
11	SCL	Serial Clock.
12	SD0	Serial Data output
13	SDI	Serial Data Input
14	WSYNC	Ram write synchronization output. Leave it OPEN when not used.
15~32	D17~D0	Data bus
33	VSS	Ground
34	DOTCLK	Dot-clock signal and oscillator source
35	HSYNC	Line Synchronous Signal
36	VSYNC	Frame Synchronous Signal
37	DE	Display enable pin for controller
38	VSS	Ground
39	PS0	Interface select PIN
40	PS1	
41	PS2	
42	PS3	
43	VSS	Ground
44~47	NC	NC
48	VSS	Ground



<b>49</b>	LEDK	Backlight LED Cathode
<b>50</b>	LEDA	Backlight LED Anode.

<b>PS3</b>	<b>PS2</b>	<b>PS1</b>	<b>PS0</b>	<b>Interface Mode</b>	<b>Data bus input</b>
0	0	0	0	16-bit 6800 parallel interface	D[17:10], D[8:1]
0	0	0	1	8-bit 6800 parallel interface	D[17:10]
0	0	1	0	16-bit 8080 parallel interface	D[17:10], D[8:1]
0	0	1	1	8-bit 8080 parallel interface	D[17:10]
0	1	0	0	9-bit generic D[9:16] (262k colour) + 3-wire SPI If 65K color, D12 shorts to D17 internally	
0	1	0	1	16-bit generic (262k colour) + 3-wire SPI	
0	1	1	0	18-bit generic (262k colour) + 3-wire SPI	
0	1	1	1	6-bit generic D[8:3] (262k colour) + 3-wire SPI	
1	0	0	0	18-bits 6800 parallel interface	D[17:0]
1	0	0	1	9-bits 6800 parallel interface	D[17:9]
1	0	1	0	18-bit 8080 parallel interface	D[17:0]
1	0	1	1	9-bit 8080 parallel interface	D[17:9]
1	1	1	0	3-wire SPI	
1	1	1	1	4-wire SPI	

# 9. Block Diagram



# 10. Reliability

Content of Reliability Test (Wide temperature, -20°C~70°C)

