

## TW2824

### NOT RECOMMENDED FOR NEW DESIGNS RECOMMENDED REPLACEMENT PART TW2837

FN7738 Rev. 0.00

4-Channel Video QUAD/MUX Controller for Security Applications

February 2, 2011

The TW2824 has four high quality NTSC/PAL video decoders, dual color display controllers and dual video encoders. The TW2824 contains four 10-bit analog-to-digital converters, proprietary digital gain/clamp controller, high quality Y/C separator to reduce cross-noise and high performance dual scaler to provide various pictures. Four built-in motion and blind detectors can increase the feature of the security system. The TW2824 has a flexible video display controller including QUAD and MUX basic functions. The TW2824 also has an excellent graphic overlay function which displays character/bitmap, box and mouse pointer. The TW2824 contains two video encoders with four 10bit digital-to-analog converters for providing 2 composite or S-video.

### **Features**

### **Four Video Decoders**

- Accepts all NTSC/PAL standard formats with auto detection
- Integrated four anti-aliasing filters and 10-bit **CMOS ADCs**
- High performance adaptive comb filters for all NTSC/PAL standards
- IF compensation filter for improvement of color demodulation
- PAL delay lines for correcting PAL phase errors
- · Programmable hue, saturation, contrast, brightness and sharpness
- Dual high performance horizontal and vertical scaler for each channel.
- Four built-in motion detectors with 16x12 cells and blind detectors

#### **Dual Video Controllers**

- Additional 1-channel digital input for playback or cascade operation
- Full live/strobe/switch function
- Auto sequence switch with 64 queues and/or manual switch by interrupt

- · Various channel attribute control
- · Image enhancement for still image
- High performance 2x zoom for horizontal and vertical direction
- Supports save and recall function
- Last image capture when video-loss
- Extendable to 8-/12-/16-channel video controller using cascade connection
- Path-to-path cascade
- Character/bitmap overlay for OSD
- 16 programmable single boxes
- 4 2D arrayed boxes for motion result display
- Mouse pointer overlay

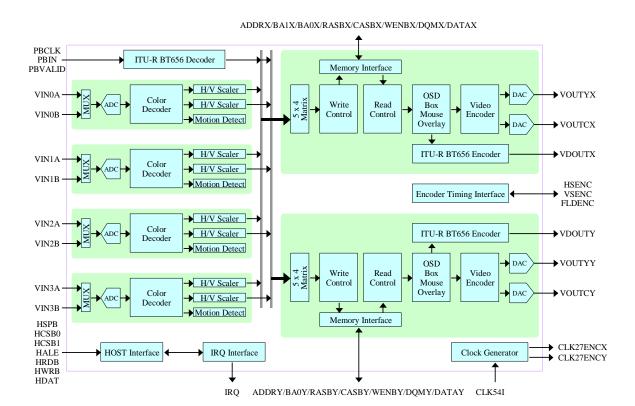
#### **Dual Video Encoders**

- 2 path digital outputs with ITU-R BT.656 standards
- 2 path analog outputs with all analog NTSC/PAL standards
- Supports CVBS or S-video for each path
- Programmable bandwidth for luminance and chrominance path
- Four 10-bit video CMOS DACs

# **Applications**

- Analog QUAD/MUX system
- 4-/8-/16-channel DVR system
- · Car rear vision system
- Hair shop system

# **Block Diagram**



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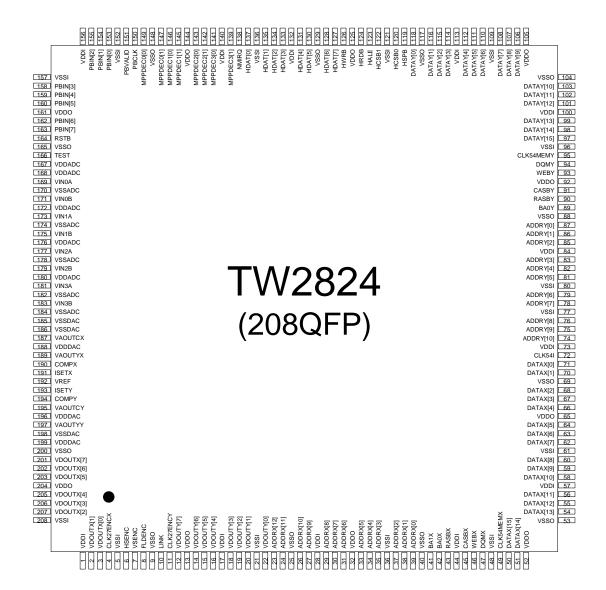
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## **Device Options**

Device Name	Description	MUX Function *1	Dual Output *2
TW2824M	QUAD/MUX function with dual outputs	0	0
TW2824Q	QUAD function with dual outputs	Χ	0
TW2824MS	QUAD/MUX function with single output	0	Χ
TW2824QS	QUAD function with single output	Х	Χ

<sup>\*</sup> Note 1. Refer to page 37 for device option of MUX function.

## **Pin Diagram**



<sup>2.</sup> Refer to page 60 for device option of dual output.

# **Pin Description**

# **Analog Interface Pins**

Name	Number	Туре	Description
VINOA	169	А	Composite video input 0A.  Must be connected through 2.2uF to input.
VIN0B	171	Α	Composite video input 0B.  Must be connected through 2.2uF to input.
VIN1A	173	Α	Composite video input 1A.  Must be connected through 2.2uF to input.
VIN1B	175	Α	Composite video input 1B.  Must be connected through 2.2uF to input.
VIN2A	177	Α	Composite video input 2A.  Must be connected through 2.2uF to input.
VIN2B	179	Α	Composite video input 2B.  Must be connected through 2.2uF to input.
VIN3A	181	Α	Composite video input 3A.  Must be connected through 2.2uF to input.
VIN3B	183	Α	Composite video input 3B.  Must be connected through 2.2uF to input.
VOUTYX	189	Α	Composite/Luminance video output of X path.
VOUTCX	187	Α	Composite/Chrominance video output of X path.
VOUTYY	197	Α	Composite/Luminance video output of Y path.
VOUTCY	195	Α	Composite/Chrominance video output of Y path.
COMPX	190	Α	Compensation capacitance. Must be connected though 0.1uF to VDDDAC.
COMPY	194	А	Compensation capacitance. Must be connected though 0.1uF to VDDDAC.
ISETX	191	Α	Current setting resistor for X path.
ISETY	193	Α	Current setting resistor for Y path.
VREF	192	А	Voltage reference. Must be connected though 0.1uF to VSSDAC.

# **Digital Video Interface Pins**

Name	Number	Туре	Description
VDOUTX [7:0]	201,202,203, 205,206,207, 2,3	0	Digital video data output for X path or Chip-to-chip cascade connection pin.
VDOUTY [7:0]	12,14,15, 16,18,19, 20,22	0	Digital video data output for Y path.
CLK27ENCX	4	0	Clock of VDOUTX.
CLK27ENCY	11	0	Clock of VDOUTY.
HSENC	6	I/O	Encoder horizontal sync.
VSENC	7	I/O	Encoder vertical sync or Chip-to-chip cascade connection pin.
FLDENC	8	I/O	Encoder field flag.
LINK	10	I/O	Chip-to-chip cascade connection pin.
PBIN[7:0]	163,162,160, 159,158,155, 154,153	I	Video data of playback input or Chip-to-chip cascade connection pin.
PBVALID	151	I	Valid data indicator of PBIN or Chip-to-chip cascade connection pin.
PBCLK	150	I	Clock of PBIN.
MPPDEC3[1:0]	139,141	0	Multi-purpose output for VIN3 or CH3.
MPPDEC2[1:0]	142,143	0	Multi-purpose output for VIN2 or CH2.
MPPDEC1[1:0]	145,146	0	Multi-purpose output for VIN1 or CH1.
MPPDEC0[1:0]	147,149	0	Multi-purpose output for VIN0 or CH0.

# **Memory Interface Pins**

Name	Number	Туре	Description				
DATAX[15:0]	50,51,54, 55,56,58, 59,60,62, 63,64,66, 67,68,70, 71	I/O	SDRAM data bus of X path.				
ADDRX[12:0]	23,24,26, 27,29,30, 31,33,34, 35,37,38, 39	0	SDRAM address bus of X path . ADDRX[10] is AP.				
BA1X	41	0	SDRAM bank1 selection of X path.				
BA0X	42	0	SDRAM bank0 selection of X path.				
RASBX	43	0	SDRAM row address selection of X path.				
CASBX	45	0	SDRAM column address selection of X path.				
WEBX	46	0	SDRAM write enable of X path.				
DQMX	47	0	SDRAM write mask of X path.				
CLK54MEMX	49	0	SDRAM clock of X path.				
DATAY[15:0]	97,98,99, 101,102,103, 106,107,108, 110,111,112, 114,115,116, 118	I/O	SDRAM data bus of Y path.				
ADDRY[10:0]	74,75,76, 78,79,81, 82,83,85, 86,87	0	SDRAM address bus of Y path. ADDRY[10] is AP.				
BA0Y	89	0	SDRAM Bank0 Selection of Y path.				
RASBY	90	0	SDRAM row address selection of Y path.				
CASBY	91	0	SDRAM column address selection of Y path.				
WEBY	93	0	SDRAM write enable of Y path.				
DQMY	94	0	SDRAM write mask of Y path.				
CLK54MEMY	95	0	SDRAM clock of Y path. Clock phase can be controlled via register.				

# **System Control Pins**

Name	Number	Туре	Description
TEST	166	I	Only for the test purpose. Must be connected to VSSO.
RSTB	164	I	System reset.
NMIRQ	138	0	Interrupt request signal.
HDAT[7:0]	127,128,130, 131,133,134, 135,137	I/O	Data bus for parallel interface. HDAT[7] is serial data for serial interface. HDAT[6:1] is slaver address[6:1] for serial interface.
HWRB	126	I	Write enable for parallel interface. VSSO for serial interface.
HRDB	124	I	Read enable for parallel interface. VSSO for serial interface.
HALE	123	I	Address line enable for parallel interface. Serial clock for serial interface.
HCSB1	122	I	Chip select 1 for parallel interface. VSSO for serial interface.
HCSB0	120	I	Chip select 0 for parallel interface. Slaver address[0] for serial interface.
HSPB	119	I	Select serial/parallel host interface.
CLK54I	72	I	54MHz system clock.
LINK	10	I/O	Cascade connection.

# **Power / Ground Pins**

Name	Number	Туре	Description
VDDO	204,161,144, 125,105,92, 65,52,32, 13	Р	Digital power for output driver. 3.3V.
VSSO	200,165,148, 129,117,104, 88,69,53, 40,25,9	G	Digital ground for output driver.
VDDI	156,140,132, 113,100,84, 73,57,44, 28,17,1	Р	Digital power for internal logic. 2.5V.
VSSI	208,157,152, 136,121,109, 96,80,77, 61,48,36, 21,5	G	Digital ground for internal logic.
VDDDAC	199, 196,188	Р	Analog power for DAC. 2.5V.
VSSDAC	198,186, 185	G	Analog ground for DAC.
VDDADC	180,176,172, 168, 167	Р	Analog power for ADC. 2.5V.
VSSADC	184, 182,178, 174, 170	G	Analog ground for ADC.

