

### DESCRIPTION

The MP8719 provides a complete power supply with the highest power density for DDR3, DDR3L, LPDDR3, and DDR4 memory. The MP8719 integrates a high-frequency, synchronous, rectified, step-down, switch-mode converter (VDDQ) with a 1A sink/source LDO (VTT) and buffered low-noise reference (VTTREF).

The MP8719 operates at high efficiency over a wide output current load range based on MPS's proprietary switching loss reduction technology and internal low R<sub>DS(ON)</sub> power MOSFETs.

Adaptive constant-on-time (COT) control mode provides fast transient response and eases loop stabilization. The DC auto-tune loop provides good load and line regulation.

The VTT LDO provides 1A of sink/source current capability and requires only a 22µF ceramic capacitor. The VTTREF tracks VDDQ/2 with excellent 1% accuracy.

Full protection features include over-current (OC) limit, over-voltage protection (OVP), under-voltage protection (UVP), over-temperature warning (OTW), and thermal shutdown.

The MP8719 requires a minimal number of external components and is available in a QFN-16 (3mmx3mm) package.

### FEATURES

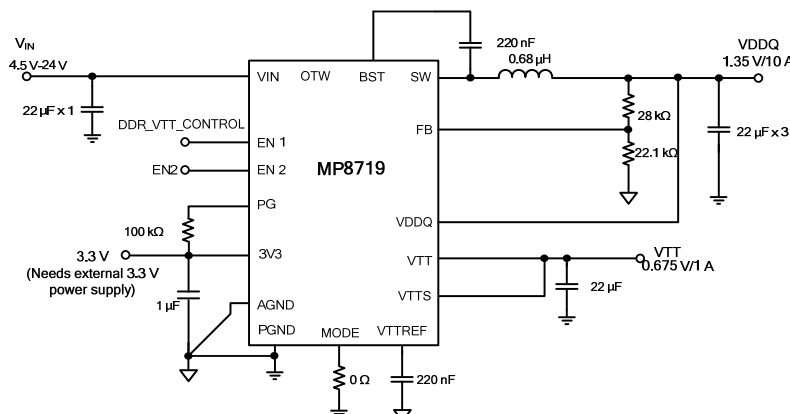
- Wide 4.5V to 26V Operating Input Range
- 135µA Low Quiescent Current
- 12A Continuous Output Current
- 13A Peak Output Current
- Selectable Ultrasonic Mode (USM)
- Selectable 500kHz/700kHz Switching Frequency
- Built-In ±1A VTTLDO
- 1% Buffered VTTREF Output
- Adaptive COT for Fast Transient
- DC Auto-Tune Loop
- Stable with POSCAP and Ceramic Output Capacitors
- Over-Temperature Warning (OTW)
- Internal Soft Start (SS)
- Output Discharge
- OCL, OVP, UVP, and Thermal Shutdown
- Latch-Off Reset via EN or Power Cycle
- Available in a QFN-16 (3mmx3mm) Package

### APPLICATIONS

- Televisions
- Networking Systems
- Distributed Power Systems
- Set-Top-Box

All MPS parts are lead-free, halogen-free, and adhere to the RoHS directive. For MPS green status, please visit the MPS website under Quality Assurance. "MPS" and "The Future of Analog IC Technology" are registered trademarks of Monolithic Power Systems, Inc.

### TYPICAL APPLICATION



### ORDERING INFORMATION

Part Number*	Package	Top Marking
MP8719GQ	QFN-16 (3mmx3mm)	See Below

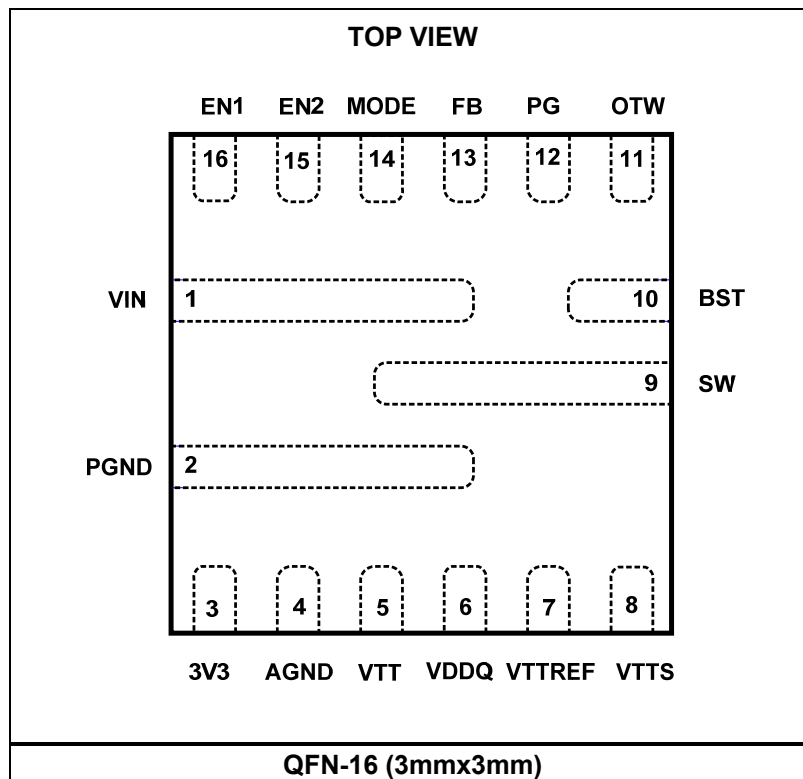
\* For Tape & Reel, add suffix -Z (e.g. MP8719GQ-Z)

### TOP MARKING

AZFY  
LLL

AZF: Product code of MP8719GQ  
 Y: Year code  
 LLL: Lot number

### PACKAGE REFERENCE



**ABSOLUTE MAXIMUM RATINGS** <sup>(1)</sup>

Supply voltage (VIN).....	26V
V <sub>SW</sub> (DC) .....	-1V to VIN + 0.3V
V <sub>SW</sub> (25ns).....	-3.6V to VIN + 4V
V <sub>BST</sub> .....	V <sub>SW</sub> + 4.5V
I <sub>EN1</sub> , I <sub>EN2</sub> .....	100μA
All other pins .....	-0.3V to +4.5V
Continuous power dissipation (T <sub>A</sub> = +25°C) <sup>(2)</sup>	
QFN-16 (3mmx3mm).....	2.3W
Junction temperature .....	150°C
Lead temperature .....	260°C
Storage temperature.....	-65°C to +150°C

**Recommended Operating Conditions** <sup>(3)</sup>

Supply voltage (VIN).....	4.5V to 24V
Supply voltage (V <sub>CC</sub> ) .....	3.15V to 3.5V
Output voltage (V <sub>DDQ</sub> ).....	0.6V to 3.3V <sup>(4)</sup>
I <sub>EN1</sub> , I <sub>EN2</sub> .....	50μA
Operating junction temp. (T <sub>J</sub> )...	-40°C to +125°C

<b>Thermal Resistance</b> <sup>(5)</sup>	<b>θ<sub>JA</sub></b>	<b>θ<sub>JC</sub></b>	
QFN-16 (3mmx3mm).....	55.....	13...	°C/W

**NOTES:**

- 1) Exceeding these ratings may damage the device.
- 2) The maximum allowable power dissipation is a function of the maximum junction temperature T<sub>J</sub>(MAX), the junction-to-ambient thermal resistance θ<sub>JA</sub>, and the ambient temperature T<sub>A</sub>. The maximum allowable continuous power dissipation at any ambient temperature is calculated by P<sub>D</sub>(MAX)=(T<sub>J</sub>(MAX)-T<sub>A</sub>)/θ<sub>JA</sub>. Exceeding the maximum allowable power dissipation produces an excessive die temperature, causing the regulator to go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- 3) The device is not guaranteed to function outside of its operating conditions.
- 4) For applications that need 3.3V < V<sub>out</sub> < 5.5V, special design requirements are needed. Please refer to the Application Information section on page 16. V<sub>DDQ</sub> must be ≤3.3V.
- 5) Measured on JESD51-7, 4-layer PCB.

**ELECTRICAL CHARACTERISTICS**
**V<sub>IN</sub> = 12V, 3V3 = 3.3V, T<sub>J</sub> = 25°C, R<sub>MODE</sub> = 0Ω, unless otherwise noted.**

Parameters	Symbol	Condition	Min	Typ	Max	Units
<b>Supply Current</b>						
3V3 supply current in normal mode	I <sub>3V3</sub>	V <sub>EN1</sub> = V <sub>EN2</sub> = 3V, no load		185		μA
3V3 supply current in S3 mode	I <sub>3V3_S3</sub>	V <sub>EN1</sub> = 0V, V <sub>EN2</sub> = 3V, no load		135		μA
3V3 shutdown current	I <sub>3V3_SDN</sub>	V <sub>EN1</sub> = V <sub>EN2</sub> = 0V, no load			1	μA
<b>MOSFET</b>						
High-side switch on resistance	HS <sub>RDS-ON</sub>	T <sub>J</sub> = 25°C		19.5		mΩ
Low-side switch on resistance	LS <sub>RDS-ON</sub>	T <sub>J</sub> = 25°C		6.6		mΩ
Switch leakage	SW <sub>LKG</sub>	V <sub>EN</sub> = 0V, V <sub>SW</sub> = 0V		0	1	μA
<b>Current Limit</b>						
Low-side valley current limit	I <sub>LIMIT</sub>		12	13	14	A
<b>Switching Frequency and Minimum Off Time</b>						
Switching frequency	F <sub>S</sub>	R <sub>MODE</sub> = 0Ω		700		kHz
		R <sub>MODE</sub> = 150kΩ		500		kHz
Constant on timer	T <sub>ON</sub>	V <sub>IN</sub> = 6V, V <sub>OUT</sub> = 3V, R <sub>MODE</sub> = 150kΩ	1100	1200	1300	ns
Minimum on time <sup>(6)</sup>	T <sub>ON_MIN</sub>			70		ns
Minimum off time <sup>(6)</sup>	T <sub>OFF_MIN</sub>			300		ns
<b>Ultrasonic Mode (USM)</b>						
Ultrasonic mode operation period	T <sub>USM</sub>	V <sub>FB</sub> = 0.62V		32		μs
<b>Protection</b>						
OVP threshold	V <sub>OVP</sub>		125	130	135	%V <sub>REF</sub>
UVP-1 threshold	V <sub>UVP-1</sub>		70%	75%	80%	V <sub>REF</sub>
UVP-1 foldback timer <sup>(6)</sup>	T <sub>UVP-1</sub>			30		μs
UVP-2 threshold	V <sub>UVP-2</sub>		45%	50%	55%	V <sub>REF</sub>
<b>Reference and Soft Start, Soft Stop</b>						
Reference voltage	V <sub>REF</sub>		594	600	606	mV
Feedback current	I <sub>FB</sub>	V <sub>FB</sub> = 0.62V		10	50	nA
Soft-start time	T <sub>SStart</sub>	EN to PG up	1.8	2.2	2.6	ms
Soft-stop time	T <sub>SStop</sub>			2		ms
<b>Enable (EN) and Under-Voltage Lockout (UVLO)</b>						
EN1 rising threshold	V <sub>EN1_TH</sub>		0.54	0.59	0.64	V
EN1 hysteresis	V <sub>EN1-HYS</sub>			125		mV
EN2 rising threshold	V <sub>EN2_TH</sub>		1.12	1.22	1.32	V
EN2 hysteresis	V <sub>EN2-HYS</sub>			125		mV
Enable input current	I <sub>EN1/2</sub>	V <sub>EN1/2</sub> = 2V			5	μA
		V <sub>EN1/2</sub> = 0V			1	