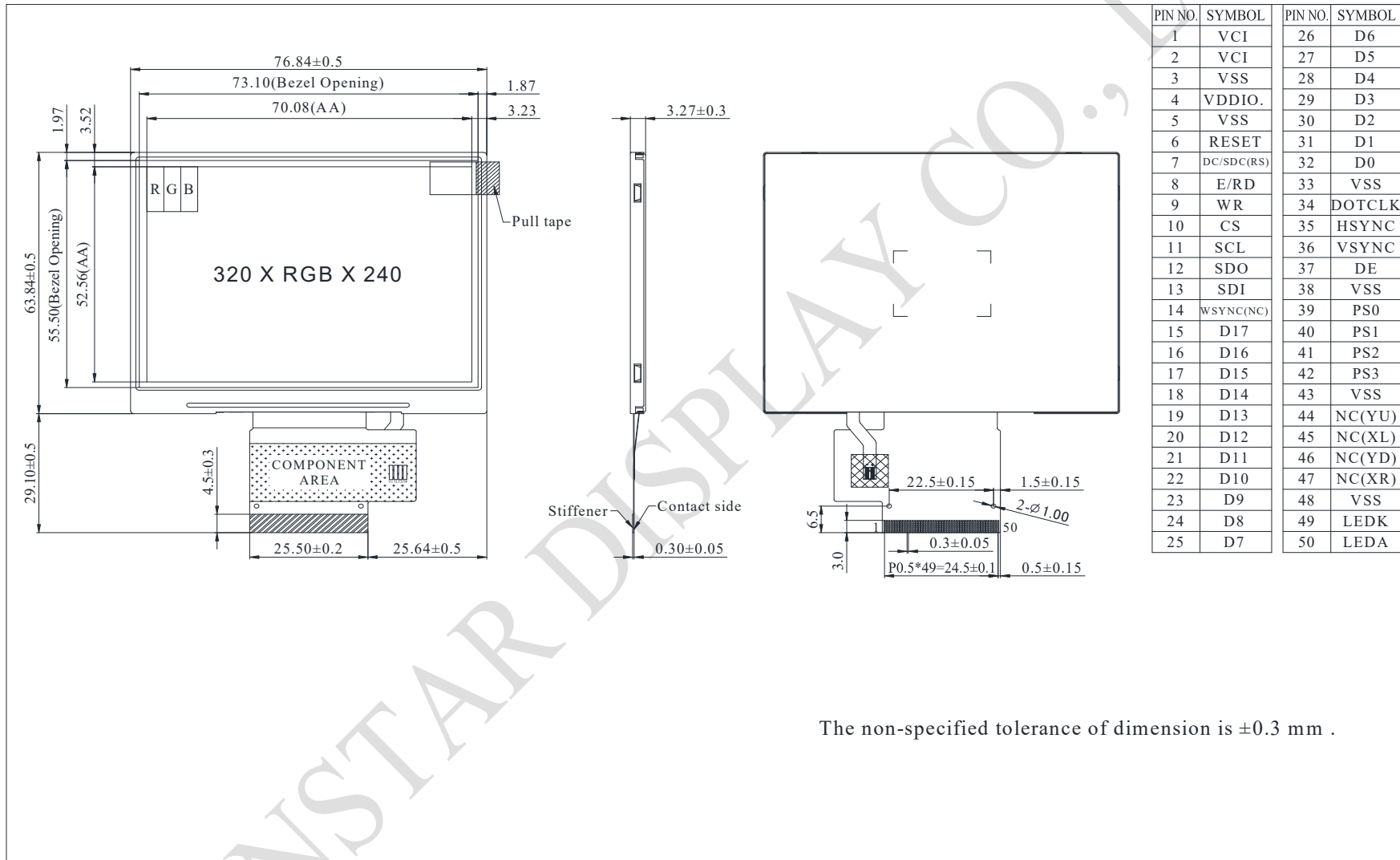
Environmental Test			
Test Item	Content of Test	Test Condition	Note
High Temperature storage	Endurance test applying the high storage temperature for a long time.	80°C 200hrs	2
Low Temperature storage	Endurance test applying the low storage temperature for a long time.	-30°C 200hrs	1,2
High Temperature Operation	Endurance test applying the electric stress (Voltage & Current) and the thermal stress to the element for a long time.	70°C 200hrs	—
Low Temperature Operation	Endurance test applying the electric stress under low temperature for a long time.	-20°C 200hrs	1
High Temperature/ Humidity Operation	The module should be allowed to stand at 60°C,90%RH max	60°C,90%RH 96hrs	1,2
Thermal shock resistance	The sample should be allowed stand the following 10 cycles of operation <div style="text-align: center;"> <p style="margin: 0;">-20°C    25°C    70°C</p> <p style="margin: 0;">30min    5min    30min</p> <p style="margin: 0;">1 cycle</p> </div>	-20°C/70°C 10 cycles	—
Vibration test	Endurance test applying the vibration during transportation and using.	Total fixed amplitude : 1.5mm Vibration Frequency : 10~55Hz One cycle 60 seconds to 3 directions of X,Y,Z for Each 15 minutes	3
Static electricity test	Endurance test applying the electric stress to the terminal.	VS=±600V(contact), ±800v(air), RS=330Ω CS=150pF 10 times	—

Note1: No dew condensation to be observed.

Note2: The function test shall be conducted after 4 hours storage at the normal Temperature and humidity after remove from the test chamber.

Note3: The packing have to including into the vibration testing.

# 11. Contour Drawing



The non-specified tolerance of dimension is ±0.3 mm .