# **Functional Description**

## **Video Input**

The TW2824 has 5 input interfaces that consist of 1 digital video input from external video decoder and 4 analog composite video inputs. Digital video input is decoded by internal ITU-R BT656 decoder and then fed to X and Y video control part. 4 analog video inputs are converted to digital video stream through 10bit ADC and luminance/chrominance processor in built-in video decoder. Each built-in video decoder has its own motion detector and dual scaler also. The scaled digital video data are transferred to X and Y video control part. The structure of video input and decoder part is shown in the following Fig 1.

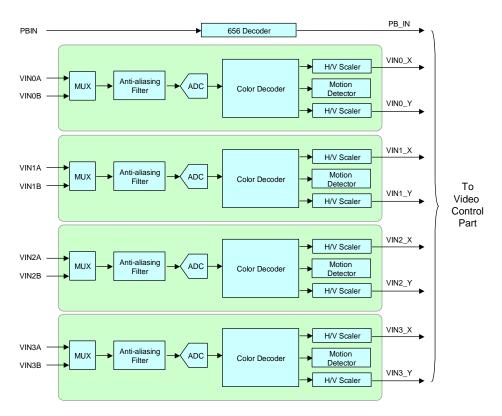


Fig 1 Structure of video input and decoder part

### **ANALOG VIDEO INPUT**

The TW2824 supports all NTSC/PAL video standards for analog input and contains automatic standard detection circuit. Automatic standard detection can be overridden by writing the value into the IFMTMAN and IFORMAT (0x01, 0x41, 0x81, 0xC1) registers. Even if video loss is detected, the TW2824 can be forced to free-running in a particular video standard mode for fast locking by programming IFORMAT register. The Table 1 shows the video input standards supported by TW2824.

Table 1 Video input standards

Format	Line/Fv (Hz)	Fh (KHz)	Fsc (MHz)		
NTSC-M* NTSC-J	525/59.94	15.734	3.579545		
NTSC-4.43*	525/59.94	15.734	4.43361875		
NTSC-N	625/50	15.625	3.579545		
PAL-BDGHI PAL-N*	625/50	15.625	4.43361875		
PAL-M*	525/59.94	15.734	3.57561149		
PAL-NC	625/50	15.625	3.58205625		
PAL-60	525/59.94	15.734	4.43361875		

Notes: \* 7.5 IRE Setup

#### **Analog-to-Digital Converter**

The TW2824 contains four 10-bit Analog to Digital converters that digitizes the analog video inputs. As the inputs are digitized at greater than two times that of the Nyquist sampling rate, only simple external anti-aliasing LPF are needed to prevent out-of-band frequencies. Each ADC has two analog switches that are controlled by the ANA\_SW (0x22, 0x62, 0xA2, 0xE2) register. The A/D converters can also be put into power-down mode by the ADC\_PWDN (0x78) register.

#### **Sync Processing**

The sync processor of TW2824 detects horizontal synchronization and vertical synchronization signals in the composite video signal. The TW2824 utilizes proprietary technology for locking to weak, noisy, or unstable signals such as those from on air signal or fast forward/backward play of VCR system.

A digital gain and clamp control circuit restores the ac coupled video signal to a fixed dc level. The clamping circuit provides line-by-line restoration of the video pedestal level to a fixed dc reference voltage. In no AGC mode, the gain control circuit adjusts only the video sync gain to achieve desired sync amplitude so that the active video is bypassed regardless of the gain control. But when AGC mode is enabled, both active video and sync are adjusted by the gain control.

The horizontal synchronization processor contains a sync separator, a PLL and the related decision logic. The horizontal sync separator detects the horizontal sync by examining low-pass filtered video input whose level is lower than a threshold. Additional logic is also used to avoid false detection on glitches. The horizontal PLL locks onto the extracted horizontal sync in all conditions to provide jitter free image output. In case of missing horizontal sync, the PLL is on free running status that matches the standard raster frequency.

The vertical sync separator detects the vertical synchronization pattern in the input video signals. The field status is determined at vertical synchronization time. When the location of the detected vertical sync is inline with a horizontal sync, it indicates a frame start or the odd field start. Otherwise, it indicates an even field.

### **Color Decoding**

The digitized composite video data at 2X pixel clock rate first passes through decimation filter. The decimation filter is required to achieve optimum performance and prevent high frequency components from being aliased back into the video image. Fig 2 shows the frequency characteristic of the decimation filter.

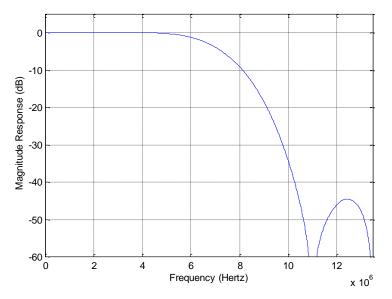
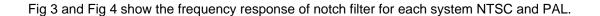


Fig 2 The frequency characteristic of the decimation Filter

The adaptive comb filter is used for high performance luminance/chrominance separation from NTSC/PAL composite video signals. The comb filter improves the luminance resolution and reduces noise such as cross-luminance and cross-color. The adaptive algorithm eliminates most of errors without introducing new artifacts or noise. To accommodate some viewing preferences, additional chrominance trap filters are also available in the luminance path.



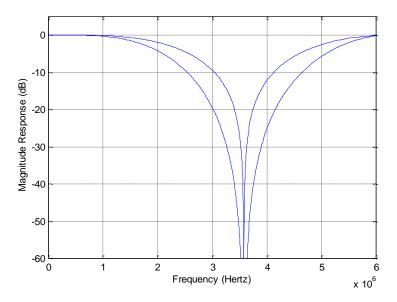


Fig 3 The frequency response of luminance notch filter for NTSC

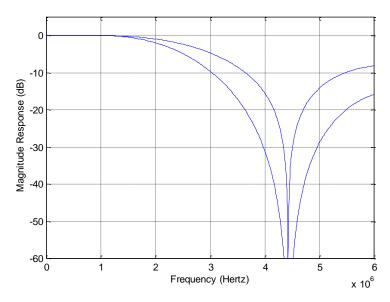


Fig 4 The frequency response of luminance notch filter for PAL

### **Luminance Processing**

The luminance signal that is separated by adaptive comb or trap filter is then fed to a peaking circuit. The peaking filter enhances the high frequency components of the luminance signal via the Y\_PEAK (0x14, 0x54, 0x94, 0xD4) register. The following Fig 5 shows the characteristics of the peaking filter for four different gain modes.

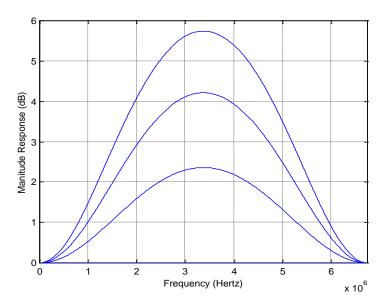


Fig 5 The frequency characteristic of luminance peaking filter

The picture contrast and brightness adjustment is provided through the CONT (0x11, 0x51, 0x91, 0xD1) and BRT (0x12, 0x52, 0x92, 0xD2) registers. The contrast adjustment range is from approximately 0 to 200 percent and the brightness adjustment is in the range of ±25 IRE. Moreover, a high frequency coring function is also embedded in TW2824 to minimize a high frequency noise. The coring level is adjustable through the Y\_H\_CORE (0xF8) register.

### **Chrominance Processing**

The chrominance demodulation is done by first quadrature mixing for NTSC and PAL. The mixing frequency is equal to the sub-carrier frequency of NTSC and PAL. After the mixing, a LPF is used to remove 2X carrier signal and yield chrominance components. The characteristic of LPF can be selected for optimized transient color performance. Fig 6 is showing the frequency response of chrominance LPF.

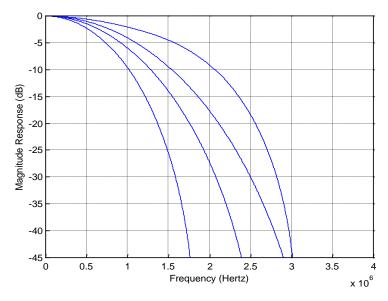


Fig 6 The frequency response of chrominance LPF

In case of a mistuned IF source, IF compensation filter makes up for any attenuation at higher frequencies or asymmetry around the color sub-carrier. The gain for the upper chrominance side band is controlled by the IFCOMP (0x13, 0x53, 0x93, 0xD3) register. Fig 7 shows the frequency response of IF-compensation filter.

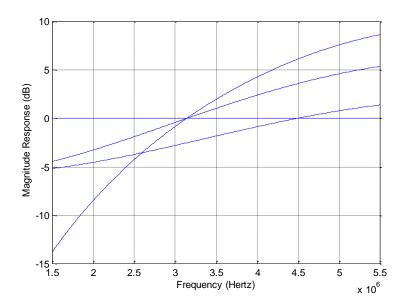


Fig 7 The frequency characteristics of IF-compensation filter

The ACC (Automatic Color gain Control) compensates for reduced chrominance amplitudes caused by high frequency suppression in video signal. The range of ACC is from –6dB to 30dB approximately. For black & white video or very weak & noisy signals, the color will be turned off by the internal color killing circuit. The color killing function can also be always enabled or disabled by programming CKIL (0x14, 0x54, 0x94, 0xD4) register.

The color saturation can be adjusted by changing SAT (0x10, 0x50, 0x90, 0xD0) register. The Cb and Cr gain can be also adjusted independently by programming UGAIN (0x3C) and VGAIN (0x3D) registers. Likewise, the Cb and Cr offset can be programmed through the U\_OFF (0x3E) and V\_OFF (0x3F) registers. Hue control is achieved with phase shift of the digitally controlled oscillator. The phase shift can be programmed through the HUE (0x0F, 0x4F, 0x8F, 0xCF) register.

### **Scaling and Cropping**

The TW2824 provides two methods to reduce the amount of video pixel data, scaling and cropping. The scaling function provides video image at lower resolution while the cropping function supplies only a portion of the video image.

The TW2824 includes a high quality horizontal and vertical down scaler. The video images can be downscaled in both horizontal and vertical direction to an arbitrary size. The luminance horizontal scaler includes an anti-aliasing filter to reduce image artifacts in the resized image and a 32 polyphase filter to accurately interpolate the value of a pixel. This results in more aesthetically pleasing video as well as higher compression ratio in bandwidth-limited application. Fig 8 shows the frequency response of anti-aliasing filter for horizontal scaling.