**ELECTRICAL CHARACTERISTICS (continued)**
**V<sub>IN</sub> = 12V, 3V3 = 3.3V, T<sub>J</sub> = 25°C, R<sub>MODE</sub> = 0Ω, unless otherwise noted.**

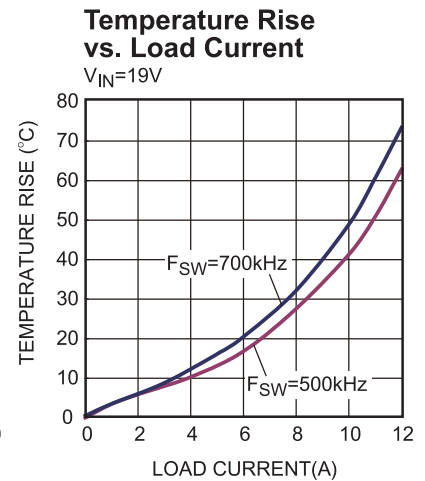
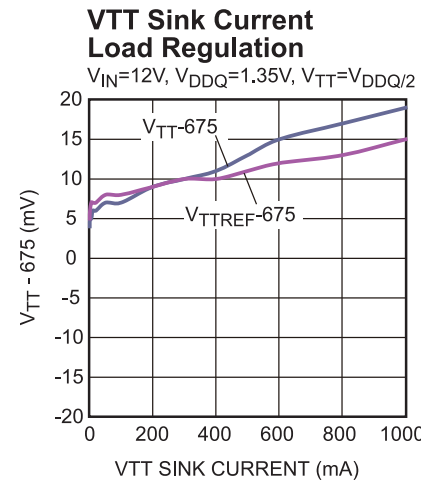
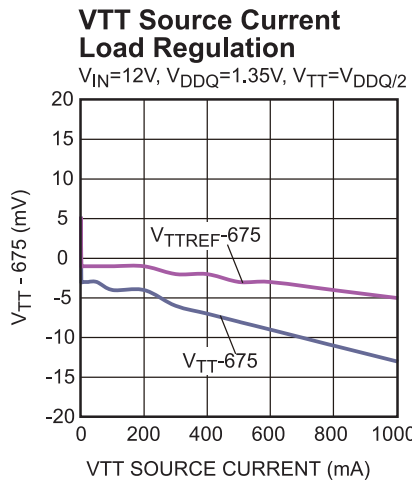
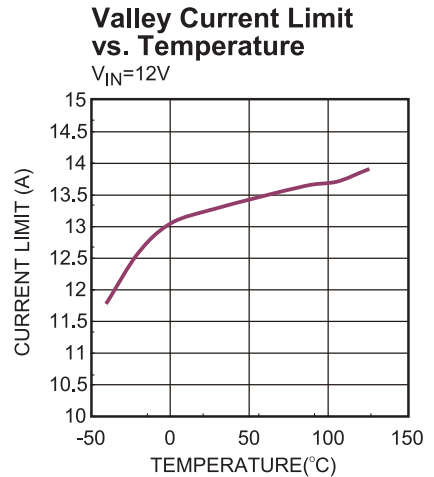
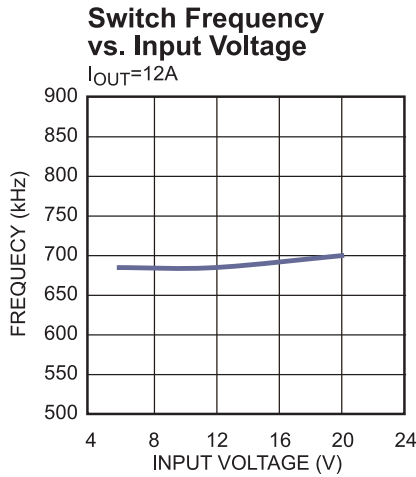
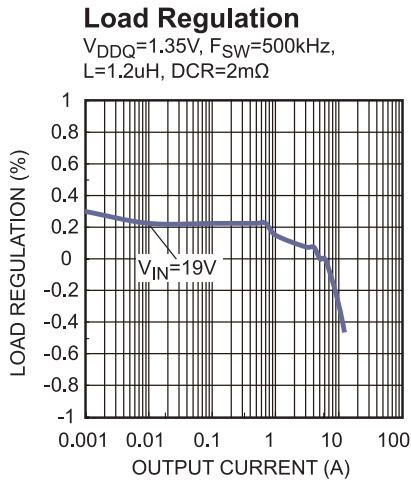
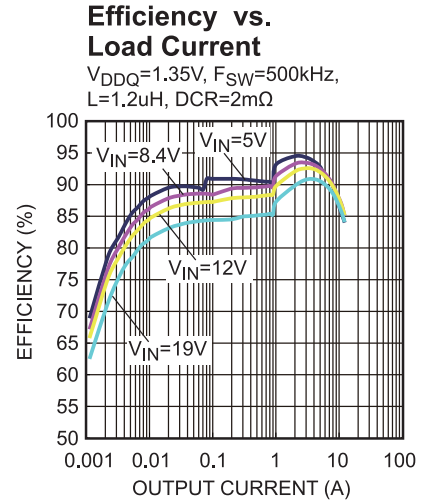
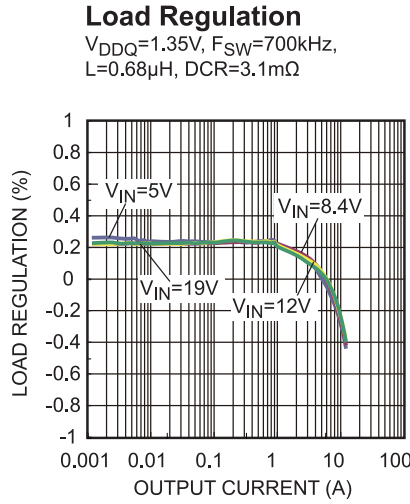
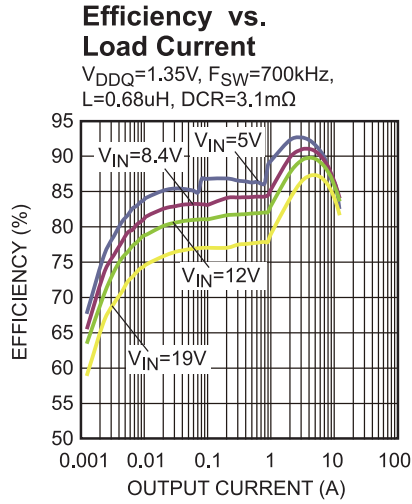
Parameters	Symbol	Condition	Min	Typ	Max	Units
VCC UVLO threshold rising	VCC <sub>Vth</sub>		2.9	3.0	3.1	V
VCC UVLO threshold hysteresis	VCC <sub>HYS</sub>			220		mV
VIN UVLO threshold rising	VIN <sub>VTH</sub>			4.2	4.4	V
VIN UVLO threshold hysteresis	VIN <sub>HYS</sub>			360		mV
<b>Power Good (PG)</b>						
PG when FB rising (good)	PG <sub>Rising(GOOD)</sub>	V <sub>FB</sub> rising, percentage of V <sub>FB</sub>		95		%
PG when FB falling (fault)	PG <sub>Falling(Fault)</sub>	V <sub>FB</sub> falling, percentage of V <sub>FB</sub>		90		
PG when FB rising (fault)	PG <sub>Rising(Fault)</sub>	V <sub>FB</sub> rising, percentage of V <sub>FB</sub>		115		
PG when FB falling (good)	PG <sub>Falling(GOOD)</sub>	V <sub>FB</sub> falling, percentage of V <sub>FB</sub>		105		
PG low to high delay	PG <sub>Td</sub>			3		μs
EN low to PG low delay	PG <sub>Td_EN low</sub>				1	μs
PG sink current capability	V <sub>PG</sub>	Sink 4mA			0.4	V
<b>VTTREF Output</b>						
VTTREF output voltage	V <sub>TTREF</sub>			V <sub>DDQ</sub> /2		
Output voltage tolerance to VDDQ	V <sub>TTREF</sub> /V <sub>DDQ</sub>	I <sub>VTTREF</sub> < 0.1mA, 1V < V <sub>DDQ</sub> < 1.5V	49.2%	50%	50.8%	
		I <sub>VTTREF</sub> < 10mA, 1V < V <sub>DDQ</sub> < 1.5V	49%	50%	51%	
Current limit	I <sub>LIMIT VTTREF</sub>		13	15		mA
<b>VTT LDO</b>						
VTT output voltage	V <sub>TT</sub>			V <sub>DDQ</sub> /2		
VTT tolerance to VTTREF	V <sub>TT</sub> -V <sub>TTREF</sub>	-10mA < I <sub>VTT</sub> < 10mA, V <sub>DDQ</sub> = [1V - 1.5V]	-15		15	mV
		-0.6A < I <sub>VTT</sub> < 0.6A, V <sub>DDQ</sub> = [1V - 1.5V]	-20		20	mV
		-1A < I <sub>VTT</sub> < 1A, V <sub>DDQ</sub> = [1V - 1.5V]	-25		25	mV
Source current limit	I <sub>LIMIT SOURCE</sub>		1.2	1.5		A
Sink current limit	I <sub>LIMIT SINK</sub>		1.2	1.5		A
<b>OTW</b>						
Over-temperature warning <sup>(6)</sup>	T <sub>OTW</sub>			130		°C
OTW hysteresis <sup>(6)</sup>	T <sub>OTW HYS</sub>			25		°C
OTW sink current capability	V <sub>OTW</sub>	Sink 4mA			0.4	V
OTW leakage current	I <sub>OTW</sub>	V <sub>OTW</sub> = 3.3V			1	μA
OTW assertion time <sup>(6)</sup>	T <sub>OTW</sub>			32		ms
<b>Thermal Protection</b>						
Thermal shutdown <sup>(6)</sup>	T <sub>SD</sub>			145		°C
Thermal shutdown hysteresis	T <sub>SD_HYS</sub>			25		°C