## 12.Initial Code For Reference

/\*\*\*\*\*

**8-bit/16-bit CPU mode initialization**

**Resolution 320x240**

\*\*\*\*\*/

Write\_Command(0x0028);  
Write\_Data16(0x0006);

Write\_Command(0x0000);  
Write\_Data16(0x0001);

Write\_Command(0x0010);  
Write\_Data16(0x0000);

Write\_Command(0x0007);  
Write\_Data16(0x0033);

Write\_Command(0x0011);  
Write\_Data16(0x6230);

Write\_Command(0x0016);  
Write\_Data16(0xffff);  
Write\_Command(0x0017);  
Write\_Data16(0xffff);

Write\_Command(0x0002);  
Write\_Data16(0x0600);

Write\_Command(0x0003);  
Write\_Data16(0xaaae);

Write\_Command(0x0001);

Write\_Data16(0x32EF);

Write\_Command(0x000f);  
Write\_Data16(0x0000);

Write\_Command(0x000b);  
Write\_Data16(0x5208);

Write\_Command(0x000c);  
Write\_Data16(0x0005);

Write\_Command(0x002a);  
Write\_Data16(0x09d5);

Write\_Command(0x000d);  
Write\_Data16(0x000d);

Write\_Command(0x000e);  
Write\_Data16(0x2400);

Write\_Command(0x001e);  
Write\_Data16(0x00ac);

Write\_Command(0x0044);  
Write\_Data16(0xef00);

Write\_Command(0x0045);  
Write\_Data16(0x0000);

Write\_Command(0x0046);  
Write\_Data16(0x013f);

Write\_Command(0x004e);  
Write\_Data16(0x0000);

Write\_Command(0x004f);  
Write\_Data16(0x0000);

Write\_Command(0x0030);  
Write\_Data16(0x0100);

Write\_Command(0x0031);  
Write\_Data16(0x0000);

Write\_Command(0x0032);  
Write\_Data16(0x0106);

Write\_Command(0x0033);  
Write\_Data16(0x0000);

Write\_Command(0x0034);  
Write\_Data16(0x0000);

Write\_Command(0x0035);  
Write\_Data16(0x0403);

Write\_Command(0x0036);  
Write\_Data16(0x0000);

Write\_Command(0x0037);  
Write\_Data16(0x0000);

Write\_Command(0x003a);  
Write\_Data16(0x1100);

Write\_Command(0x003b);  
Write\_Data16(0x0009);

Write\_Command(0x0025);  
Write\_Data16(0xe000);

Write\_Command(0x0026);  
Write\_Data16(0x3800);

WINSTAR DISPLAY CO., LTD

```
/******  
SSD2119 3-Line SPI mode initialization  
Resolution 320x240  
******/
```

```
#define SPI_COMMAND 0  
#define SPI_DATA 1  
  
//Register Address  
#define VCOM_OTP 0x28  
#define OSC_START 0x00  
#define SLEEP_MODE 0x10  
#define DISP_CTRL 0x07  
#define ENTRY_MODE 0x11  
#define H_PORCH 0x16  
#define V_PORCH 0x17  
#define LCD_DRIVER 0x02  
#define PWR_CTRL_1 0x03  
#define DRIVER_OUTPUT 0x01  
  
#define GATE_SCAN_POS 0x0F  
#define CYCLE_CTRL 0x0B  
#define PWR_CTRL_2 0x0C  
#define PWR_CTRL_3 0x0D  
#define PWR_CTRL_4 0x0E  
#define PWR_CTRL_5 0x1E  
#define V_ADDR 0x44  
#define H_STR_ADDR 0x45  
#define H_END_ADDR 0x46  
#define RAM_XADDR 0x4E  
#define RAM_YADDR 0x4F  
  
#define GRAM_WRITE 0x22  
  
void SPI_WRT_3PIN(unsigned char DC, unsigned char dat)  
{  
    unsigned char i;  
  
    SSD2119_CS = 0;  
    SSD2119_SCK = 0;  
    SSD2119_SDA = DC;  
    SSD2119_SCK = 1;  
  
    for(i=0; i < 8; i++)  
    {  
        SSD2119_SCK = 0;  
  
        if(dat&0x80)  
            SSD2119_SDA = 1;  
        else
```



```

        SSD2119_SDA = 0;

        dat <<= 1;
        SSD2119_SCK = 1;
    }

    SSD2119_SCK = 0;
    SSD2119_CS = 1;
}

void LCD_RST(void)
{
    IC_RST = 1;
    delay(6000);

    IC_RST = 0;
    delay(30000);

    IC_RST = 1;

    delay(60000);
    delay(60000);
}

void SSD2119_PWR_ON_SEQUENCE()
{
    SPI_WRT_3PIN(SPI_COMMAND, DISP_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x08);

    SPI_WRT_3PIN(SPI_COMMAND, OSC_START);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x01);

    SPI_WRT_3PIN(SPI_COMMAND, DISP_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x23);

    SPI_WRT_3PIN(SPI_COMMAND, SLEEP_MODE);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
}