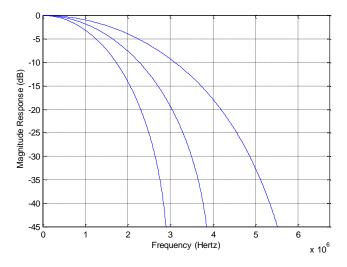


Fig 8 The frequency response of anti-aliasing filter for horizontal scaling

Similarly, the vertical scaler also contains an anti-aliasing filter and 16 poly-phase filters for down scaling. The filter characteristics are shown in Fig 9.

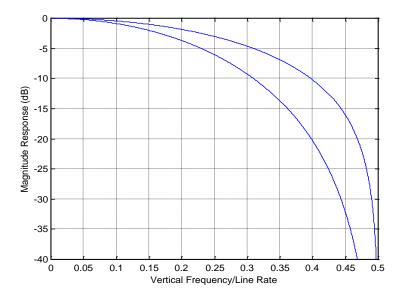


Fig 9 The characteristics of anti-aliasing filter for vertical scaling

Down scaling is achieved by programming the horizontal scaling register HSCALE (0x1C  $\sim$  0x1F, 0x5C  $\sim$  0x5F, 0x9C  $\sim$  0x9F, 0xDC  $\sim$  0xDF) and vertical scaling register VSCALE (0x18  $\sim$  0x1B, 0x58  $\sim$  0x5B, 0x98  $\sim$  0x9B, 0xD8  $\sim$  0xDB). When no scaled video image, the TW2824 will output the number of pixels per line as specified by the HACTIVE (0x04  $\sim$  0x07, 0x44  $\sim$  0x47, 0x84  $\sim$  0x87, 0xC4  $\sim$  0xC7) register. If the number of output pixels required is smaller than the number specified by the HACTIVE register, the 16bit HSCALE register is used to reduce the output pixels to the desired number.

The following equation is used to determine the horizontal scaling ratio to be written into the 16bit HSCALE register.

$$HSCALE = [N_{pixel\_desired} / HACTIVE] * (2^16 - 1)$$

Where N<sub>pixel</sub> desired is the desired number of active pixels per line

For example, to scale picture from full size (HACTIVE = 720) to CIF (360 pixels), the HSCALE value can be found as:

$$HSCALE = [320/720] * (2^16 - 1) = 0x7FFF$$

The following equation is used to determine the vertical scaling ratio to be written into the 16bit VSCALE register.

Where Nine desired is the desired number of active lines per field

For example, to scale picture from full size (VACTIVE = 240 lines for NTSC and 288 lines for PAL) to CIF (120 lines for NTSC and 144 lines for PAL), the VSCALE value can be found as:

$$VSCALE = [120 / 240] * (2^16 - 1) = 0x7FFF for NTSC$$

$$VSCALE = [144 / 288] * (2^16 - 1) = 0x7FFF for PAL$$

The scaling ratios of popular case are listed in Table 2.

Table 2 HSCALE and VSCALE value for popular video formats

Scaling Ratio	Format	Output Resolution	HSCALE	VSCALE
1	NTSC	720x480	0xFFFF	0xFFFF
l	PAL	720x576	0xFFFF	0xFFFF
1/2 (CIE)	NTSC	360x240	0x7FFF	0x7FFF
1/2 (CIF)	PAL	360x288	0x7FFF	0x7FFF
1/4 (QCIF)	NTSC	180x120	0x3FFF	0x3FFF
1/4 (QCIF)	PAL	180x144	0x3FFF	0x3FFF

The cropping function allows only subsection of a video image to be output. The active video region is determined by the HDELAY, HACTIVE ( $0x04 \sim 0x07$ ,  $0x44 \sim 0x47$ ,  $0x84 \sim 0x87$ ,  $0xC4 \sim 0xC7$ ), VDELAY and VACTIVE ( $0x09 \sim 0x0D$ ,  $0x49 \sim 0x4D$ ,  $0x89 \sim 0x8D$ ,  $0xC9 \sim 0xCD$ ) registers. The first active line is defined by the VDELAY register and the first active pixel is defined by the HDELAY register. The VACTIVE register can be programmed to define the number of active lines in a video field, and the HACTIVE register can be programmed to define the number of active pixels in a video line. This function is used to implement for panning and tilt.

The horizontal delay register HDELAY determines the number of pixel delays between the horizontal reference and the leading edge of the active region. The horizontal active register HACTIVE determines the number of active pixels to be processed. Note that these values are referenced to the pixel number before scaling. Therefore, even if the scaling ratio is changed, the active video region used for scaling remains unchanged as set by the HDEALY and HACTIVE register. In order for the cropping to work properly, the following equation should be satisfied.

HDELAY + HACTIVE < Total number of pixels per line

Where the total number of pixels per line is 858 for NTSC and 864 for PAL

To process full size region, the HDELAY should be set to 32 and HACTIVE set to 720 for both NTSC and PAL system.

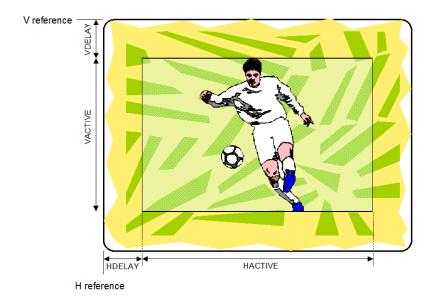
The vertical delay register (VDELAY) determines the number of line delays from the vertical reference to the start of the active video lines. The vertical active register (VACTIVE) determines the number of lines to be processed. These values are referenced to the incoming scan lines before the vertical scaling. In order for the vertical cropping to work properly, the following equation should be satisfied.

VDELAY + VACTIVE < Total number of lines per field

Where the total number of lines per field is 262 for NTSC and 312 for PAL

To process full size region, the VDELAY should be set to 6 and VACTIVE set to 240 for NTSC and the VDELAY should be also set to 5 and VACTIVE set to 288 for PAL.

The effect of scaling and cropping is shown in Fig 10.



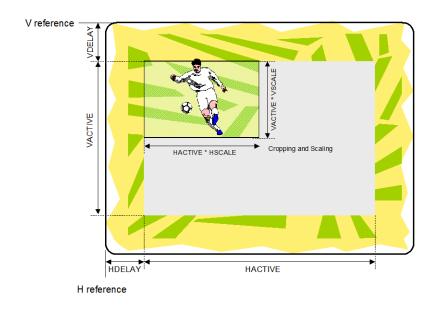


Fig 10 The effect of cropping and scaling

#### **DIGITAL VIDEO INPUT**

The TW2824 supports 1 digital video input from external decoder with 8bit ITU-R BT.656 standard for playback or cascade operation. This digital input is decoded in built-in ITU-R BT 656 decoder and fed to video channel control part with 4 decoded video data from built-in decoder. External decoder should have scaler to display scaled picture and supply valid signal to indicate valid pixel data in scaled video data because the TW2824 does not have scaler for digital video input. The TW2824 supports error correction code for decoding ITU-R BT.656. The timing of digital video input is illustrated in Fig 11.

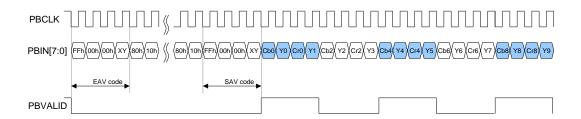


Fig 11 Timing diagram of ITU-R BT.656 format for digital video input

The SAV and EAV sequences are shown in Table 3.

Table 3 ITU-R BT.656 SAV and EAV code sequence

Table 6 116 11 B1:000 C/17 and E/17 0000 coquence											
Condition			656 FVH Value			SAV/EAV Code Sequence					
Field	Vertical	Horizontal	F	V	Н	First	Second Third		Fourth		
EVEN	Plank	EAV	1	4	1				0xF1		
EVEIN	Blank	SAV	I	1	0				0xEC		
EVEN	Active	EAV	1	0	1				0xDA		
EVEIN	Active	SAV	ı		0	0xFF	0x00	0x00	0xC7		
ODD	Blank	EAV	0		1	UXFF	UXUU	UXUU	0xB6		
ODD	DIATIK	SAV	U		0				0xAB		
ODD	Active	EAV	0	0	1				0x9D		
ODD	Active	SAV	U	U	0				0x80		

### **Motion Detector**

The TW2824 supports motion detector individually for 4 analog video inputs. The built-in motion detection algorithm uses the difference of luminance level between current and reference field. The TW2824 also supports blind input detection for 4 analog video inputs. To detect motion properly according to situation, TW2824 provides several sensitivity and velocity control parameters for each motion detector.

When motion or blind is detected in any video inputs, TW2824 provides the interrupt request to host via IRQ pin. The host processor (i.e. Micom or CPU) can take the information of motion or blind by accessing the DET\_MOTION (0x39), DET\_BLIND (0x3A), MD\_MASK (2x84  $\sim$  2x9B, 2xA4  $\sim$  2xBB, 2xC4  $\sim$  2xDB, 2xE4  $\sim$  2xFB) register. This status information is updated in the vertical blank period of each input.

The TW2824 also provides the motion detection result through MPPDEC pin with the control of MPPSET (0x7C) register.

### **MASK AND DETECTION REGION**

The motion detection algorithm utilizes the full screen video data and detects individual motion of 16x12 cell. This full screen for motion detection consists of 704 pixels and 240 for NTSC and 288 for PAL video lines. Starting pixel on horizontal direction can be shifted from 0 to 15 pixel using the MD\_ALIGN (2x80, 2xA0, 2xC0, 2xE0) register.

Each cell can be masked via the MD\_MASK (2x84 ~ 2x9B, 2xA4 ~ 2xBB, 2xC4 ~ 2xDB, 2xE4 ~ 2xFB) register as illustrated in Fig 12. If the mask bit in specific cell is programmed to high, the related cell is ignored for motion detection.

The MD\_MASK register has different function for reading and writing mode. For writing mode, setting "1" to MD\_MASK register inhibits the specific cell from detecting motion. For reading mode, the state of MD\_MASK register has two kinds of information depending on MASK\_MODE (2x80, 2xA0, 2xC0, 2xE0) register. For MASK\_MODE = "1", the state of MD\_MASK register means masking information of cell. For MASK\_MODE = "0", the state of MD\_MASK register means the result of motion detection that "1" indicates detecting motion and "0" denotes no motion detection in the cell.

	<b>—</b>						704 Pi	xels (4	4 Pixe	ls/Cell)	)					
	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0	MASK0
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
Lines/Cell)	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1	MASK1
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
(24	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2	MASK2
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
for 50Hz	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3	MASK3
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
Lines f	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4	MASK4
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
288	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5	MASK5
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
Lines/Cell),	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6	MASK6
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
(20 Line	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7	MASK7
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
60Hz (2	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8	MASK8
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
for	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9	MASK9
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
240 Lines	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10	MASK10
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]
27	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_	MD_
	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11	MASK11
	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]	[10]	[11]	[12]	[13]	[14]	[15]

Fig 12 Motion mask and detection cell

#### SENSITIVITY CONTROL

The motion detector has 4 sensitivity parameters to control threshold of motion detection such as level sensitivity via the MD\_LVSENS (2x81, 2xA1, 2xC1, 2xE1) register, cell sensitivity via MD\_CELSENS (2x81, 2xA1, 2xC1, 2xE1) register, spatial sensitivity via the MD\_SPSENS (2x83, 2xA3, 2xC3, 2xE3) register, and temporal sensitivity parameter via the MD\_TMPSENS (2x83, 2xA3, 2xC3, 2xE3) register. The interval between current and reference field for motion velocity is controlled via the MD\_SPEED (2x82, 2xA2, 2xC2, 2xE2) register.