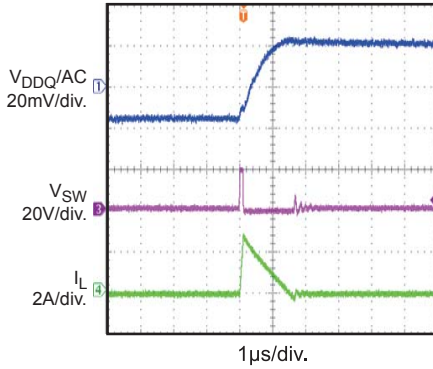
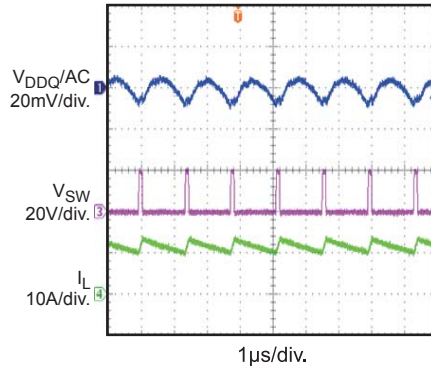
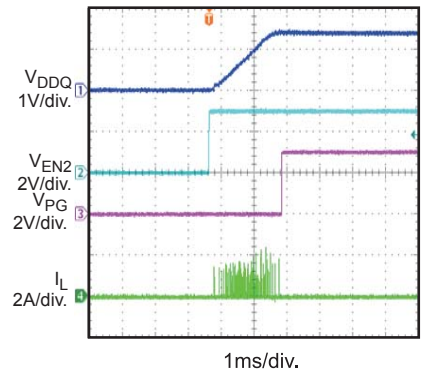
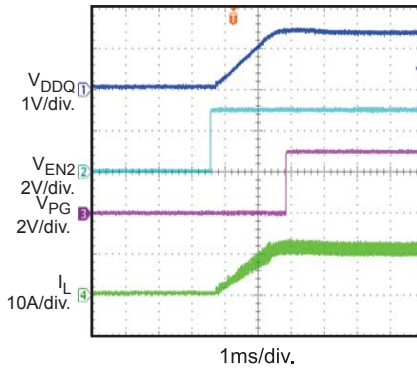
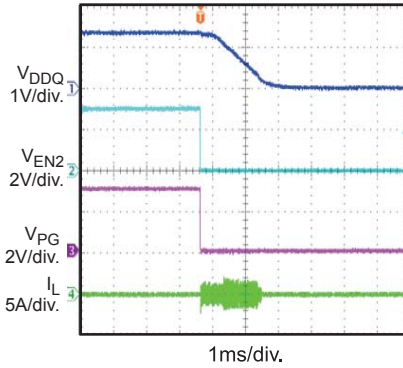
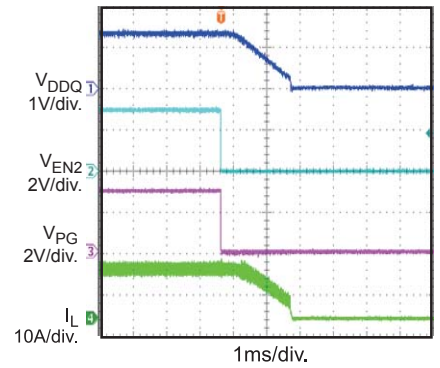
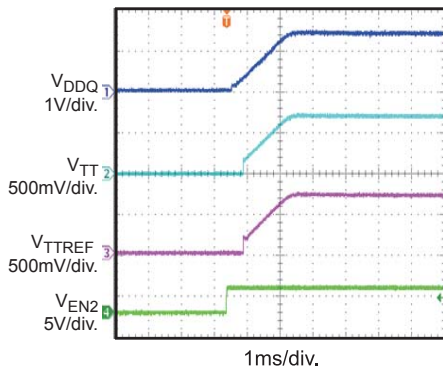
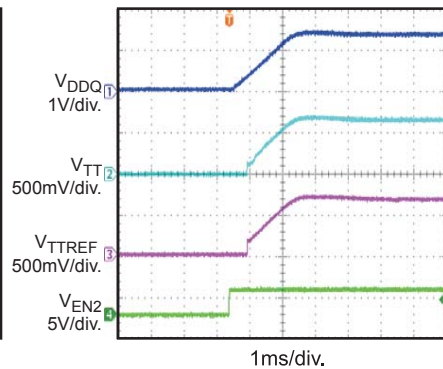
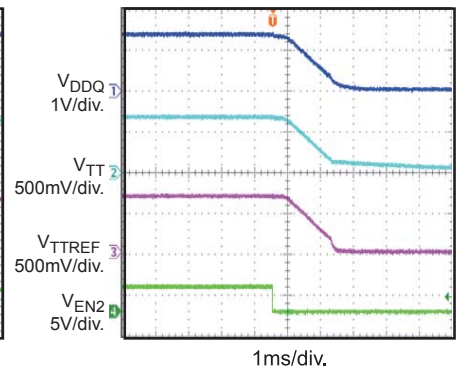
**NOTE:**

6) Guaranteed by design.

**PIN FUNCTIONS**

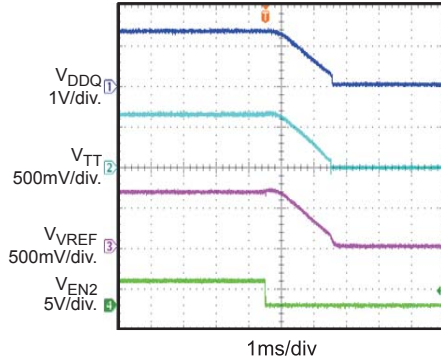
PIN #	Name	Description
1	VIN	<b>Supply voltage.</b> VIN supplies power for the internal MOSFET and regulators. The MP8719 operates from a +4.5V to +26V input rail. An input capacitor is needed to decouple the input rail. Use wide PCB traces and multiple vias to make the connection.
2	PGND	<b>Power ground.</b> Use wide PCB traces and multiple vias to make the connection.
3	3V3	<b>External 3V3 VCC input for control and driver.</b> Place a 1μF decoupling capacitor close to 3V3 and AGND. It is recommended to form an R-C filter.
4	AGND	<b>Analog ground.</b> The internal reference is referred to AGND. Connect GND of the FB divider resistor to AGND for better load regulation.
5	VTT	<b>VTT LDO output.</b> Decouple with a minimum 22μF ceramic capacitor as close to VTT as possible. X7R or X5R grade dielectric ceramic capacitors are recommended for their stable temperature characteristics.
6	VDDQ	<b>Input of VTTLDO.</b> VDDQ is also used for V <sub>OUT</sub> sense. Do not float VDDQ at any time. Connect VDDQ to the output capacitor of the regulator directly with a thick (>100mil) trace.
7	VTTREF	<b>Buffered VTT reference output.</b> Decouple VTTREF with a minimum 0.22μF ceramic capacitor as close to it as possible. X7R or X5R grade dielectric ceramic capacitors are recommended for their stable temperature characteristics.
8	VTTs	<b>VTT output sense.</b> Connect VTTs to the output capacitor of the VTT regulator directly.
9	SW	<b>Switch output.</b> Connect SW to the inductor and bootstrap capacitor. SW is connected to VIN when the HS-FET is on. SW is connected to PGND when the LS-FET is on. Use wide and short PCB traces to make the connection. SW is noisy, so keep sensitive traces away from SW.
10	BST	<b>Bootstrap.</b> A capacitor connected between SW and BST is required to form a floating supply across the high-side switch driver.
11	OTW	<b>Over-temperature status.</b> OTW is used to indicate that the MP8719 is close to OTP. OTW is pulled low once the junction temperature is higher than the over-temperature warning threshold. OTW can be left open if not used.
12	PG	<b>Power good output.</b> PG is an open-drain signal. PG is high if the output voltage is within a proper range.
13	FB	<b>Feedback.</b> An external resistor divider from the output to GND (tapped to FB) sets the output voltage. Place the resistor divider as close to FB as possible. Avoid vias on the FB traces.
14	MODE	<b>Switching frequency and ultrasonic mode selection.</b> A 1% pull-down resistor is needed on MODE.
15	EN2	<b>Enable.</b> EN1 and EN2 are digital inputs which are used to enable or disable the internal regulators. Once EN1 = EN2 = 1, the VDDQ regulator, VTT LDO, and VTTREF output are turned on. When EN1 = 0 and EN2 = 1, all the regulators are on except VTT LDO. All regulators are turned off when EN2 = 0 or EN1 = EN2 = 0. Do not float EN1 at any time. If the VTT LDO function is not used, tie EN1 to GND.
16	EN1	

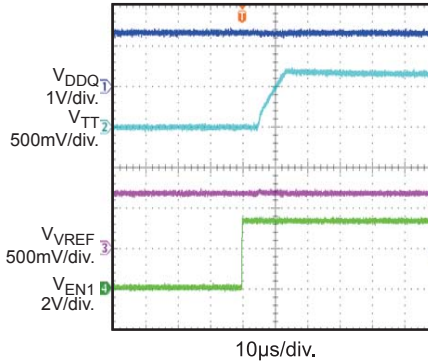
**TYPICAL PERFORMANCE CHARACTERISTICS**
 **$V_{IN} = 20V$ ,  $V_{DDQ} = 1.35V$ ,  $L = 0.68\mu H/3.1m\Omega$ ,  $F_{SW} = 700kHz$ , unless otherwise noted.**


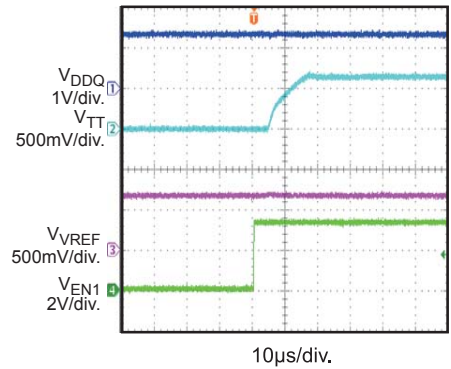
**TYPICAL PERFORMANCE CHARACTERISTICS (continued)**
 **$V_{IN} = 20V$ ,  $V_{DDQ} = 1.35V$ ,  $L = 0.68\mu H/3.1m\Omega$ ,  $F_{sw} = 700kHz$ , unless otherwise noted.**
**Output Voltage Ripple**  
 $I_{OUT} = 0A$ 