```

```

    SPI_WRT_3PIN(SPI_COMMAND, DISP_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x33);
}

void SSD2119_35U_SPI_INIT()
{
    SPI_WRT_3PIN(SPI_COMMAND, ENTRY_MODE);//check sync, den later
    SPI_WRT_3PIN(SPI_DATA, 0x62);
    SPI_WRT_3PIN(SPI_DATA, 0x30);

    SPI_WRT_3PIN(SPI_COMMAND, H_PORCH);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, SSD2119_HBP);

    SPI_WRT_3PIN(SPI_COMMAND, V_PORCH);
    SPI_WRT_3PIN(SPI_DATA, SSD2119_VFP);
    SPI_WRT_3PIN(SPI_DATA, SSD2119_VBP);

    SPI_WRT_3PIN(SPI_COMMAND, LCD_DRIVER); //lcd driver
    SPI_WRT_3PIN(SPI_DATA, 0x06);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

    SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_1);
    SPI_WRT_3PIN(SPI_DATA, 0xaa);
    SPI_WRT_3PIN(SPI_DATA, 0xae);

    SPI_WRT_3PIN(SPI_COMMAND, DRIVER_OUTPUT);
    SPI_WRT_3PIN(SPI_DATA, 0x32);
    SPI_WRT_3PIN(SPI_DATA, 0xEF);

    SPI_WRT_3PIN(SPI_COMMAND, GATE_SCAN_POS);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

    SPI_WRT_3PIN(SPI_COMMAND, CYCLE_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x52);
    SPI_WRT_3PIN(SPI_DATA, 0x08);

    SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_2);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x05);

    SPI_WRT_3PIN(SPI_COMMAND, 0x002a);
    SPI_WRT_3PIN(SPI_DATA, 0x09);
    SPI_WRT_3PIN(SPI_DATA, 0xd5);

    SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_3);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

```

```

SPI_WRT_3PIN(SPI_DATA, 0x0d);

SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_4);
SPI_WRT_3PIN(SPI_DATA, 0x24);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_5);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0xac);

SPI_WRT_3PIN(SPI_COMMAND, V_ADDR);
SPI_WRT_3PIN(SPI_DATA, 0xEF);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, H_STR_ADDR);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, H_END_ADDR);
SPI_WRT_3PIN(SPI_DATA, 0x01);
SPI_WRT_3PIN(SPI_DATA, 0x3F);

SPI_WRT_3PIN(SPI_COMMAND, RAM_XADDR);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, RAM_YADDR);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

//-----Gamma control-----//
SPI_WRT_3PIN(SPI_COMMAND, 0x30);
SPI_WRT_3PIN(SPI_DATA, 0x01);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, 0x31);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, 0x32);
SPI_WRT_3PIN(SPI_DATA, 0x01);
SPI_WRT_3PIN(SPI_DATA, 0x06);

SPI_WRT_3PIN(SPI_COMMAND, 0x33);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, 0x34);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