#### **Level Sensitivity**

In built-in motion detection algorithm, motion is detected when luminance level difference between current and reference field is greater than MD\_LVSENS value. Motion detector is more sensitive for the smaller MD\_LVSENS value and less sensitive for the larger. When the MD\_LVSENS is too small, the motion detector may be weak in noise.

#### **Spatial Sensitivity**

The TW2824 uses 196 (16x12) detection cells in full screen for motion detection. Each detection cell is composed of 44 pixels and 20 lines for NTSC and 24 lines for PAL. Motion detection from only luminance level difference between two fields is very weak in spatial random noise. To remove the fake motion detection from the random noise, a spatial filter is used. The MD\_SPSENS defines the number of detected cell to decide motion detection in full size image. The large MD\_SPSENS value increases the immunity of spatial random noise.

Each detection cell has 4 sub-cells also. Actually motion detection of each cell comes from comparison of sub-cells in it. The MD\_CELSENS defines the number of detected sub-cell to decide motion detection in cell. Likewise, the large MD\_CELSENS value increases the immunity of spatial random noise in small area.

### **Temporal Sensitivity**

Similarly, temporal filter is used to remove the fake motion detection from the temporal random noise. The MD\_TMPSENS regulates the number of taps in the temporal filter to control the temporal sensitivity so that the large MD\_TMPSENS value increases the immunity of temporal random noise.

#### **VELOCITY CONTROL**

Motion has various velocities. That is, in a fast motion an object appears and disappears rapidly between the adjacent fields while in a slow motion it is to the contrary. As the built-in motion detection algorithm uses the only luminance level difference between two adjacent fields, a slow motion is inferior in detection rate to a fast motion. To compensate this weakness, MD\_SPEED (2x82, 2xA2, 2xC2, 2xE2) parameter is used which is controllable up to 64 fields. MD\_SPEED parameter adjusts the field interval in which the luminance level is compared. Thus, for detection of a fast motion a small value is needed and for a slow motion a large value is required. The parameter MD SPEED value should be greater than MD TMPSENS value.

Additionally, the TW2824 has 2 more parameters to control the selection of reference field. The MD\_FLD (2x80, 2xA0, 2xC0, 2xE0) register is a field selection parameter such as odd, even or any field selection.

The MD\_REFFLD (2x82, 2xA2, 2xC2, 2xE2) register is provided to control the updating period of reference field. For MD\_REFFLD = "0", the interval from current field to reference field is always same as the MD\_SPEED. It means that the reference field is always updated every field. Fig 13 shows the relationship between current and reference field for motion detection when MD\_REFFLD is "0".

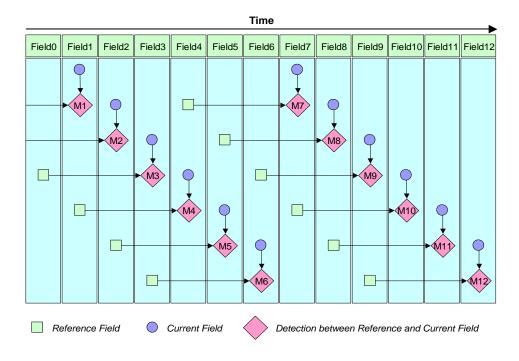


Fig 13 The relationship between current and reference field when MD\_REFFLD = "0"

The TW2824 can update reference field only at the period of MD\_SPEED when MD\_REFFLD is high. For this case, TW2824 can detect a motion with sense of a various velocity. Fig 14 shows the relationship between current and reference field for motion detection when MD\_REFFLD is high.

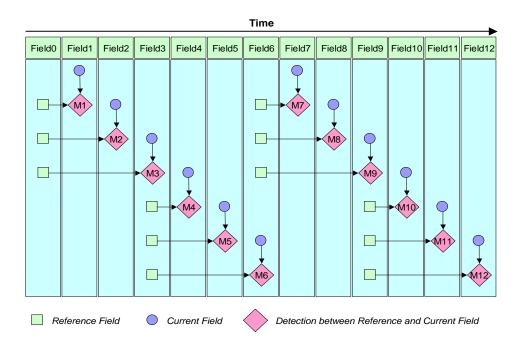


Fig 14 The relationship between current and reference when MD\_REFFLD = "1"

### **BLIND DETECTION**

The TW2824 supports a blind input detection individually for 4 analog video inputs and makes an interrupt of blind detection to host. If video level in wide area of field is almost equal to average video level of field due to camera shaded by something, this input is defined as blind input.

The TW2824 has two sensitivity parameters to detect blind input such as level sensitivity via the BD\_LVSENS (2x7F) register and spatial sensitivity via the BD\_CELSENS (2x7F) register. The BD\_LVSENS parameter controls threshold of level between cell and field average. The BD\_CELL parameter defines the number of cells to detect blind. The TW2824 uses total 768 (32x24) cells of full screen. For BD\_CELSENS = "0", the number of cell whose level is same as average of field should be over than 60% to detect blind. The large value of BD\_LVSENS and BD\_CELSENS makes blind detector less sensitive.

## **Video Control**

The TW2824 has identical dual video controllers for display and capture path. These 2 paths have same functionality except extension capability of external SDRAM. For display path, external SDRAM can be extended from 16M to 512M. This capability is related to only save and recall function. Therefore, hereafter the display and capture path will not be discriminated in the following description and they will be represented just as X and Y path. The block diagram of video controller is shown in following Fig 15.

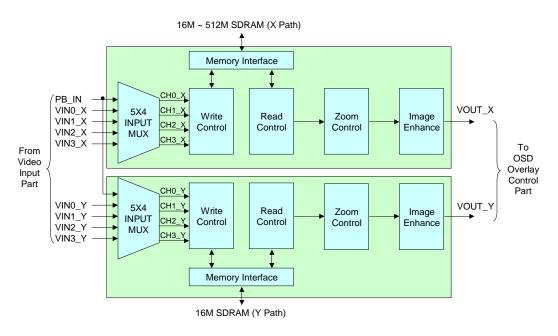


Fig 15 Block diagram of video controller

The TW2824 supports channel blanking, boundary on/off and blink, horizontal mirroring, and freeze function for each channel. The TW2824 can capture last 4 images automatically for each channel when video loss is detected. The TW2824 can save video to external SDRAM and recall for X path. The TW2824 supports image enhancement function for non-real time video such as freezing video or playback video. The TW2824 also provides high performance 2X zoom function with interpolation filter and image enhancement technique.

The TW2824 has three operating modes such as live, strobe and switch mode. Each channel can be operated in its individual operating mode. That is, the TW2824 can be operated as multi-operating mode if each channel has different operating mode. Live mode is used to display real time video as QUAD, strobe mode is used to display non-real time video with strobe signal from host and switch mode is used to display time-multiplexed video from several channels. For switch mode, the TW2824 supports two different types such as switch live and switch still mode.

The TW2824 also provides two picture display modes such as monitor display mode and DVR display mode. For DVR display mode, there are some limitations to control channel size and position.

The TW2824 supports chip-to-chip cascade and path-to-path overlay operation as well.

#### **INPUT SELECTION**

Each video controller for X and Y paths can accept 5 different video sources but can control only 4 video out of 5 video sources. First step is selecting 4 channels to be controlled via the DEC\_PATH (1x10, 1x17, 1x1E, 1x25 for X Path, 1x40, 1x47, 1x4E, 1x55 for Y Path) register. X and Y paths are operated independently and each path has four 5x1 MUX respectively. The selected 4 channel videos are controlled in next step with various operations. Fig 16 shows the internal channel input selection.

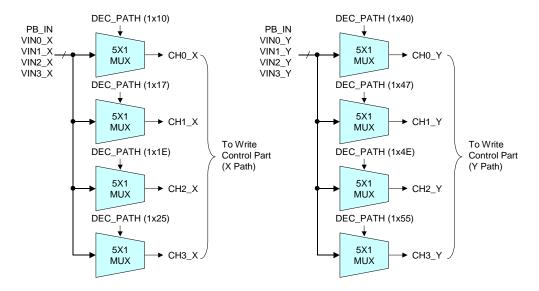


Fig 16 Channel input selection

### **OPERATION MODE**

Each channel can be working with three kinds of operating mode such as live, strobe and switch mode via the FUNC\_MODE (1x10, 1x17, 1x1E, 1x25 for X Path, 1x40, 1x47, 1x4E, 1x55 for Y Path) register. The operation mode can be selected individually for each channel so that multi-operating mode can be implemented.

#### **Live Mode**

If FUNC\_MODE is "0", channel is operated in live mode. For the live mode, video display is updated with real time field rate. This mode is used to display a live video such as QUAD, PIP, and POP.

#### **Strobe Mode**

If FUNC\_MODE is "1", channel is operated in strobe mode. For strobe mode, video display is updated whenever the TW2824 receives strobe command from host like CPU or Micom. If host doesn't send a strobe command to TW2824 anymore, the channel displays the last strobe image until getting a new strobe command. This mode is useful to display non-real time video input such as playback video with multiplexed signal input and to implement pseudo 8 channel application or dual page mode or panorama channel display. Specially, the TW2824 supports easy interface for pseudo 8 channels application and refer to later in dummy channel function section.

Strobe operation is performed independently for each channel via the STRB\_REQ (1x04, 1x34) register. But the STRB\_REQ register has a different mode for reading and writing. Writing "1" into STRB\_REQ in each channel makes the TW2824 updated by each incoming video. The updating status after strobe command can be known by reading the STRB\_REQ register. If reading value is "1", updating is not completed after getting the strobe command. In that case, this channel cannot accept a new strobe command or a disabling strobe command from host. To send a new strobe command, host should wait until STRB\_REQ state is "0". For freeze or non-strobe channel, the TW2824 can ignore the strobe command even though host sends it. In this case, the STRB\_REQ register is cleared to "0" automatically without any updating video. The status of STRB\_REQ register can also be read through MPPDEC pin with control of the MPPSET (0x7C) register.

When updating video with a strobe command, the TW2824 supports field or frame updating mode via the STRB\_FLD (1x04, 1x34) register. Odd field of input video can be updated and displayed for STRB\_FLD = "0", even field for "1". For "2" of STRB\_FLD register, the TW2824 doesn't care for even or odd field, and updates video by next any field. If the STRB\_FLD register is "3", the strobe command updates video by frame. The following Fig 17 shows the example for various STRB\_FLD value.