**Output Voltage Ripple**  
 $I_{OUT} = 12A$ 

**Start-Up through EN2**  
 $I_{OUT} = 0A$ 

**Start-Up through EN2**  
 $I_{OUT} = 12A$ 

**Shutdown through EN2**  
 $I_{OUT} = 0A$ 

**Shutdown through EN2**  
 $I_{OUT} = 12A$ 

**VTT Start-Up through EN2**
 $I_{VDDQ} = I_{VTT} = I_{VTTREF} = 0A$ 

**VTT Start-Up through EN2**
 $I_{VDDQ} = 12A$ ,  $I_{VTT} = 1A$ ,  $I_{VTTREF} = 0mA$ 

**VTT Shutdown through EN2**
 $I_{VDDQ} = I_{VTT} = I_{VTTREF} = 0A$ 


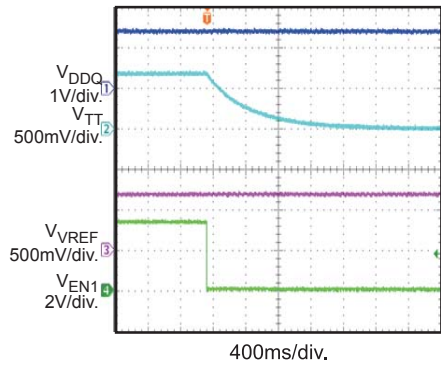


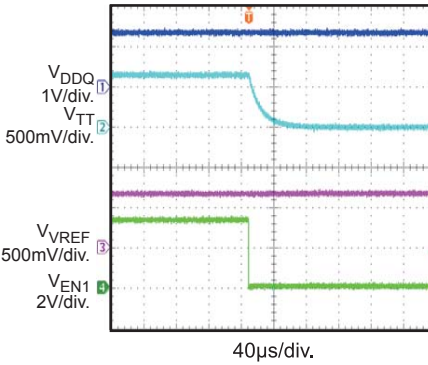
**TYPICAL PERFORMANCE CHARACTERISTICS (continued)**
**VIN = 20V, VDDQ = 1.35V, L = 0.68μH/3.1mΩ, F<sub>sw</sub> = 700kHz, unless otherwise noted.**
**VTT Shutdown through EN2**

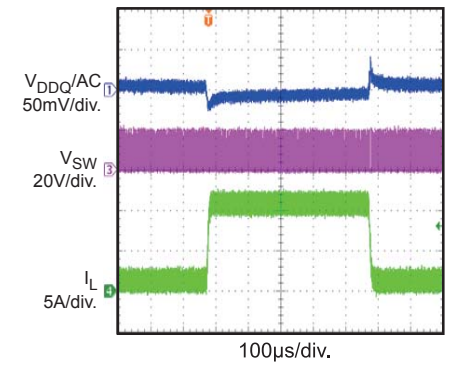
 I<sub>VDDQ</sub>=12A, I<sub>VTT</sub>=1A, I<sub>VTTREF</sub>=0mA

**VTT Start-Up through EN1**

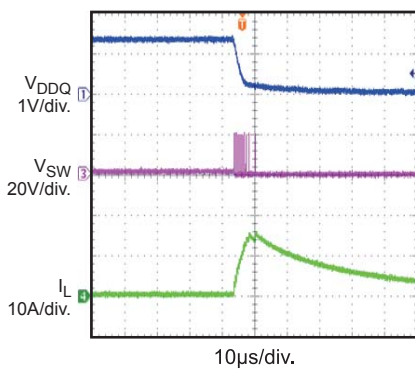
 I<sub>VDDQ</sub>=I<sub>VTT</sub>=I<sub>VTTREF</sub>=0A

**VTT Start-Up through EN1**

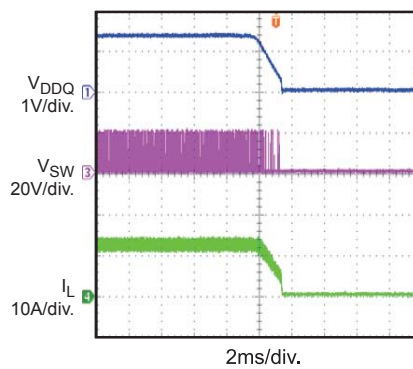
 I<sub>VDDQ</sub>=12A, I<sub>VTT</sub>=1A, I<sub>VTTREF</sub>=0mA

**VTT Shutdown through EN1**

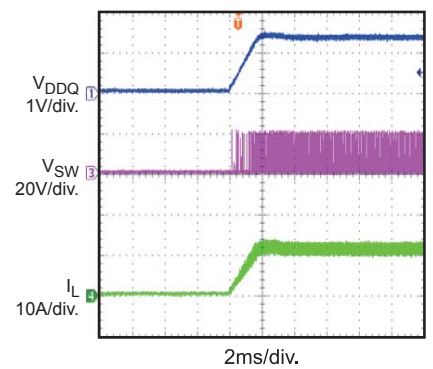
 I<sub>VDDQ</sub>=I<sub>VTT</sub>=I<sub>VTTREF</sub>=0A

**VTT Shutdown through EN1**

 I<sub>VDDQ</sub>=12A, I<sub>VTT</sub>=1A, I<sub>VTTREF</sub>=0mA

**Transient**

 I<sub>OUT</sub>=1.2-10.8A@1.6A/μs, F<sub>sw</sub>=700kHz, C<sub>OUT</sub>=66μF

**Short-Circuit Protection**

 I<sub>OUT</sub> = 0A

**Thermal Shutdown**

 I<sub>OUT</sub> = 12A in Temp Chamber

**Thermal Recovery**

 I<sub>OUT</sub> = 12A in Temp Chamber


### BLOCK DIAGRAM

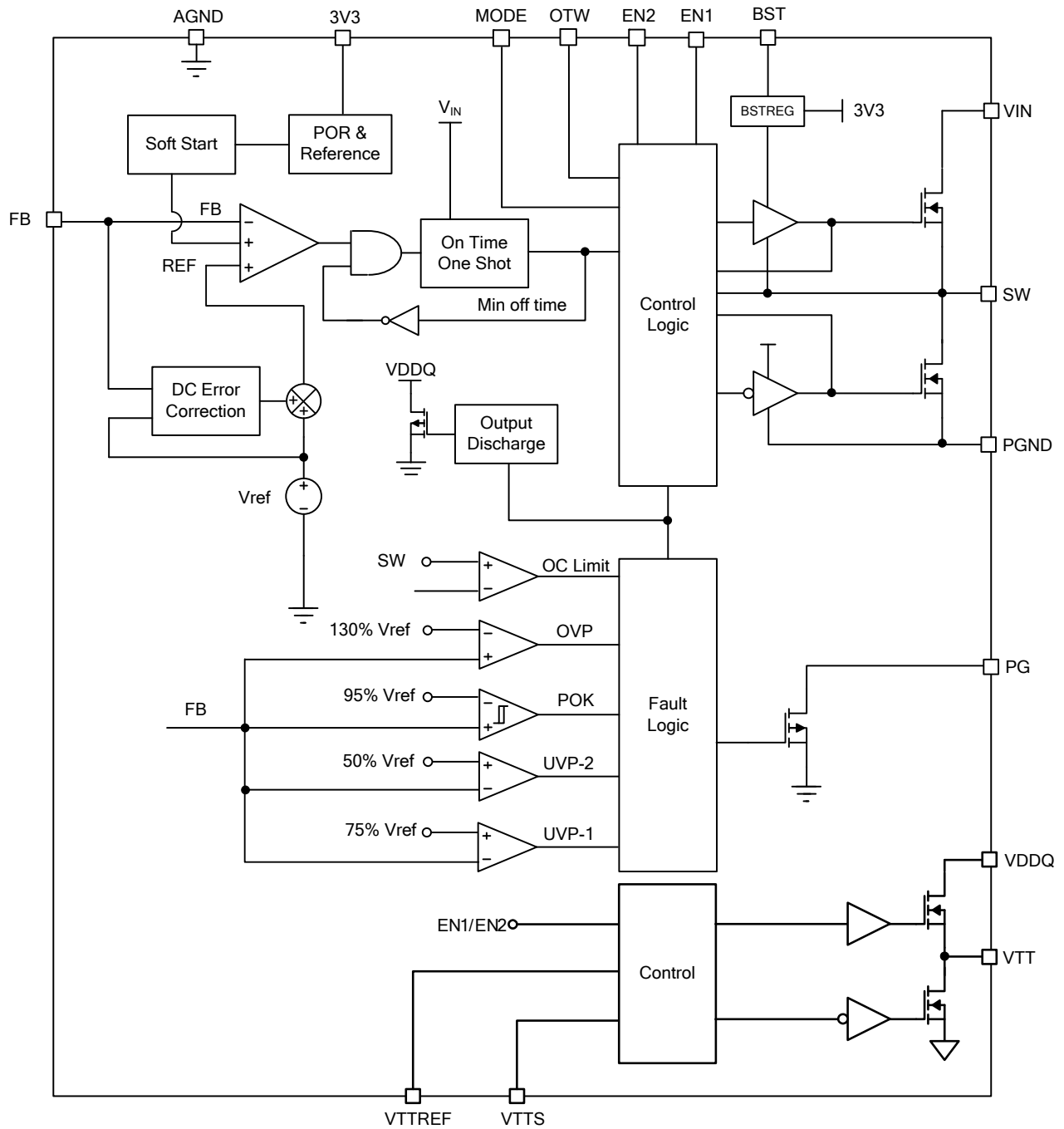


Figure 1: Functional Block Diagram

## OPERATION

### Pulse-Width Modulation (PWM) Operation

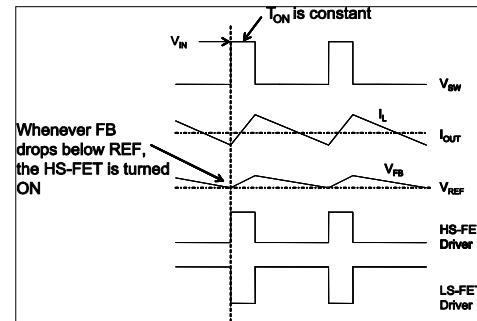
The MP8719 is a fully integrated, synchronous, rectified, step-down, switch-mode converter with ±1A of LDO current. Constant-on-time (COT) control provides fast transient response and eases loop stabilization. At the beginning of each cycle, the high-side MOSFET (HS-FET) is turned on when the feedback voltage ( $V_{FB}$ ) is below the reference voltage ( $V_{REF}$ ), which indicates an insufficient output voltage. The on period is determined by both the output voltage and the input voltage to make the switching frequency fairly constant over the input voltage range.

After the on period elapses, the HS-FET is turned off or enters an off state. The HS-FET is turned on again when  $V_{FB}$  drops below  $V_{REF}$ . By repeating operation this way, the converter regulates the output voltage. The integrated low-side MOSFET (LS-FET) is turned on when the HS-FET is in its off state to minimize conduction loss. A dead short occurs between the input and GND if both the HS-FET and the LS-FET are turned on at the same time. This is called shoot-through. To prevent shoot-through, a dead time (DT) is generated internally between the HS-FET off and the LS-FET on period or the LS-FET off and the HS-FET on period.

Internal compensation is applied for COT control for stable operation, even when ceramic capacitors are used as output capacitors. This internal compensation improves jitter performance without affecting the line or load regulation.

### Heavy-Load Operation

Continuous conduction mode (CCM) occurs when the output current is high and the inductor current is always above zero amps (see Figure 2). When  $V_{FB}$  is below  $V_{REF}$ , the HS-FET is turned on for a fixed interval, which is determined by the one-shot on timer. When the HS-FET is turned off, the LS-FET is turned on until the next period.