```

```

SPI_WRT_3PIN(SPI_COMMAND, 0x35);
SPI_WRT_3PIN(SPI_DATA, 0x04);
SPI_WRT_3PIN(SPI_DATA, 0x03);

SPI_WRT_3PIN(SPI_COMMAND, 0x36);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, 0x37);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, 0x3a);
SPI_WRT_3PIN(SPI_DATA, 0x11);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, 0x3b);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x09);

SPI_WRT_3PIN(SPI_COMMAND, 0x25);
SPI_WRT_3PIN(SPI_DATA, 0xe0);
SPI_WRT_3PIN(SPI_DATA, 0x00);

SPI_WRT_3PIN(SPI_COMMAND, 0x26);
SPI_WRT_3PIN(SPI_DATA, 0x38);
SPI_WRT_3PIN(SPI_DATA, 0x00);
}

void main()
{
    LCD_RST();

    SSD2119_PWR_ON_SEQUENCE();

    SSD2119_35U_SPI_INIT();

    SPI_WRT_3PIN(SPI_COMMAND, GRAM_WRITE);

    //start GRAM writing
    //...
    //end GTAM writing
}

```

```
/*  
SSD2119 3-Line SPI +RGB mode initialization  
Resolution 320x240  
*/
```

```
#define SPI_COMMAND 0  
#define SPI_DATA 1  
  
//Register Address  
#define VCOM_OTP 0x28  
#define OSC_START 0x00  
#define SLEEP_MODE 0x10  
#define DISP_CTRL 0x07  
#define ENTRY_MODE 0x11  
#define H_PORCH 0x16  
#define V_PORCH 0x17  
#define LCD_DRIVER 0x02  
#define PWR_CTRL_1 0x03  
#define DRIVER_OUTPUT 0x01  
  
#define GATE_SCAN_POS 0x0F  
#define CYCLE_CTRL 0x0B  
#define PWR_CTRL_2 0x0C  
#define PWR_CTRL_3 0x0D  
#define PWR_CTRL_4 0x0E  
#define PWR_CTRL_5 0x1E  
#define V_ADDR 0x44  
#define H_STR_ADDR 0x45  
#define H_END_ADDR 0x46  
#define RAM_XADDR 0x4E  
#define RAM_YADDR 0x4F  
  
#define GRAM_WRITE 0x22  
  
void SPI_WRT_3PIN(unsigned char DC, unsigned char dat)  
{  
    unsigned char i;  
  
    SSD2119_CS = 0;  
    SSD2119_SCK = 0;  
    SSD2119_SDA = DC;  
    SSD2119_SCK = 1;  
  
    for(i=0; i < 8; i++)  
    {  
        SSD2119_SCK = 0;  
  
        if(dat&0x80)  
            SSD2119_SDA = 1;  
        else
```

```

        SSD2119_SDA = 0;

        dat <<= 1;
        SSD2119_SCK = 1;
    }

    SSD2119_SCK = 0;
    SSD2119_CS = 1;
}

void LCD_RST(void)
{
    IC_RST = 1;
    delay(6000);

    IC_RST = 0;
    delay(30000);

    IC_RST = 1;

    delay(60000);
    delay(60000);
}

void SSD2119_PWR_ON_SEQUENCE()
{
    SPI_WRT_3PIN(SPI_COMMAND, DISP_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x08);

    SPI_WRT_3PIN(SPI_COMMAND, OSC_START);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x01);

    SPI_WRT_3PIN(SPI_COMMAND, DISP_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x23);

    SPI_WRT_3PIN(SPI_COMMAND, SLEEP_MODE);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
    delay(60000);
}