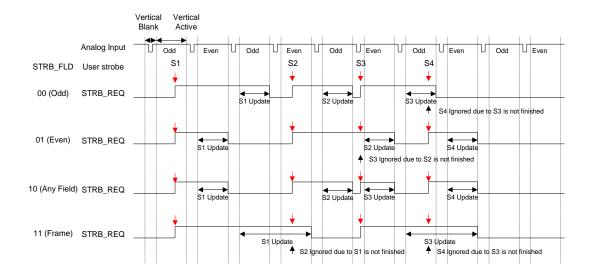


Fig 17 Example of strobe sequence for various STRB\_FLD setting

The timing of strobe operation is related only with input video timing and strobe operation can be performed independently for each channel. So each channel is updated with different timing. The TW2824 provides a special feature as dual page mode using the DUAL\_PAGE (1x04, 1x34) register. Although each channel is updated with different time, all channels can be displayed simultaneously in dual page mode. This means that the TW2824 waits until all channels are updated and then displays all channels with updated video at the same time. When dual page mode is enabled, host should send a strobe command for all channels and host should wait until all channels complete their strobe operations to send a new strobe command. Fig 18 shows the example of 4 channel strobe sequences for dual page.

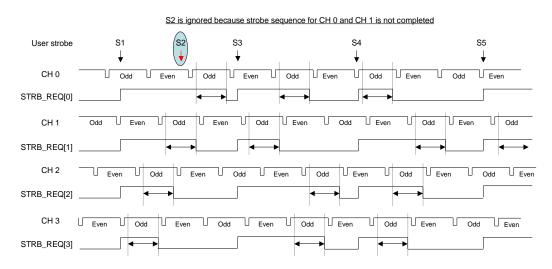


Fig 18 The example of 4 channel strobe sequences for dual page mode

#### **Switch Mode**

If FUNC\_MODE is "2", channel is operated in switch mode. The TW2824 supports 2 different types of switching mode such as still switching and live switching mode via the MUX\_MODE (1x05, 1x35) register. For still switching mode, the TW2824 maintains the switched channel video as still image until next switching request, but for live switching mode the TW2824 updates every field of switched channel video until next switching request. The live switching mode is used for channel sequencer without any timing loss or disturbing. In switch mode, there is a constraint that picture size of the switched channel should be same even though their size can be varied. The TW2824 can switch the channel by fields or frames that can be controlled up to 1 field or 1 frame rate. But if the channel is on freeze state or disabled, the TW2824 ignores the request for switch mode.

The TW2824 contains two internal 64 depth queues which have channel sequence information, and can be operated with internal or external triggering. Actual queue size can be defined by the QUE\_SIZE (1x06, 1x36) register. To change the channel switching sequence in internal queue, set "1" to QUE\_WR register after defining queue address with the QUE\_ADDR (1x09, 1x39) register and channel number with the QUE\_CH (1x08, 1x38) register. The QUE\_WR register will be cleared automatically after updating queue. The channel sequence information in the queue can be read through the QUE\_CH register also.

To operate the switching function properly, the channel switching should be requested with triggering that has three kind modes such as internal triggering from internal field counter, external triggering from external host and interrupted triggering like alarm. The triggering mode can be selected by the TRIG\_MODE (1x05, 1x35) register. This switching architecture is shown in the following Fig 19.

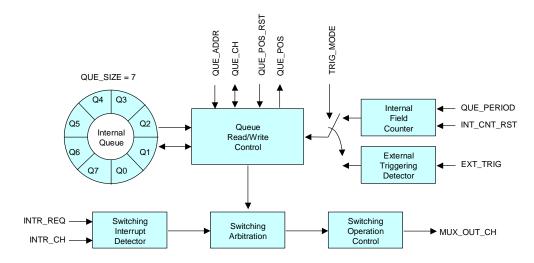


Fig 19 The Switching control structure when QUE\_SIZE = 7

For internal triggering mode, the switching period can be specified in the QUE\_PERIOD (1x07, 1x37) register that has 1 ~ 1024 field range. The internal field counter can be reset at anytime using the INT\_CNT\_RST (1x08, 1x38) register and restarted automatically after reset. To reset an internal queue position, set "1" to QUE\_POS\_RST (1x08, 1x38) register and then the queue position will be restarted after reset. Both INT\_CNT\_RST and QUE\_POS\_RST register can be cleared automatically after set to "1". The following Fig 20 shows an illustration of QUE\_POS\_RST and INT\_CNT\_RST.

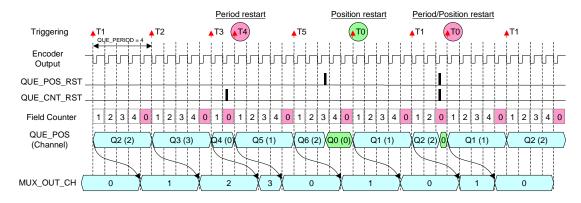


Fig 20 The illustration of QUE\_POS\_RST and INT\_CNT\_RST

For external triggering mode, the request of channel switching comes from the EXT\_TRIG (1x05, 1x35) register. Like internal triggering mode, QUE\_POS\_RST = "1" can reset the queue position in external triggering mode.

For interrupted mode, host can request the channel switching at anytime via the INTR\_REQ and INTR\_CH (1x05, 1x35) register for internal or external triggering mode. Because the interrupted trigger has priority over internal or external triggering, the channel defined by INTR\_CH can be inserted into the programmed channel sequence immediately. The next queue position can be read via the QUE\_POS (1x0A, 1x3A) register.

The TW2824 also provides various switching types as odd field, even field or frame switching via the MUX\_FLD (1x08, 1x38) register. For MUX\_FLD = "0", it is working as field switching mode with only odd field, but with only even field for MUX\_FLD = "1". For MUX\_FLD = "2" or "3", it is working as frame switching with both odd and even field.

Actually the channel switching is executed just before vertical sync of video output in field switching mode or before vertical sync of only odd field in frame switching mode. So all registers for switching should be set before that timing. Otherwise, the control values will be applied to the next field or frame. For the reference timing of switching, the TW2824 provides the VSENC pin whose timing can be varied via ENC\_VSDEL (1x74) and ENC\_VSOFF (1x74) registers. So the timing of VSENC pin can be equal to the vertical sync of video output if the ENC\_VSDEL is set to "16" for 60Hz system or to "22" for 50Hz system.

Basically it takes 4 fields duration to display the switching channel from any triggering (field or frame). The host can read the current switching channel information through the MUX\_OUT\_CH (1x0B, 1x3B) register. The switching channel information is updated just before vertical sync of video output in field switching mode or before vertical sync of only odd field in frame switching mode. The illustration of channel switching is shown in Fig 21 and Fig 22.

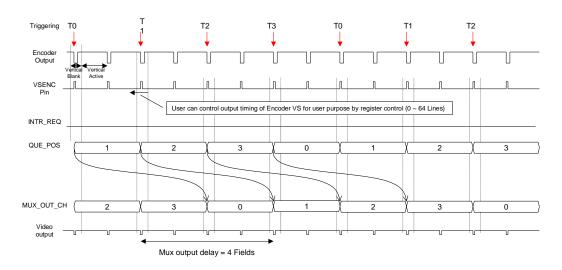


Fig 21 The illustration of switching sequence when Q\_SIZE = 3, Q\_PERIOD = 1

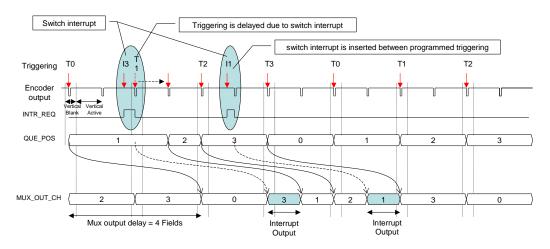


Fig 22 The illustration of the interrupted switching sequence when Q\_SIZE = 3, Q\_PERIOD = 1 The TW2824 has device option for switching operation such as TW2824Q and TW2824QS that have several limitations. The first limitation is that switching mode is fixed to switch live mode. The second limitation is that switching period should be greater than 12 fields.

# **CHANNEL ATTRIBUTE**

The TW2824 provides various channel attributes such as channel enable, boundary selection, blank enable, freeze, horizontal mirroring and image enhancement. As special feature, TW2824 supports save-and-recall function and dummy channel display function for each channel.

# **Background Control**

Summation of all active channel regions can be called as active region and the rest region except active region is defined as background region. The TW2824 supports background overlay and the overlay color is controlled via the BGDCOL (1x0F, 1x3F) register.

# **Boundary Control**

The TW2824 can overlay channel boundary on each channel region using the BOUND (1x11, 1x18, 1x1F, 1x26 for X Path, 1x41, 1x48, 1x4F, 1x56 for Y Path) register and it can be blinked via the BLINK (1x11, 1x18, 1x1F, 1x26 for X Path, 1x41, 1x48, 1x4F, 1x56 for Y Path) register when BOUND is high. The boundary color can be selected through the BNDCOL (1x0F, 1x3F) register. The blink period can be also controlled through the TBLINK (1x04, 1x34) register. For last image capture mode, channel boundary can be blinked automatically.

# **Blank Control**

Each channel can be blanked with specified color using the BLANK (1x11, 1x18, 1x1F, 1x26 for X Path, 1x41, 1x48, 1x4F, 1x56 for Y Path) register and BLKCOL (1x0F, 1x3F) register. The channel blank control is related with last image capture mode. For last image capture mode, channel can be blanked automatically.

#### **Freeze Control**

Each channel can capture last 4 field images whenever freeze function is enabled and display 1 field image out of the captured 4 field images using the FRZ\_FLD (1x0F, 1x3F) register. The freeze function can be enabled or disabled independently for each channel via the FREEZE (1x11, 1x18, 1x1F, 1x26 for X Path, 1x41, 1x48, 1x4F, 1x56 for Y Path) register.

# **Last Image Capture**

When video loss has occurred or gone, the TW2824 provides 4 kinds of indication such as bypass of incoming video, blank, capture of last image and capture of last image with blinking channel boundary depending on the NOVID\_MODE (1x0A, 1x3A) register. This function is working automatically on video loss. The capturing last image is same as freeze function described above. To select 1 field image out of captured 4 filed images, control the FRZ\_FLD (1x0F, 1x3F) register which is shared with freeze function.

# **Horizontal Mirroring**

The TW2824 supports image mirroring function in horizontal direction via the MIRROR (1x11, 1x18, 1x1F, 1x26 for X Path, 1x41, 1x48, 1x4F, 1x56 for Y Path) register. It is useful to display a reflection image.

# **Image Enhancement**

The TW2824 supports special filter to enhance image quality for non real time video display. In non real time video such as freeze image, recalled image from saving images and playback video which records multi-channel video using field switching, so many line flicker noise can be found in image because it displays same field image for both odd and even field. The embedded filter in TW2824 can remove effectively this line flicker noise and be enabled via the ENHANCE (1x11, 1x18, 1x1F, 1x26 for X Path, 1x41, 1x48, 1x4F, 1x56 for Y Path) register for each channel.