**Figure 2: CCM Operation**

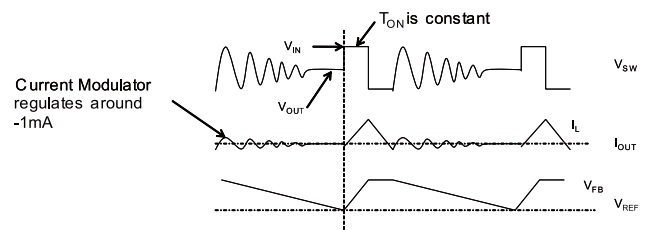
In CCM operation, the switching frequency is fairly constant (PWM mode).

### Light-Load Operation

When the load decreases, the inductor current decreases as well. Once the inductor current reaches zero, the MP8719 transitions from CCM to discontinuous conduction mode (DCM). DCM operation is shown in Figure 3.

When  $V_{FB}$  is below  $V_{REF}$ , the HS-FET is turned on for a fixed interval, which is determined by the one-shot on timer. When the HS-FET is turned off, the LS-FET is turned on until the inductor current reaches zero. In DCM operation, the  $V_{FB}$  does not reach  $V_{REF}$  when the inductor current is approaching zero. The LS-FET driver turns into tri-state (Hi-Z) when the inductor current reaches zero. A current modulator takes over the control of the LS-FET and limits the inductor current to less than -1mA. Therefore, the output capacitors discharge slowly to GND through the LS-FET. As a result, efficiency during light-load condition is improved greatly. The HS-FET does not turn on as frequently during light-load condition as it does during heavy-load condition (skip mode).

At a light-load or no-load condition, the output drops very slowly, and the MP8719 reduces the switching frequency naturally, achieving high efficiency at light load.



**Figure 3: DCM Operation**

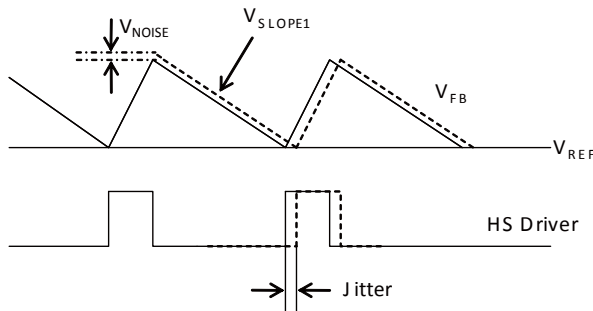
As the output current increases from light-load condition, the current modulation regulation time period becomes shorter. The HS-FET is turned on more frequently, making the switching frequency increase. The output current reaches the critical level when the current modulator time is zero. The critical level of the output current is determined with Equation (1):

$$I_{OUT\_Critical} = \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{2 \times L \times F_s \times V_{IN}} \quad (1)$$

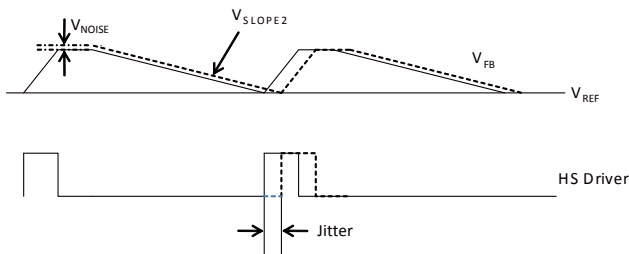
The MP8719 enters PWM mode once the output current exceeds the critical level. Afterward, the switching frequency remains fairly constant over the output current range.

**Jitter and FB Ramp**

Jitter occurs in both PWM and skip mode when noise in the  $V_{FB}$  ripple propagates a delay to the HS-FET driver (see Figure 4 and Figure 5). Jitter affects system stability, with noise immunity proportional to the steepness of  $V_{FB}$ 's downward slope, so the jitter in DCM is usually larger than it is in CCM. However,  $V_{FB}$  ripple does not affect noise immunity directly.



**Figure 4: Jitter in PWM Mode**



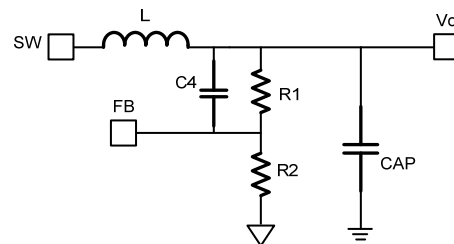
**Figure 5: Jitter in Skip Mode**

**Operating without External Ramp Compensation**

The traditional COT control scheme is intrinsically unstable if the output capacitor's ESR is not large enough to act as an effective current-sense resistor. Usually, ceramic capacitors cannot be used directly as output capacitors.

The MP8719 has built-in internal ramp compensation to ensure that the system is stable, even without the help of the output capacitor's ESR. Use the pure ceramic capacitor solution, which reduces the output ripple, total BOM cost, and board area significantly.

Figure 6 shows a typical output circuit in PWM mode without an external ramp circuit. Refer to the Application Information section on page 16 for design steps without external compensation.



**Figure 6: Simplified Output Circuit**

When using a large capacitor (e.g.: OSCON) on the output, add a >10µF ceramic capacitor in parallel to minimize the effect of ESL.

**Operating with External Ramp Compensation**

Usually, the MP8719 is able to support ceramic output capacitors without an external ramp. However in some cases, the internal ramp may not be enough to stabilize the system, or there is too much jitter, which requires external ramp compensation. Refer to the Application Information section on page 16 for design steps with external ramp compensation.

**VTT and VTTREF**

The MP8719 integrates high performance, low dropout linear regulators (VTT and VTTREF) to provide complete DDR3/DDR3L power solutions. The VTTREF has a 10mA sink/source current capability and always tracks half of VDDQ with ±1% accuracy using an on-

chip divider. A minimum 0.22 $\mu$ F ceramic capacitor must be connected close to the VTTREF terminal for stable operation.

VTT responds quickly to track VTTREF with  $\pm 30$ mV in all conditions. The current capability of the VTT regulator is up to 1A for both sink and source modes. A minimum 22 $\mu$ F ceramic capacitor must be connected close to the VTT terminal. VTTs should be connected to the positive node of the remote VTT output capacitor as a separate trace from the high-current line to VTT.

### Configuring the EN Control

The MP8719 has two enable pins to turn the internal regulators on or off (EN1, EN2). When EN1 and EN2 are high, VDDQ, VTTREF and VTT are turned on. When EN1 is low and EN2 is high, VDDQ and VTTREF remain on while VTT is turned off and left at a high-impedance state (Hi-Z). The VTT output floats and does not sink or source current in this state. When EN1 and EN2 are low, all of the regulators remain off and discharge to GND through a soft shutdown(see Table 1).

**Table 1: EN1/EN2 Control**

EN1	EN2	VDDQ	VTTREF	VTT
High	High	On	On	On
Low	High	On	On	Off (Hi-Z)
Low	Low	Off	Off	Off
High	Low	Off	Off	Off

### Ultrasonic Mode (USM)

Ultrasonic mode (USM) is designed to keep the switching frequency above an audible frequency area during light-load or no-load conditions. Once the part detects that both the HS-FET and the LS-FET are off for about 32 $\mu$ s), PWM is forced to initiate  $T_{ON}$ , so the switching frequency is out of the audible range. To prevent  $V_{OUT}$  from rising too high, the MP8719 reduces  $T_{ON}$  to control  $V_{OUT}$ . If the MP8719's FB is still too high after reducing  $T_{ON}$  to the minimum value, the output discharge function is activated and keeps  $V_{OUT}$  within a reasonable range. USM is selected by MODE.

### MODE Selection

The MP8719 implements MODE for multiple applications for USM and switching frequency selection. USM and the switching frequency

can be selected by a different resistor on the 3V3 logic mode pin. There are four modes that can be selected for normal application with external resistors (see Table 2). It is recommended to use a 1% accuracy resistor.

**Table 2: Mode Selection**

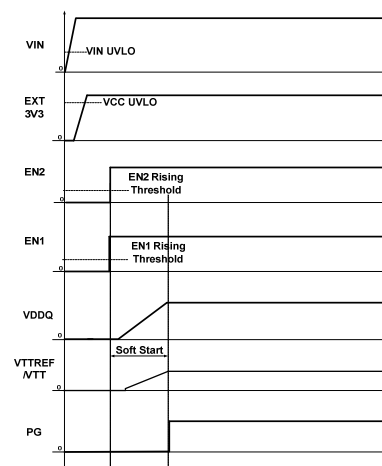
State	USM	Fs	Resistor to GND
M1	No	700kHz	0 $\Omega$
M2	Yes	700kHz	90k $\Omega$
M3	No	500kHz	150k $\Omega$
M4	Yes	500kHz	>230k $\Omega$ or float

### VDDQ Power Good (PG)

The MP8719 uses a power good (PG) output to indicate whether the output voltage of the VDDQ regulator is ready. PG is the open drain of a MOSFET. It should be connected to  $V_{CC}$  or another voltage source through a resistor (e.g.: 100k $\Omega$ ). After the input voltage is applied, the MOSFET is turned on, so PG is pulled to GND before SS is ready. After  $V_{FB}$  reaches 95% of  $V_{REF}$ , PG is pulled high (after a delay time within 10 $\mu$ s). When  $V_{FB}$  drops to 90% of  $V_{REF}$ , PG is pulled low.

### Soft Start (SS)

The MP8719 employs a soft-start (SS) mechanism to ensure a smooth output during power-up. When EN becomes high, the internal reference voltage ramps up gradually, and the output voltage ramps up smoothly as well. Once the reference voltage reaches the target value, the soft start finishes, and the MP8719 enters steady-state operation (see Figure 7).

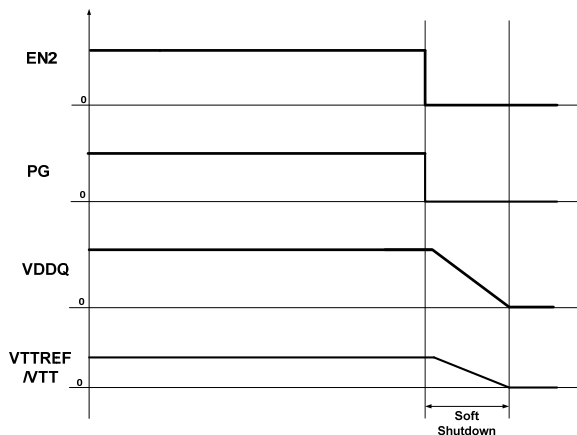


**Figure 7: Start-Up Power Sequence**

If the output is pre-biased to a certain voltage during start-up, the IC disables the switching of both the high-side and low-side switches until the voltage on the internal reference exceeds the sensed output voltage at the FB node.