```

```

    SPI_WRT_3PIN(SPI_COMMAND, DISP_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x33);
}

void SSD2119_35U_SPI_INIT()
{
    SPI_WRT_3PIN(SPI_COMMAND, ENTRY_MODE); //check sync, den later
    SPI_WRT_3PIN(SPI_DATA, 0xC7);
    SPI_WRT_3PIN(SPI_DATA, 0x30);

    SPI_WRT_3PIN(SPI_COMMAND, H_PORCH);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, SSD2119_HBP);

    SPI_WRT_3PIN(SPI_COMMAND, V_PORCH);
    SPI_WRT_3PIN(SPI_DATA, SSD2119_VFP);
    SPI_WRT_3PIN(SPI_DATA, SSD2119_VBP);

    SPI_WRT_3PIN(SPI_COMMAND, LCD_DRIVER); //lcd driver
    SPI_WRT_3PIN(SPI_DATA, 0x06);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

    SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_1);
    SPI_WRT_3PIN(SPI_DATA, 0xaa);
    SPI_WRT_3PIN(SPI_DATA, 0xae);

    SPI_WRT_3PIN(SPI_COMMAND, DRIVER_OUTPUT);
    SPI_WRT_3PIN(SPI_DATA, 0x32);
    SPI_WRT_3PIN(SPI_DATA, 0xEF);

    SPI_WRT_3PIN(SPI_COMMAND, GATE_SCAN_POS);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

    SPI_WRT_3PIN(SPI_COMMAND, CYCLE_CTRL);
    SPI_WRT_3PIN(SPI_DATA, 0x52);
    SPI_WRT_3PIN(SPI_DATA, 0x08);

    SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_2);
    SPI_WRT_3PIN(SPI_DATA, 0x00);
    SPI_WRT_3PIN(SPI_DATA, 0x05);

    SPI_WRT_3PIN(SPI_COMMAND, 0x002a);
    SPI_WRT_3PIN(SPI_DATA, 0x09);
    SPI_WRT_3PIN(SPI_DATA, 0xd5);

    SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_3);
    SPI_WRT_3PIN(SPI_DATA, 0x00);