#### **Save and Recall Function**

The TW2824 can save images in external memory and recall them to display. This function can be working for X path only because external memory can be extended from 16M to 512M only in X path. The number of images to be saved depends on extended memory capability, picture size and field type (field or frame). This function is working independently for each channel.

The TW2824 can save image only in live channel so that it cannot be saved in freezing channel. If channel is working on strobe operating mode, this channel can be saved with new strobe command. For switch operating mode, the channel can be saved only on switching time because this channel can be updated at this moment.

To save image, several parameters should be controlled which are the SAVE\_FLD, SAVE\_HID, SAVE\_REQ (1x03) and SAVE\_ADDR (1x02) registers. The SAVE\_FLD determines field or frame type for image to be saved. Even though the channel to be saved is hidden by upper layer picture, it can be saved using the SAVE\_HID register that makes no effect on current display. The saving function is requested by writing "1" on the SAVE\_REQ register and this register will be cleared when saving is done. Before it is cleared, the TW2824 cannot accept new saving request. The SAVE\_ADDR register defines address where an image will be saved. Because 4M bit is allocated for each 1 field image, SAVE\_ADDR unit is 4M bit and can have range 0 ~ 127 for 512M. The first 0~3 are reserved for normal operation so that it cannot be used for saving function.

To recall image, several parameters are required such as RECALL\_FLD (1x03), RECALL\_EN and RECALL\_ADDR (1x12, 1x19, 1x20, 1x27) register. If RECALL\_EN is "1", the TW2824 recalls saved image which is located at RECALL\_ADDR in external memory and display it just like incoming video. The RECALL\_FLD register determines 1 field or 1 frame mode to display. The following Fig 23 illustrates the relationship between SDRAM size and SAVE\_ADDR / RECALL\_ADDR.

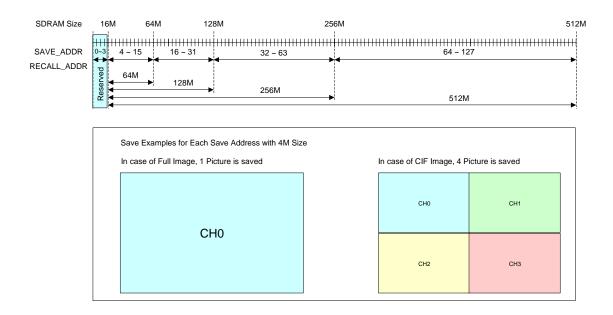


Fig 23 The Relationship between SDRAM size and SAVE\_ADDR / RECALL\_ADDR

# **Dummy Channel Function**

The TW2824 supports additional 4 dummy channel controllers to display up to 8 channel videos even though it is not real time. This dummy channel function is useful to implement low cost and high feature application system such as pseudo 8-channel QUAD system.

The TW2824 has 4 main channel controllers as described before and each main channel has its own corresponding dummy channel. Except channel location and size defined in the PICHL, PICHR, PICVT, and PICVB registers, all attributes of main channel such as boundary, blank, input source selection and pop-up priority are applied to dummy channel also. But the several functions including freeze, save-and-recall and switch operation mode are not supported for dummy channel. Dummy channel can be used for either X or Y path, but picture location and size information of dummy channel is shared in both paths.

To use dummy channel function, dummy channel region should be defined in the DMPICHL (1x60, 1x64, 1x68 and 1x6C), DMPICHR (1x61, 1x65, 1x69 and 1x6D), DMPICVT (1x62, 1x66, 1x6A and 1x6E), and DMPICVB (1x63, 1x67, 1x6B and 1x6F) registers and dummy channel should be enabled using the DMCH\_EN (1x11, 1x17, 1x1E and 1x25 for X Path, 1x41, 1x47, 1x4E and 1x55 for Y Path) register. The path to be updated is selected via the DMCH\_PATH (1x11, 1x17, 1x1E and 1x25 for X Path, 1x41, 1x47, 1x4E and 1x55 for Y Path) register. For DMCH\_PATH = "1", dummy channel will be updated, but for DMCH\_PATH = "0", main channel will be updated. So the updating path should be defined before updating, for example, during vertical blanking time or between completed strobe and new strobe.

Fig 24 shows an example of dummy channel function. This is pseudo 8 channel operation using dummy channel function, strobe operating mode and internal analog mux switch in front of video decoder.

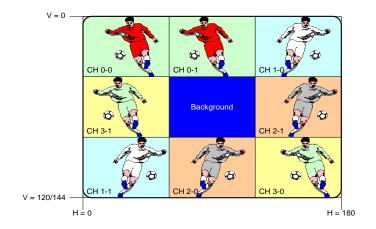


Fig 24 Pseudo 8 channel operation

# **PICTURE DISPLAY MODE**

The TW2824 supports four picture display modes such as monitor display mode, frame display mode, DVR display mode and DVR frame display mode. The DVR display mode and DVR frame display mode generate continuous video stream for each channel and transfer it to compression part (M-JPEG or MPEG) so that they are very useful for DVR application.

The TW2824 provides the independent picture display mode for X and Y path through the DIS\_MODE and FRAME\_OP (1x01, 1x31) register. If FRAME\_OP is "0", DIS\_MODE = "0" stands for monitor display mode and DIS\_MODE = "1" represents DVR display mode. If FRAME\_OP is "1", DIS\_MODE = "0" stands for frame mode and DIS\_MODE = "1" represents DVR frame mode.

# **Monitor Display Mode**

Each channel region can be defined using its own PICHL (1x13, 1x1A, 1x21, 1x28 for X Path, 1x43, 1x4A, 1x51, 1x58 for Y Path), PICHR (1x14, 1x1B, 1x22, 1x29 for X Path, 1x44, 1x4B, 1x52, 1x59 for Y Path), PICVT (1x15, 1x1C, 1x23, 1x2A for X Path, 1x45, 1x4C, 1x53, 1x5A for Y Path), PICVB (1x16, 1x1D, 1x24, 1x2B for X Path, 1x46, 1x4D, 1x54, 1x5B for Y Path) register. If more than 2 channels have same region, there will be a confliction how to display for that area. Generally TW2824 defines that channel 0 has priority over channel 3. So if a conflicting happens between more than 2 channels, channel 0 will be displayed first as top layer and then channel 1 and 2 and 3 are hidden beneath. The TW2824 also provides channel pop-up attribute via the POP\_UP (1x11, 1x17, 1x1E, 1x25 for X Path, 1x41, 1x47, 1x4E, 1x55 for Y Path) register to give priority for another display. If a channel has pop-up attribute, it will be displayed as top layer. Fig 25 shows the channel definition and priority for display. This feature is used to configure PIP (Picture-In-Picture) or POP (Picture-out-Picture).

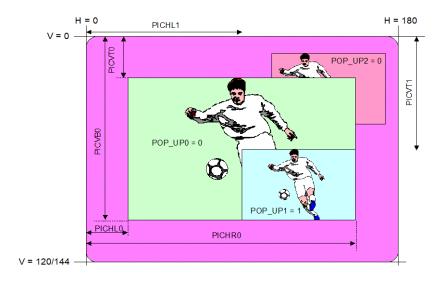
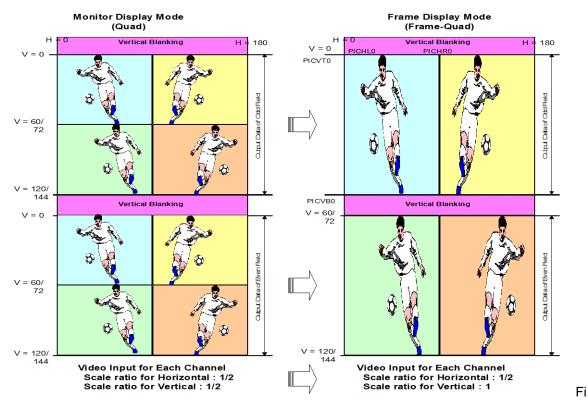


Fig 25 Channel position and overlay in monitor display mode

# **Frame Display Mode**

The frame display mode is similar to monitor display mode except that the definition of picture size is extended to frame area and only one field data is output in 1 frame. The odd or even field selection is controlled via FRAME\_FLD (1x01, 1x31) register. Like monitor display mode, the frame display mode also provides the full flexibility of the picture size and position using PICVT, PICVB, PICHL, PICHR registers and pop-up control using POP\_UP register. But the picture size step for vertical direction is twice as large as monitor display mode. Fig 26 shows the example of channel position and overlay in frame display mode.



g 26 Channel position and overlay in frame display mode

The TW2824 supports the full function such as live/strobe/switch operation, save & recall and dummy channel function in frame display mode. However, there are three limitations in it. The first is that the zoom operation is not supported. The second is that all operation is controlled by frame rate. The third is that the vertical scale ratio should be twice as large as monitor display mode and picture size for vertical direction should be less than one field size.

# **DVR Display Mode**

The DVR display mode outputs the continuous video stream for compression part (M-JPEG or MPEG) in DVR application. Like frame display mode, there is one constraint that all channels should have same picture size and it should be one of 1, 1/2, 1/3 and 1/4 scale ratio for horizontal and vertical direction independently. Channel size can be defined using the HDIV and VDIV (1x01, 1x31) registers. The HDIV controls horizontal scale ratio and the VDIV controls vertical scale ratio. Because all channels have same picture size, all channels have the same value of HDIV and VDIV. So the maximum channel number to be displayed in this mode is "(HDIV+1) \* (VDIV+1)".

The picture position for each channel in DVR display mode is defined via the PICHL[7:6] (1x13, 1x1A, 1x21, 1x28 for X Path, 1x43, 1x4A, 1x51, 1x58 for Y Path) and PICVT[7:6] (1x15, 1x1C, 1x23, 1x2A for X Path, 1x45, 1x4C, 1x53, 1x5A for Y Path) register. The value of PICHL [7:6] should be less than or equal to the value of HDIV and likewise the value of PICVT [7:6] should be less than or equal to the value of VDIV. If the channel is defined out of range, it will not be displayed. The following equation is used to determine the position of channel and Fig 27 shows the example of DVR display mode.

Channel position = (HDIV+1) \* PICVT [7:6] + PICHL [7:6]

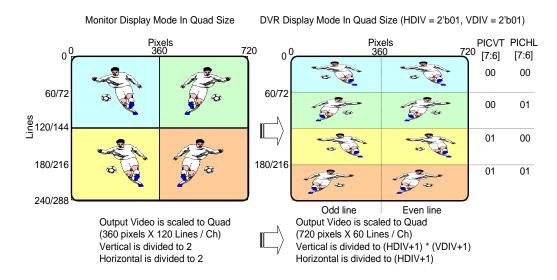


Fig 27 Channel position and overlay for DVR display mode

The TW2824 supports the full function such as live/strobe/switch operation, save & recall and dummy channel function in DVR display mode. However, The channel boundary and zoom operation is not supported in DVR display mode.