### Soft Shutdown

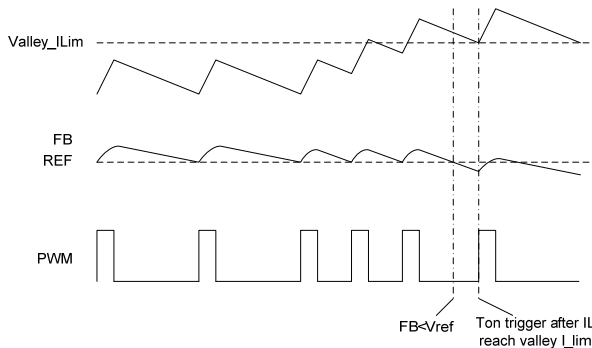
The MP8719 employs a soft shutdown mechanism for DDR to ensure that VTTREF and VTT follow exactly half of the VDDQ. When EN2 is low, the internal reference then ramps down gradually, so the output voltage falls linearly (see Figure 8).



**Figure 8: Soft Shutdown Sequence**

### VDDQ Over-Current Limit (OCL)

The MP8719 has cycle-by-cycle over-current limiting control. The current-limit circuit employs a valley current-sensing algorithm. The MP8719 uses the  $R_{DS(ON)}$  of the LS-FET as a current-sensing element. If the magnitude of the current-sense signal is above the current-limit threshold, the PWM is not allowed to initiate a new cycle, even if FB is lower than REF (see Figure 9).



**Figure 9: Valley Current-Limit Control**

Since the comparison is done during the LS-FET on state, the OC trip level sets the valley level of the inductor current. The maximum load current at the over-current threshold ( $I_{OC}$ ) can be calculated using Equation (2):

$$I_{OC} = I_{limit} + \frac{\Delta I_{inductor}}{2} \quad (2)$$

The over-current limit (OCL) limits the inductor current and does not latch off. In an over-current condition, the current to the load exceeds the current to the output capacitor, so the output voltage tends to fall off. Eventually, the currents ends up crossing the under-voltage protection (UVP) threshold and latches off. Fault latching can be reset by EN going low or cycling the power of VIN.

### VTT/VTTREF Over-Current Protection (OCP)

The VTT LDO has an internal, non-latched, fixed current limit of 1.5A for both sink and source operation. Once the current limit is reached, the gate of the sink/source MOSFET is adjusted to limit the current. VTTREF also has an internal non-latch 15mA current limit.

### VDDQ Over/Under-Voltage Protection (OVP, UVP)

The MP8719 monitors a resistor divided feedback voltage to detect over and under voltage. When the feedback voltage rises higher than 130% of the target voltage, the OVP comparator output goes high, the circuit latches as the HS-FET turns off, and the LS-FET turns on, acting as a -2A current source.

To protect the MP8719 from damage, there is an absolute 3.6V OVP on  $V_{OUT}$ . Once  $V_{OUT}$  reaches this value, it latches off as well. The LS-FET behaves the same as it does at 130% OVP.

When the feedback voltage drops below 75% of  $V_{REF}$ , but remains higher than 50% of  $V_{REF}$ , the UVP-1 comparator output goes high, and the MP8719 latches if  $V_{FB}$  remains in this range for about 30 $\mu$ s (latching the HS-FET off and the LS-FET on). The LS-FET remains on until the inductor current reaches zero. During this period, the valley current limit helps control the inductor current.

When the feedback voltage drops below 50% of  $V_{REF}$ , the UVP-2 comparator output goes high, and the MP8719 latches off directly after the comparator and logic delay (latching the HS-FET off and the LS-FET on). The LS-FET remains on until the inductor current reaches zero. Fault latching can be reset by driving EN low or cycling the power of VIN.

### Under-Voltage Lockout (UVLO) Protection

The MP8719 has two under-voltage lockout (UVLO) protections: a 3V VCC UVLO and a 4.2V VIN UVLO. The MP8719 starts up only when both VCC and VIN exceed their respective UVLO thresholds. The MP8719 shuts down when either VCC is lower than the UVLO falling threshold voltage (typically 2.8V) or VIN is lower than the 3.9V VIN falling threshold. Both UVLO protections are non-latch off.

If an application requires a higher under-voltage lockout (UVLO), use EN2 to adjust the input voltage UVLO by using two external resistors (see Figure 10).

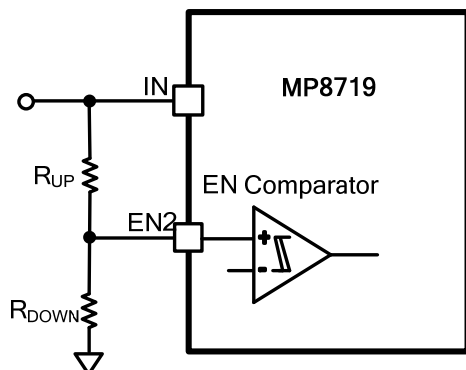


Figure 10: Adjustable UVLO

### Over-Temperature Warning (OTW)

An over-temperature warning (OTW) status pin is added on the MP8719 to act as a pre-over-temperature indicator. When the IC detects that it is close to its over-temperature threshold, OTW pulls low and remains low for at least 10ms. OTW pulls high again when the device temperature has cooled below the temperature hysteresis. OTW does not trigger any protection.

### Thermal Shutdown

Thermal shutdown is employed in the MP8719. The junction temperature of the IC is monitored internally. If the junction temperature exceeds the threshold value (typically 145°C), the converter shuts off. This is a non-latch protection. There is a hysteresis of about 25°C. Once the junction temperature drops to about 120°C, soft start is initiated.

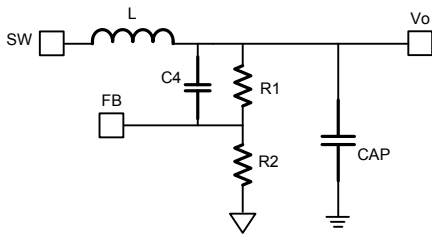
### Output Discharge

The MP8719 discharges all the outputs including VDDQ, VTTREF, and VTT when the controller is turned off by a protection function (UVP, OCP, OVP, UVLO, or thermal shutdown). The discharge resistor on VDDQ is 3Ω, typically. Note that the output discharge is not active during soft shutdown.

## APPLICATION INFORMATION

### Setting the Output Voltage with No External Ramp

The MP8719 does not need ramp compensation for applications where POSCAP or ceramic capacitors are set as output capacitors (when  $V_{IN}$  is over 6V), so external compensation is not needed. The output voltage is then set by feedback resistors R1 and R2 (see Figure 11).



**Figure 11: Simplified Circuit without External Ramp**

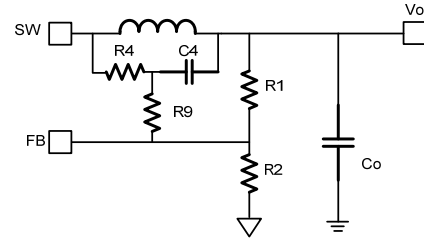
First, choose a value for R2. R2 should be chosen reasonably. A small value for R2 leads to considerable quiescent current loss, but an R2 value that is too large makes FB noise-sensitive. It is recommended to choose a value within 5 - 50kΩ for R2. Use a comparatively larger value for R2 when  $V_{OUT}$  is low; use a smaller value for R2 when  $V_{OUT}$  is high. Considering the output ripple, determine R1 with Equation (3):

$$R_1 = \frac{V_{OUT} - V_{REF}}{V_{REF}} \cdot R_2 \quad (3)$$

C4 acts as a feed-forward capacitor to improve the transient and can be set in the range of 0 - 1000pF. A larger value for C4 leads to better transient, but it is more noise sensitive. Reserve room for a noise filter resistor (R9) (see Figure 12).

### Setting the Output Voltage with External Compensation

If the system is not stable enough or there is too much jitter when a ceramic capacitor is used on the output (i.e.: with a ceramic  $C_{OUT}$  and  $V_{IN}$  is 5V or lower), an external voltage ramp should be added to FB through resistor R4 and capacitor C4. Since there is already an internal ramp added in the system, a 1MΩ (R4) 220pF (C4) ramp should suffice.



**Figure 12: Simplified Circuit with External Ramp**

Besides the R1 and R2 divider, the output voltage is influenced by R4 (see Figure 12). R2 should be chosen reasonably. A small value for R2 leads to considerable quiescent current loss, but a value for R2 that is too large makes FB noise sensitive. It is recommended to choose a value within 5 - 50kΩ for R2. Use a comparatively larger value for R2 when  $V_{OUT}$  is low; use a smaller value for R2 when  $V_{OUT}$  is high. The value of R1 then is determined with Equation (4):

$$R_1 = \frac{1}{\frac{V_{REF}}{V_{OUT} - V_{REF}} - \frac{R_2}{R_4}} \cdot R_2 \quad (4)$$

To get a pole for better noise immunity, set R9 with Equation (5):

$$R_9 = \frac{1}{2\pi \times C_4 \times 2F_{SW}} \quad (5)$$

Set R9 in the range of 100Ω to 1kΩ to reduce its influence on the ramp.

### Selecting the Input Capacitor

The input current to the step-down converter is discontinuous and therefore requires a capacitor to supply AC current to the step-down converter while maintaining the DC input voltage. For the best performance, use ceramic capacitors placed as close to  $V_{IN}$  as possible. Capacitors with X5R and X7R ceramic dielectrics are recommended because they are fairly stable with temperature fluctuations.

The capacitors must have a ripple current rating greater than the maximum input ripple current of the converter. The input ripple current can be estimated with Equation (6):

$$I_{CIN} = I_{OUT} \times \sqrt{\frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)} \quad (6)$$



The worst-case condition occurs at  $V_{IN} = 2V_{OUT}$ , shown in Equation (7):

$$I_{CIN} = \frac{I_{OUT}}{2} \quad (7)$$

For simplification, choose an input capacitor with an RMS current rating greater than half of the maximum load current.

The input capacitance value determines the input voltage ripple of the converter. If there is an input voltage ripple requirement in the system, choose an input capacitor that meets the specification.

The input voltage ripple can be estimated with Equation (8):

$$\Delta V_{IN} = \frac{I_{OUT}}{F_{SW} \times C_{IN}} \times \frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \quad (8)$$

The worst-case condition occurs at  $V_{IN} = 2V_{OUT}$ , shown in Equation (9):

$$\Delta V_{IN} = \frac{1}{4} \times \frac{I_{OUT}}{F_{SW} \times C_{IN}} \quad (9)$$

### Selecting the Output Capacitor

The output capacitor is required to maintain the DC output voltage. Ceramic or POSCAP capacitors are recommended. The output voltage ripple can be estimated using Equation (10):

$$\Delta V_{OUT} = \frac{V_{OUT}}{F_{SW} \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times \left(R_{ESR} + \frac{1}{8 \times F_{SW} \times C_{OUT}}\right) \quad (10)$$

When using ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance, which mainly causes the output voltage ripple. For simplification, the output voltage ripple can be estimated with Equation (11):

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times F_{SW}^2 \times L \times C_{OUT}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \quad (11)$$

The output voltage ripple caused by ESR is very small. Therefore, an external ramp is needed to stabilize the system. The external ramp can be generated through resistor R4 and capacitor C4.