```

```
SPI_WRT_3PIN(SPI_DATA, 0x0d);
```

```
SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_4);  
SPI_WRT_3PIN(SPI_DATA, 0x24);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, PWR_CTRL_5);  
SPI_WRT_3PIN(SPI_DATA, 0x00);  
SPI_WRT_3PIN(SPI_DATA, 0xac);
```

```
SPI_WRT_3PIN(SPI_COMMAND, V_ADDR);  
SPI_WRT_3PIN(SPI_DATA, 0xEF);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, H_STR_ADDR);  
SPI_WRT_3PIN(SPI_DATA, 0x00);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, H_END_ADDR);  
SPI_WRT_3PIN(SPI_DATA, 0x01);  
SPI_WRT_3PIN(SPI_DATA, 0x3F);
```

```
SPI_WRT_3PIN(SPI_COMMAND, RAM_XADDR);  
SPI_WRT_3PIN(SPI_DATA, 0x00);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, RAM_YADDR);  
SPI_WRT_3PIN(SPI_DATA, 0x00);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
//-----Gamma control-----//
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x30);  
SPI_WRT_3PIN(SPI_DATA, 0x01);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x31);  
SPI_WRT_3PIN(SPI_DATA, 0x00);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x32);  
SPI_WRT_3PIN(SPI_DATA, 0x01);  
SPI_WRT_3PIN(SPI_DATA, 0x06);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x33);  
SPI_WRT_3PIN(SPI_DATA, 0x00);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x34);  
SPI_WRT_3PIN(SPI_DATA, 0x00);  
SPI_WRT_3PIN(SPI_DATA, 0x00);
```



```
SPI_WRT_3PIN(SPI_COMMAND, 0x35);
SPI_WRT_3PIN(SPI_DATA, 0x04);
SPI_WRT_3PIN(SPI_DATA, 0x03);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x36);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x37);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x3a);
SPI_WRT_3PIN(SPI_DATA, 0x11);
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x3b);
SPI_WRT_3PIN(SPI_DATA, 0x00);
SPI_WRT_3PIN(SPI_DATA, 0x09);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x25);
SPI_WRT_3PIN(SPI_DATA, 0xe0);
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
SPI_WRT_3PIN(SPI_COMMAND, 0x26);
SPI_WRT_3PIN(SPI_DATA, 0x38);
SPI_WRT_3PIN(SPI_DATA, 0x00);
```

```
}
```

```
void SSD1963_INIT() //To be modified 20210625
```

```
{
```

```
    //sw reset
```

```
    Write_Command(0x01);    //Software Reset
```

```
    delay(10000);
```

```
    //config PLL clk, 0xE2
```

```
    //10MHz to 10MHz
```

```
    Write_Command(0xE2);
```

```
    Write_Data(SSD1963_PLL_M);
```

```
    Write_Data(SSD1963_PLL_N);
```

```
    Write_Data(SSD1963_PLL_C);
```

```
    //turn on PLL
```

```
    Command_Write(0xe0,0x01);    //START PLL
```

```
    delay(10000);
```

```
    //Switch clk source to PLL
```

```
    Command_Write(0xe0,0x03);    //LOCK PLL
```

```
    delay(10000);
```

```

//sw reset
Write_Command(0x01);    //Software Reset
delay(10000);

//configuration dot clk, 0xE6
//10M Hz to 5M Hz
Write_Command(0xE6);
Write_Data(SSD1963_LCDC_FPR_HB);
Write_Data(SSD1963_LCDC_FPR_MB);
Write_Data(SSD1963_LCDC_FPR_LB);

//configuration LCD setting

Write_Command(0xb0);    //SET LCD MODE  SET TFT 18Bits MODE
Write_Data(0x04);
Write_Data(0x20);       //SET TFT MODE & hsync+Vsync+DEN MODE
Write_Data(0x01);       //SET horizontal size=240-1 HightByte
Write_Data(0x3f);       //SET horizontal size=240-1 LowByte
Write_Data(0x00);       //SET vertical size=320-1 HightByte
Write_Data(0xEF);       //SET vertical size=320-1 LowByte
Write_Data(0x00);       //SET even/odd line RGB seq.=RGB

Command_Write(0xf0,0x03); //SET pixel data I/F format=16bit(565 format)
Command_Write(0x36,0x00); // SET read from frame buffer to the display is RGB

Write_Command(0xb4);    //SET HSYNC
Write_Data(0x01);       //SET HSYNC Totol = 440
Write_Data(0xb8);
Write_Data(0x00);       //SET HBP = 68
Write_Data(0x44);
Write_Data(0x07);       //SET VBP 16 = 15 + 1
Write_Data(0x00);       //SET Hsync pulse start position
Write_Data(0x00);       //SET Hsync pulse subpixel start position

Write_Command(0xb6);    //SET VSYNC
Write_Data(0x01);       //SET Vsync total 265 = 264 + 1
Write_Data(0x08);
Write_Data(0x00);       //SET VBP = 19
Write_Data(0x13);
Write_Data(0x07);       //SET Vsync pulse 8 = 7 + 1
Write_Data(0x00);       //SET Vsync pulse start position
Write_Data(0x00);

Write_Command(0x2a);    //SET column address
Write_Data(0x00);       //SET start column address=0
Write_Data(0x00);
Write_Data(0x01);       //SET end column address=240    Write_Data(0x00);
Write_Data(0x3F);       // Write_Data(0xEF);