# **DVR Frame Display Mode**

The DVR frame display mode is generated from the combination of frame display mode and DVR display mode. The odd or even field selection is controlled via FRAME\_FLD register like frame display mode. The following Fig 28 shows the example of DVR frame display mode.

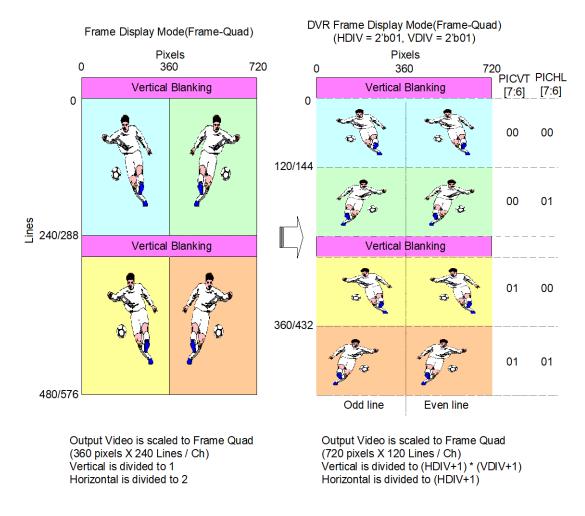


Fig 28 Channel position and overlay for DVR frame display mode

The TW2824 supports the full function such as live/strobe/switch operation, save & recall and dummy channel function in DVR frame display mode. However, there are three limitations in DVR frame display mode. The first is that the channel boundary and zoom operation is not supported. The second is that all operation is based on frame rate like frame display mode. The third is that all channels should have same picture size such as DVR display mode but the vertical scale ratio should be twice as large as DVR display mode.

# **ZOOM FUNCTION**

The TW2824 supports high performance 2X zoom function in vertical and horizontal direction. This function is working in any operation mode such as live, strobe and switch mode in monitor display mode, but it is not working for DVR display mode and frame mode and DVR frame mode because the region to be zoomed cannot be defined and actually this function is needed in only monitor display mode.

Conventional system also has zoom function, but it has a very poor quality due to line flicker noise even though interpolation filter is adapted. The TW2824 provides high quality zoom characteristics using high performance interpolation filter and image enhancement technique. When zoom is executed, the image enhancement is operated automatically.

The zoomed region will be defined with the ZOOMH (1x0D, 1x3D) and ZOOMV (1x0E, 1x3E) registers and can be displayed depending on the ZMBNDCOL, ZMBNDEN, ZMAREAEN, ZMAREA (1x0C, 1x3C) register. The zoom operation is enabled via the ZMENA (1x0C, 1x3C) register.

#### **CASCADE CONNECTION**

The TW2824 supports chip-to-chip cascade connection up to 4 chips for 16 channel application and path-to-path cascade for 5 channels application in all of display mode.

# **Chip-to-Chip Cascade**

The TW2824 can be extended up to 16 channel application using cascade connection and cascade operation is working independently for X and Y path. This means that X path can be operated with cascaded connection even though Y path is working in normal operation. For chip-to-chip cascade connection, the PB\_IN and PB\_VALID pin in master chip should be connected to VDOUTX and VSENC pin in slaver chips. So the playback input is available only in lowest slaver chips and VDOUTX and VSENC output pin is available only in master device when cascaded.

For cascade operation, LINK\_EN, LINK\_NUM and LINK\_LAST (1x00) registers should be controlled properly. The following Fig 29 illustrates cascade connection for dual path.

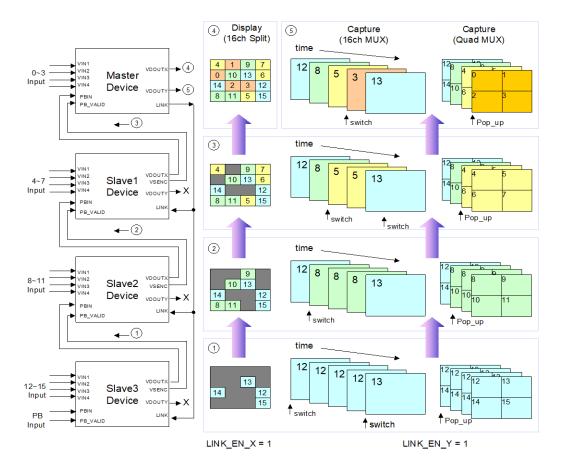


Fig 29 Cascade connection with dual path

When operating with cascade connection, the TW2824 transfers all information of slaver chip to master chips including video data, zoom factors and switching information except overlay information such as box, mouse pointer and OSD information. Therefore, master chip should be controlled for overlay and the lowest slaver chip should be controlled for the others such as video data, zoom and switching. The information of switching channel, MUX\_OUT\_CH (1x0B, 1x3B) can be taken from master chip.

When 2 channels are merged by chip-to-chip cascade, there is a priority from top to bottom layer, popup attributed channel of master device, popup attributed channel of slaver device, non-popup attributed channel of master device and non-popup attributed channel of slaver device. Using this popup attribute, the TW2824 can implement QUAD MUX operation or channel overlay in chip-to-chip cascade connection.

The following Fig 30 illustrates cascade connection with X path only. In this case, user can increase recording rate up to 480 frame/sec with 4 chip cascade connection.

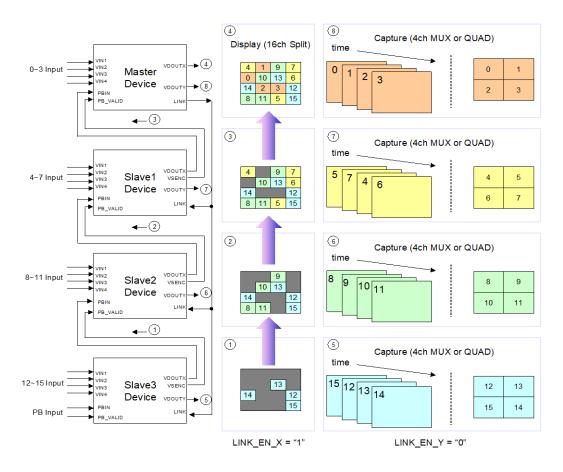


Fig 30 Cascade connection with X path only

# Path-to-Path Cascade

The TW2824 also supports overlay function between X path and Y path. Path-to-path overlay function makes X path overlay on Y path or Y path overlay on X path. This function is useful to display 5 channel video for only single path application.

By enabling the OVERLAY\_X (1x00) register, active video of Y path can be overlaid on X path and the opposite case is also possible via OVELAY\_Y (1x00) register. When 2 paths are merged by overlay function, there is a priority from top to bottom layer, popup attributed channel of main path, popup attributed channel of overlaid path, non-popup attributed channel of main path and non-popup attributed channel of overlaid path. The example of path-to-path overlay function is shown in Fig 31. In this example, a main path is X path which has 4 channels (CH0, CH1 CH2, CH3) with non-popup attributed, and the overlaid path is Y path which has 1 channel (CH0) with popup attributed.

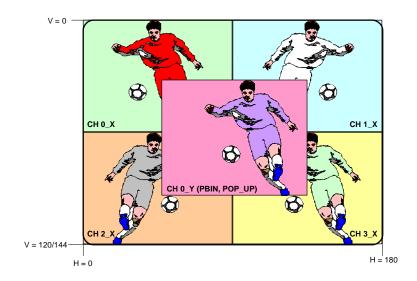


Fig 31 Example of path-to-path overlay function

# **OSD (On Screen Display) Overlay**

The TW2824 provides various OSD (On Screen Display) overlays such as character/bitmap overlay, box overlay and mouse pointer that can be overlaid on X and Y path independently. The following Fig 32 shows OSD overlay block diagram. The font data can be downloaded from host and supported up to 128 fonts. The TW2824 has 16 programmable single boxes and four 2D arrayed boxes that are programmable for size, position and color.

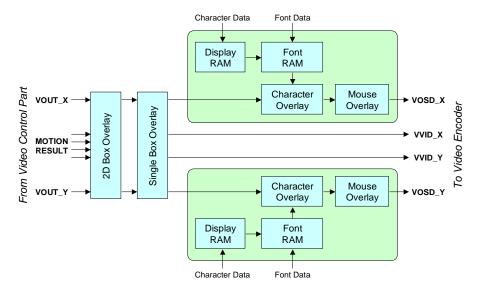


Fig 32 OSD overlay block diagram

Dual analog video outputs and dual digital video outputs can enable or disable a character and mouse pointer respectively. The overlay priority of OSD layer is shown in Fig 33. The various OSD overlay function is very useful to build GUI interface.

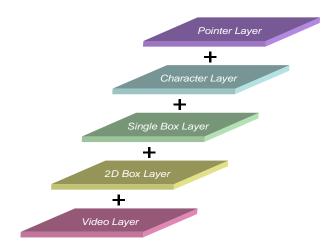


Fig 33 The overlay priority of OSD layer

# **CHARACTER/BITMAP OVERLAY**

The TW2824 has character overlay function for X and Y path independently. Each character overlay function block consists of a font RAM, a display RAM and an overlay control block. A font RAM stores font data that can be downloaded from host at anytime. A display RAM stores index, position and attributes of character to be displayed. Character size can be defined as  $8\sim14$  dots in horizontal and  $10\sim16$  lines in vertical direction.

Bitmap data can also be downloaded from host just like character. That is, Bitmap is almost same as character except the control of class 0 color. A character type has a blank for class 0 color in default mode, but a bitmap color has a selectable color for it. However, if CLASSEN0 (1x81) is set to "1", even a character type can have a selectable color like bitmap type. In that case, a character type is completely same as a bitmap type. The character and bitmap types can be selected via TYPE bit of character attributes in display RAM.

# **Download Font Group**

The TW2824 supports 4 different font groups and each font group can have 128 fonts. A font consists of several dots such as 8 (10, 12, 14) x 10 (12, 14, 16) dots. 1 dot is composed of 2 pixels x 1 video line and each dot has 2 bits to define colors (class 0, class1, class2 and class3). The following Fig 34 shows a font RAM structure.

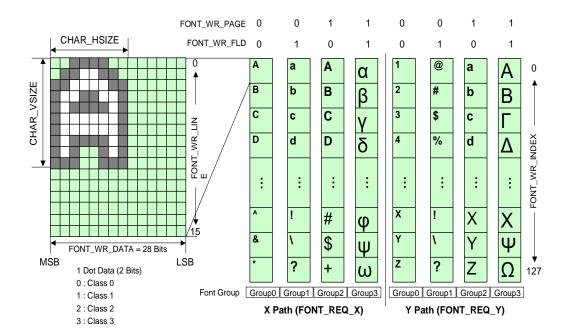


Fig 34 Font RAM structure

Font data can be written to font RAM via FONT\_WR\_DATA (1x7A ~ 1x7D), FONT\_WR\_INDEX (1x7E), FONT\_WR\_LINE, FONT\_WR\_FLD, FONT\_WR\_PAGE and FONT\_REQ (1x7F) register. By setting "1" to FONT\_REQ, font data in the FONT\_WR\_DATA is transferred to font RAM addressed by FONT\_WR\_INDEX, FONT\_WR\_LINE, FONT\_WR\_FLD and FONT\_WR\_PAGE. The FONT\_REQ register has status information of transferring in read mode. If FONT\_REQ = "1" in read mode, it means that the TW2824 is busy in transferring font data. In this case, additional request cannot be accepted. The TW2824 has individual 2 FONT\_REQ for X and Y path so that the different font data can be stored in font RAM of X and Y path. The TW2824 requires special font data for index 0 to define blank character that will be discussed in write character section. Fig 35 shows the flow chart of transferring font data to font RAM.