When using POSCAP capacitors, the ESR dominates the impedance at the switching frequency. The ramp voltage generated from the ESR dominates the output ripple. The output ripple can be approximated with Equation (12):

$$\Delta V_{OUT} = \frac{V_{OUT}}{F_{SW} \times L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times R_{ESR} \quad (12)$$

The maximum output capacitor limitation should be considered in the design application. The MP8719 has a soft-start time period of around 1.6ms. If the output capacitor value is too high, the output voltage cannot reach the design value during the soft-start time, causing it to fail to regulate. The maximum output capacitor value ( $C_{O\_MAX}$ ) can be limited approximately with Equation (13):

$$C_{O\_MAX} = (I_{LIM\_AVG} - I_{OUT}) \times T_{SS} / V_{OUT} \quad (13)$$

Where  $I_{LIM\_AVG}$  is the average start-up current during the soft-start period (which can be equivalent to the current limit), and  $T_{SS}$  is the soft-start time.

### Selecting the Inductor

An inductor is necessary for supplying constant current to the output load while being driven by the switched input voltage. A larger-value inductor results in less ripple current, resulting in lower output ripple voltage, but also has a larger physical footprint, a higher series resistance, and a lower saturation current. A good rule for determining the inductance value is to design the peak-to-peak ripple current in the inductor to be in the range of 30% to 50% of the maximum output current, and the peak inductor current below the maximum switch current limit. The inductance value can be calculated with Equation (14):

$$L = \frac{V_{OUT}}{F_{SW} \times \Delta I_L} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \quad (14)$$

Where  $\Delta I_L$  is the peak-to-peak inductor ripple current.

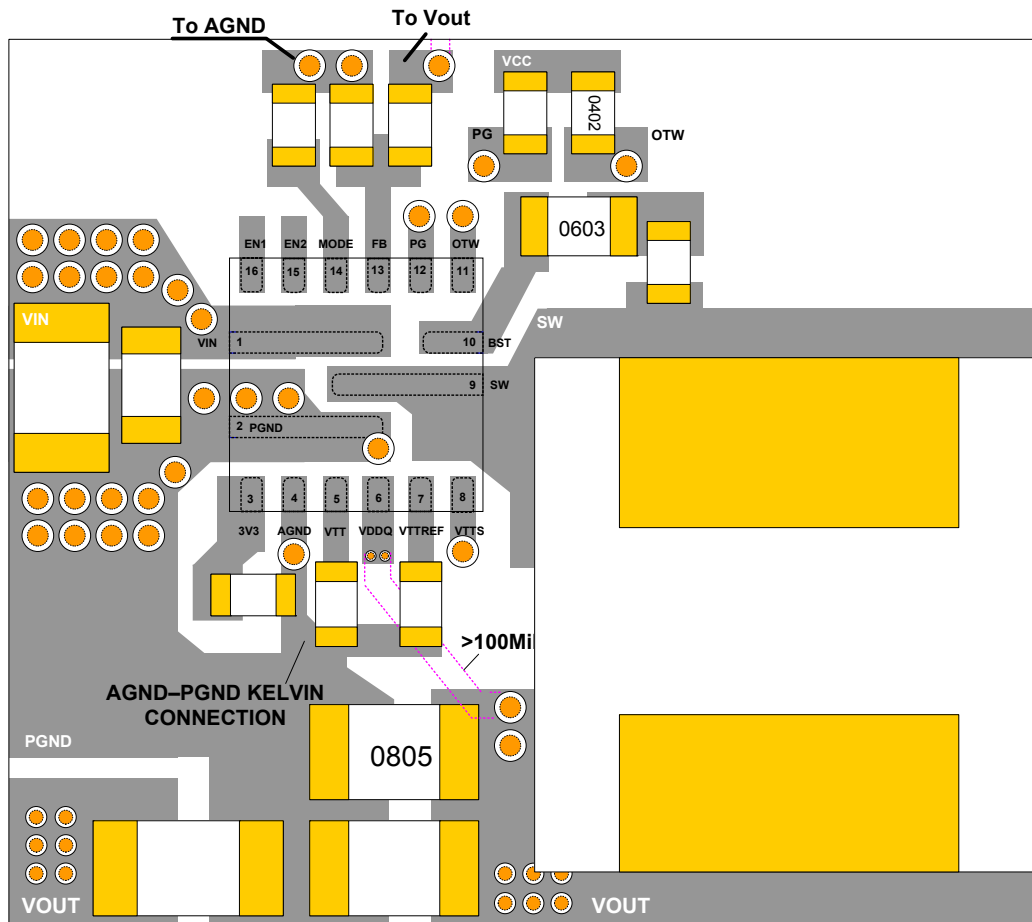
The inductor should not saturate under the maximum inductor peak current (including a short-current), so  $I_{SAT}$  is recommended to be >13A.

### PCB Layout Guidelines

Efficient PCB layout is critical for stable operation of the IC. A 4-layer layout is strongly recommended to achieve better thermal performance. For best results, refer to Figure 13 and follow the guidelines below. For more information, refer to the application note AN087 “PCB Layout Design Guidelines for NB68X Families.”

1. Keep the VDDQ trace width greater than 100mil to avoid a voltage drop at the input of the VTTLDO.
2. Place the high-current paths (GND, VIN, and SW) very close to the device with short, direct, and wide traces. *A thick PGND trace under the IC should be top priority.*
3. Place the input capacitors as close to VIN and GND as possible on the same layer as the IC.

4. Place the decoupling capacitor as close to VCC and GND as possible.
5. Keep the switching node (SW) short and away from the feedback network.
6. Place the external feedback resistors next to FB.
7. Ensure that there is no via on the FB trace.
8. Keep the BST voltage path (BST, C3, and SW) as short as possible.
9. Keep the VIN and GND pads connected with a large copper plane to achieve better thermal performance.
10. Add several vias with 10mil drill/18mil copper width close to the VIN and GND pads to help thermal dissipation.



**Figure 13: Recommended PCB Layout**

### Design Example

For applications that need currents over 10A, it is recommended to apply a 500kHz  $f_{SW}$  part for better thermal performance and efficiency (see Table 3). Otherwise, a 700kHz  $f_{SW}$  operation makes the system more compact with faster transient (see Table 4).

There is a resistor from an external 3.3V supply to 3V3 acting as a ripple noise filter of the 3.3V power supply. It is recommended to have a resistor value from 0 - 5.1 $\Omega$  depending on the noise level. A size 0402 resistor is sufficient if the 3.3V voltage rises up with  $SS > 100\mu s$ . Otherwise, a larger resistor (e.g.: 0603/0805) is needed.

For applications where  $V_{IN}$  is 5V or lower, it is recommended to apply the SCH shown in Figure 14 with a proper external ramp.

The MP8719 also supports non DDR applications with very compact external components (see Figure 15).

Some design examples are provided below when ceramic capacitors are applied.

**Table 3: Design Example for 500kHz  $f_{SW}$**

$V_{OUT}$ (V)	$C_{out}$ (F)	L ( $\mu H$ )	$R_{Mode}$ ( $\Omega$ )	C4 (pF)	R1 (k $\Omega$ )	R2 (k $\Omega$ )
1.0	22 $\mu x 4$	1.0	150k	220	13.3	20
1.2	22 $\mu x 4$	1.0	150k	220	20	20
1.35	22 $\mu x 4$	1.0	150k	220	28	22.1
1.5	22 $\mu x 4$	1.2	150k	220	30.1	20
1.8	22 $\mu x 4$	1.5	150k	220	40.2	20

**Table 4: Design Example for 700kHz  $f_{SW}$**

$V_{OUT}$ (V)	$C_{out}$ (F)	L ( $\mu H$ )	$R_{Mode}$ ( $\Omega$ )	C4 (pF)	R1 (k $\Omega$ )	R2 (k $\Omega$ )
1	22 $\mu x 3$	0.68	0	220	13.3	20
1.2	22 $\mu x 3$	0.68	0	220	20	20
1.35	22 $\mu x 3$	0.68	0	220	28	22.1
1.5	22 $\mu x 3$	0.68	0	220	30.1	20
1.8	22 $\mu x 3$	0.68	0	220	40.2	20

### Additional Design Examples with Higher $V_{OUT}$

The MP8719 supports designs that need  $V_{OUT}$  to be in the range of 3.3V to 5.5V. Figure 17 shows an SCH with a 5V  $V_{OUT}$  with proper external settings. Please pay attention to the red components, and please note that USM is not allowed for this application.

## TYPICAL APPLICATION CIRCUITS

### DDR Application for $V_{IN} > 6V$

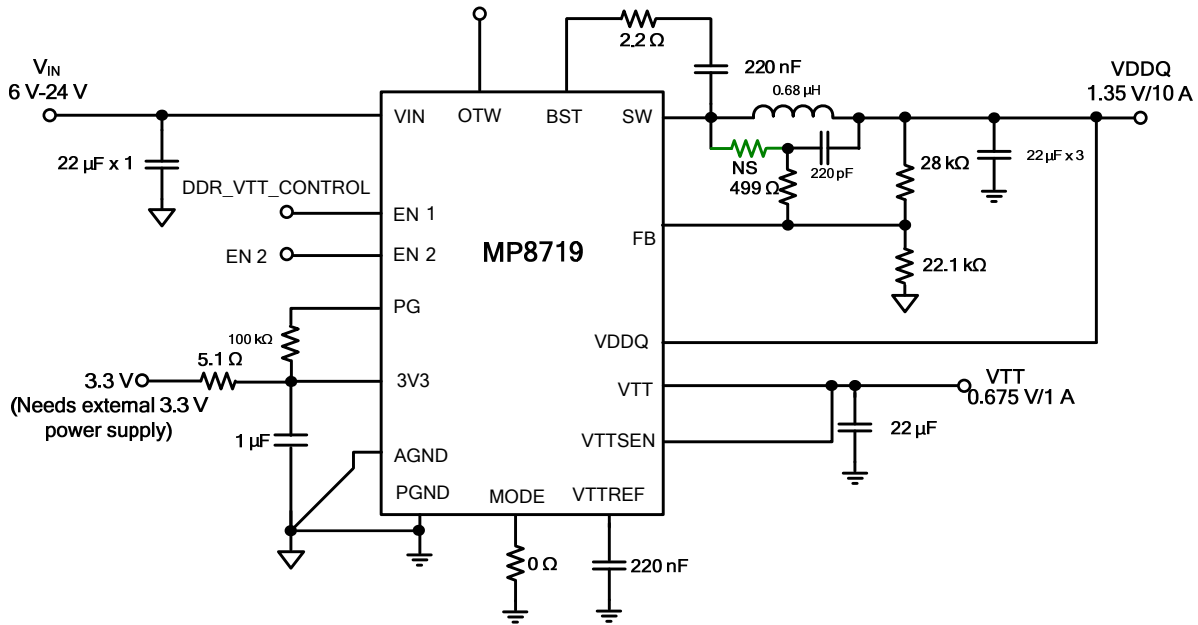


Figure 14: Typical DDR Application Circuit,  $V_{IN} = 6V - 24V$ ,  $V_{OUT} = 1.35V$ ,  $I_{OUT} = 10A$ , with  $V_{TT} f_s = 700kHz$