```

```

Write_Command(0x2b); //SET page address
Write_Data(0x00); //SET start page address=0
Write_Data(0x00); //Write_Data(0x00);
Write_Data(0x00); //SET end page address=320 Write_Data(0x01);
Write_Data(0xEF); //Write_Data(0x3F);

Write_Command(0xb8); //SET GPIO
Write_Data(0x0f); //SET I/O
Write_Data(0x01);

Write_Command(0xba); //SET GPIO
Write_Data(0x01); //SET I/O

delay(1000);
}

void main()
{
LCD_RST();

SSD2119_PWR_ON_SEQUENCE();

SSD2119_35U_SPI_INIT();

SSD1963_INIT();

Write_Command(0x29);

Write_Command(0x2C);

//start GRAM writing
//...
//end GTAM writing
}

```



Module Number : \_\_\_\_\_

**1、Panel Specification :**

- 1. Panel Type :  Pass  NG , \_\_\_\_\_
- 2. View Direction :  Pass  NG , \_\_\_\_\_
- 3. Numbers of Dots :  Pass  NG , \_\_\_\_\_
- 4. View Area :  Pass  NG , \_\_\_\_\_
- 5. Active Area :  Pass  NG , \_\_\_\_\_
- 6. Operating Temperature :  Pass  NG , \_\_\_\_\_
- 7. Storage Temperature :  Pass  NG , \_\_\_\_\_
- 8. Others : \_\_\_\_\_

**2、Mechanical Specification :**

- 1. PCB Size :  Pass  NG , \_\_\_\_\_
- 2. Frame Size :  Pass  NG , \_\_\_\_\_
- 3. Material of Frame :  Pass  NG , \_\_\_\_\_
- 4. Connector Position :  Pass  NG , \_\_\_\_\_
- 5. Fix Hole Position :  Pass  NG , \_\_\_\_\_
- 6. Backlight Position :  Pass  NG , \_\_\_\_\_
- 7. Thickness of PCB :  Pass  NG , \_\_\_\_\_
- 8. Height of Frame to PCB :  Pass  NG , \_\_\_\_\_
- 9. Height of Module :  Pass  NG , \_\_\_\_\_
- 10. Others :  Pass  NG , \_\_\_\_\_

**3、Relative Hole Size :**

- 1. Pitch of Connector :  Pass  NG , \_\_\_\_\_
- 2. Hole size of Connector :  Pass  NG , \_\_\_\_\_
- 3. Mounting Hole size :  Pass  NG , \_\_\_\_\_
- 4. Mounting Hole Type :  Pass  NG , \_\_\_\_\_
- 5. Others :  Pass  NG , \_\_\_\_\_

**4、Backlight Specification :**

- 1. B/L Type :  Pass  NG , \_\_\_\_\_
- 2. B/L Color :  Pass  NG , \_\_\_\_\_
- 3. B/L Driving Voltage (Reference for LED Type) :  Pass  NG , \_\_\_\_\_
- 4. B/L Driving Current :  Pass  NG , \_\_\_\_\_
- 5. Brightness of B/L :  Pass  NG , \_\_\_\_\_
- 6. B/L Solder Method :  Pass  NG , \_\_\_\_\_
- 7. Others :  Pass  NG , \_\_\_\_\_

>> Go to page 2 <<



winstar

Module Number : \_\_\_\_\_

Page: 2

**5、Electronic Characteristics of Module :**

- |                              |                               |                                     |
|------------------------------|-------------------------------|-------------------------------------|
| 1. Input Voltage :           | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 2. Supply Current :          | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 3. Driving Voltage for LCD : | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 4. Contrast for LCD :        | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 5. B/L Driving Method :      | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 6. Negative Voltage Output : | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 7. Interface Function :      | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 8. LCD Uniformity :          | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 9. ESD test :                | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |
| 10. Others :                 | <input type="checkbox"/> Pass | <input type="checkbox"/> NG , _____ |

**6、Summary :**

Sales signature : \_\_\_\_\_

Customer Signature : \_\_\_\_\_

Date :        /        /       