### DDR Application Cover 5V $V_{IN}$ Application

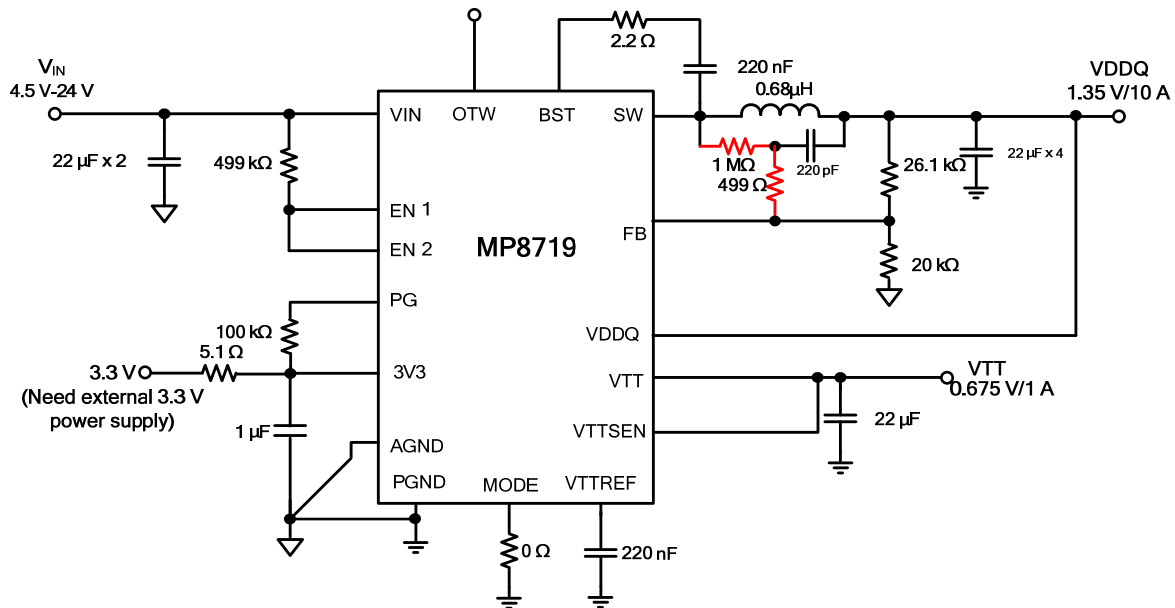
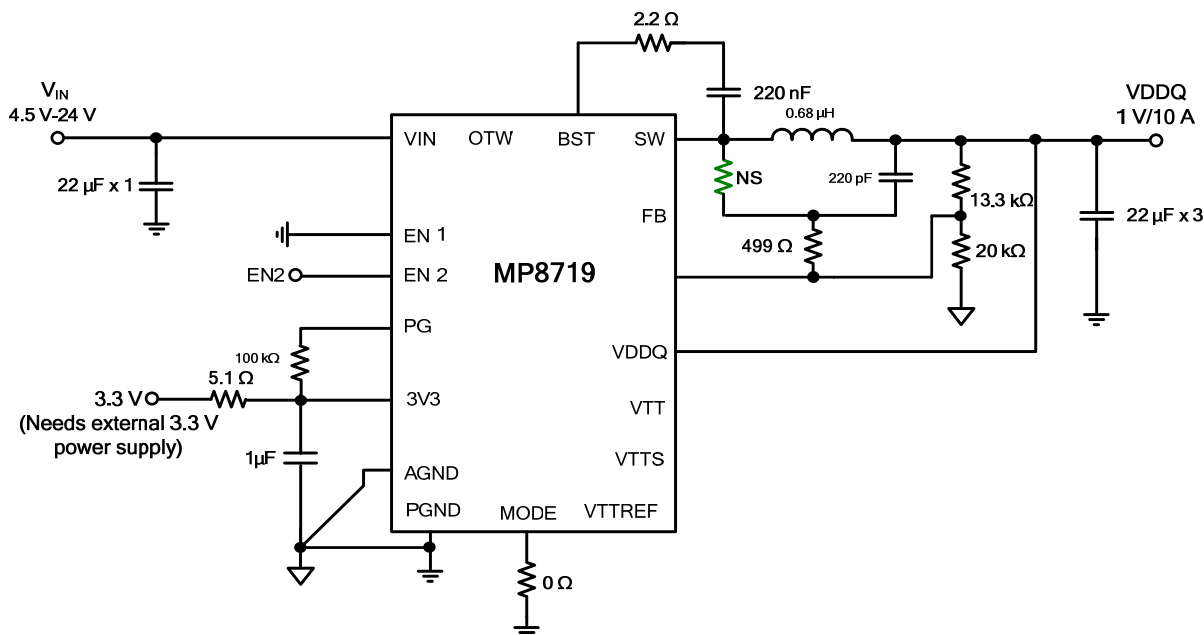
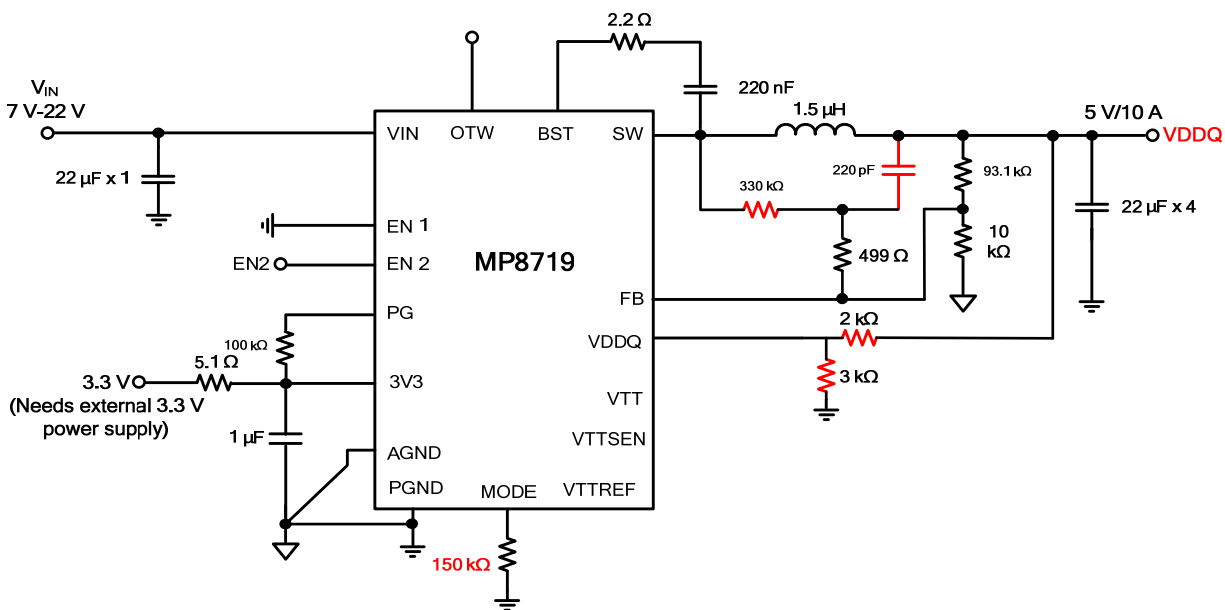


Figure 15: Typical DDR Application Circuit,  $V_{IN} = 4.5V - 24V$ ,  $V_{OUT} = 1.35V$ ,  $I_{OUT} = 10A$ , with  $V_{TT} f_s = 700kHz$

**TYPICAL APPLICATION CIRCUITS (continued)**
**Non DDR Application**


**Figure 16: Normal Single Buck Application Circuit,  $V_{IN} = 4.5V - 24V$ ,  $V_{OUT} = 1V$ ,  $I_{OUT} = 10A$ , without VTT fs = 700kHz**

**Special Application with  $3.3V < V_{OUT} < 5.5V$** 


**Figure 17: Special Application Circuit,  $V_{IN} = 7V - 22V$ ,  $V_{OUT} = 5V$ ,  $I_{OUT} = 10A$ , fs = 700kHz**

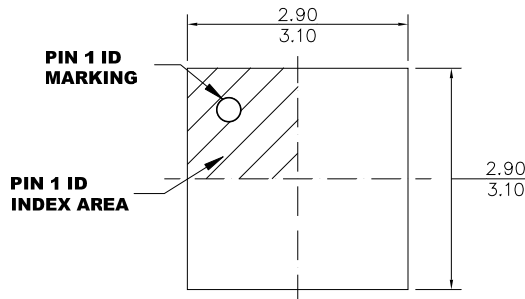
**NOTE 1:** Ultrasonic mode is not effective if applied in this SCH.

**NOTE 2:** The maximum load is 10A in this application. Fs is set with a 500kHz mode but is actually 700kHz.

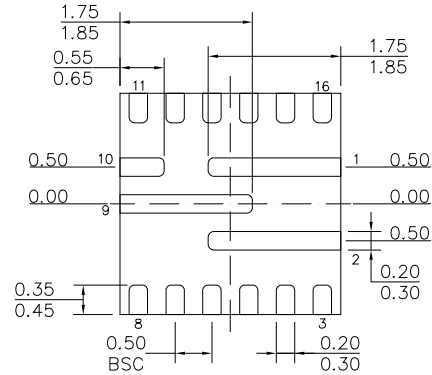
**NOTE 3:** It is recommended to avoid VDDQ voltages over 3.3V by using the external resistors setting.

## PACKAGE INFORMATION

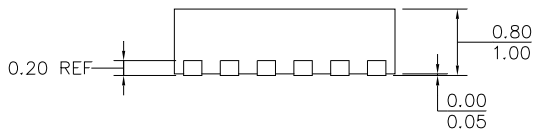
### QFN-16 (3mmx3mm)



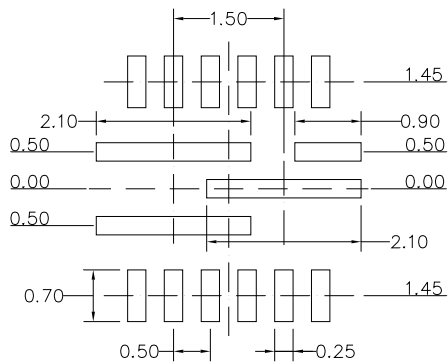
**TOP VIEW**



**BOTTOM VIEW**



**SIDE VIEW**



**RECOMMENDED LAND PATTERN**

**NOTE:**

- 1) ALL DIMENSIONS ARE IN MILLIMETERS.
- 2) EXPOSED PADDLE SIZE DOES NOT INCLUDE MOLD FLASH.
- 3) LEAD COPLANARITY SHALL BE 0.10 MILLIMETERS MAX.
- 4) JEDEC REFERENCE IS MO-220.
- 5) DRAWING IS NOT TO SCALE.

**NOTICE:** The information in this document is subject to change without notice. Users should warrant and guarantee that third party Intellectual Property rights are not infringed upon when integrating MPS products into any application. MPS will not assume any legal responsibility for any said applications.