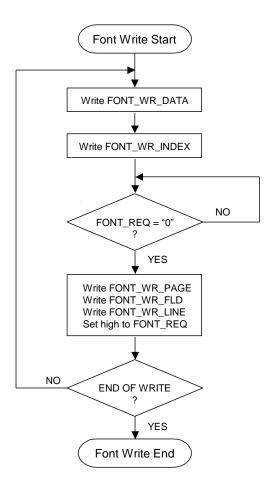


Fig 35 Flow chart of downloading font data

# **Select Font Group**

The font group can be divided into 4 groups for X and Y path as shown in Fig 34. The FONT\_RD\_PAGE register selects one of two pages. Setting "0" to FONT\_RD\_FLD register makes a character overlay function disabled. If the FONT\_RD\_FLD register is set to "1" or "2", one group fonts are displayed for both odd and even field. But by setting "3" on FONT\_RD\_FLD register, the different font groups are displayed on odd and even field respectively so that the character resolution can be enhanced 2 times in vertical direction. The following Fig 36 is shown for the structure of the font group.

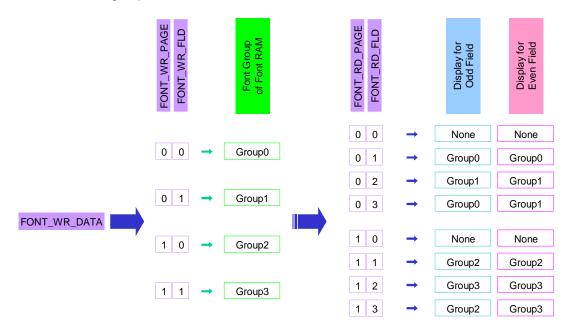


Fig 36 Structure of font group

# **Write Character**

The TW2824 has independent 2 display RAM for X and Y path and each character in display RAM has its own character's attributes which include mix, blink, class 3 color, type and font index. The display RAM consists of 45x29 character's attributes. Actually the number of displayed characters depends on character size. The horizontal and vertical address of display RAM represents character position to be displayed. The following Fig 37 shows the structure of display RAM.

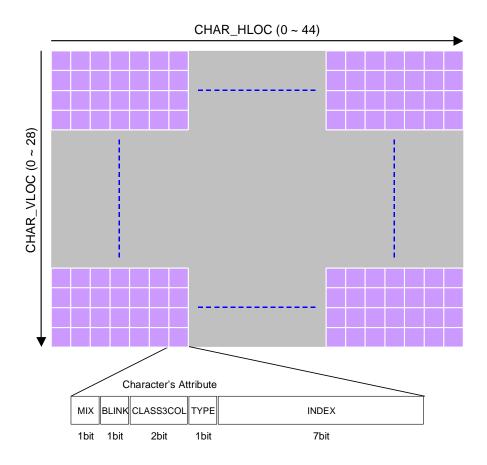


Fig 37 Display RAM structure

Before writing character's attribute, the CHAR\_PATH, CHAR\_VLOC (1x9Ch) and CHAR\_HLOC (1x9Dh) register should be written previously to define the location of displayed character. CHAR\_PATH defines the path (X or Y path) and CHAR\_VLOC / CHAR\_HLOC defines the vertical / horizontal location of displayed character. The character's attribute consists of 12bit so that 2 bytes are required to write in display RAM. The TW2824 supports the special procedure for writing to and reading from display RAM as shown in Fig 38. If the character's attributes are written continuously with the same path and vertical location, CHAR\_HLOC value increases by 1 automatically.

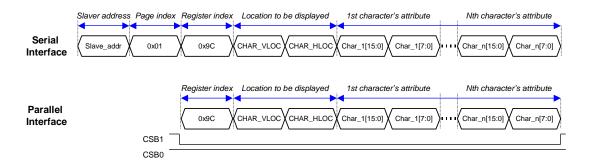


Fig 38 Writing procedure to display RAM

The TW2824 also supports a useful function that writes blank character to whole display RAM automatically by setting "1" to RAMCLR (1x81). This function requires that font data in index 0 should be blank character and the CLASSEN0 (1x81) register should be set to "0" because it writes this character in index 0 to whole display RAM. This RAM clear function takes about 100usec and the RAMCLR register will be cleared by itself after finished.

#### **Character Attribute**

Each character has its own attributes in display RAM that includes mix, blink, class 3 color of character, type and font index. The mix attribute makes character mixed with video data by half tone and blink attribute makes blinked character with the period defined in PHIGH and PLOW (1x81) register. The class 3 color of character takes one of 4 colors defined in the CLASS3COL (1x89 ~ 1x8C) register. The type attribute defines one of 2 types, character or bitmap type for each character and the font index attribute defines address of font. The mix and blink attributes can be enabled for each class via the CHAR\_MIX (1x87), CHAR\_BLK (1x88) register for each character or bitmap.

# **Character Color**

The TW2824 provides 16 different colors that consist of fixed 12 colors (8 colors from color bar of 75% amplitude 100% saturation and 100% white, 50% gray, 25% gray and 75% blue) and user's defined 4 colors using the CLUT (1x90 ~ 1x9B) register. The class 0, 1 and 2 color of character will be one of 16 colors via the CLASS0COL, CLASS1COL and CLASS2COL (1x8D ~ 1x8F) registers and are applied to all of characters to be displayed. For class 3 color, 4 colors are predefined via

the CLASS3COL ( $1x89 \sim 1x8C$ ) register and each character can take one of these 4 colors using character's attribute as described previously. The different color selection for each character and bitmap can be supported also.

# **Character Size and Space**

The TW2824 supports different character size for X path and Y path and the character size can be varied horizontally and vertically. The CHAR\_HSIZE (1x82) register defines horizontal character size that can be one of 8, 10, 12 and 14 dots and the CHAR\_VSIZE (1x82) register defines vertical character size that can be one of 10, 12, 14 and 16 lines. The character size is not required to be same with font size. If character size is greater than downloaded font size, garbage data are displayed in character region and if character size is smaller than downloaded font size, font will be cropped by character size.

Likewise, the space between characters can be varied horizontally and vertically. The CHAR\_HSPC (1x83, 1x85) register defines horizontal character space that can be increased by 1 dot unit and the CHAR\_VSPC (1x83, 1x85) register defines vertical character space that can be increased by 1 line unit. The TW2824 can define the horizontal and vertical position for first dot of first character. The CHAR\_HDEL (1x84, 1x86) register defines horizontal delay and the CHAR\_VDEL (1x84, 1x86) register defines vertical delay. Each unit is same as CHAR\_HSPC and CHAR\_VSPC unit. The following Fig 39 shows the definition of character size and space.

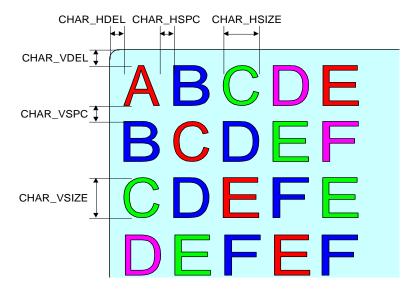


Fig 39 Definition of character size and space

# **BOX OVERLAY**

The TW2824 supports two kinds of box overlay such as 16 single boxes and 4 2-dimensional arrayed boxes.

# Single Box

The TW2824 provides 16 single boxes that can be a flat type or 3D type using the BOX\_TYPE (2x03) register. The flat type is just simple rectangular box and 3D type looks like 3 dimension view. Each single box has programmable location and size parameters with the BOX\_HL (2x08 + 5N, N = 0 ~ 15), BOX\_HW (2x09 + 5N, N = 0 ~ 15), BOX\_VT (2x0A + 5N, N = 0 ~ 15) and BOX\_VW (2x0B + 5N, N = 0 ~ 15) registers. The BOX\_HL is the horizontal location of box with 2 pixel unit and the BOX\_HW is the horizontal size of box with 4 pixel unit. The BOX\_VT is the vertical location of box with 1 line unit and BOX\_VW is the vertical size of box with 2 line unit. There are some definitions about single box as shown in Fig 40.

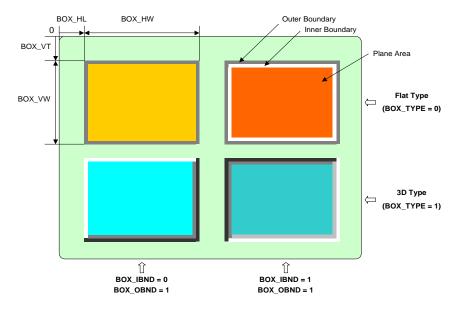


Fig 40 Single box structure

The other controllable parameters are plane color, boundary color, boundary enable, luminance level control of plane. The single box plane is controlled via BOX\_OBND (2x07 + 5N, N = 0~15) and BOX\_IBND (2x07 + 5N, N = 0~15) register as described in Table 4. BOX\_PLNEN (2x03) register enables each plane color and its color is defined by BOX\_PLNSEL (2x07 + 5N, N = 0~15) and BOX\_PLNCOL (2x05, 2x06) register. Using BOX\_PLNSEL, the plane of each single box can have one of 4 colors defined by BOX\_PLNCOL as described in character color section. Actually the TW2824 provides total 16 different colors that consist of fixed 12 colors (8 colors from color bar and 100%, 50%, 25% gray and 75% blue) and user's defined 4 colors using CLUT (1x90 ~ 1x9B) register. This color table is used in common with plane color for single box and character color. The

color of box boundary is defined by BOX\_TYPE (2x03), BOX\_OBND (2x07 + 5N, N =  $0\sim15$ ), BOX\_IBND (2x07 + 5N, N =  $0\sim15$ ) and BOX\_BNDCOL (2x04) registers

Table 4 The Color of Single Box Boundary

Boundary		C	ontrol Registe		Color Description			
Bou	ndary	BOX_TYPE	BOX_OBND	BOX_IBND	Register	Color		
			0	0		Box off		
Outer		0	0	1	BOX_ BNDCOL [7:4]	Boundary off		
			1	0		0~10:0, 10, 20, 30, 40, 50, 60, 70, 80, 90, 100 IRE Gray 11~14: Selected by BOX PLNCOL0 ~ BOX PLNCOL3.		
			1	1		15 : Same as plane color with 20IRE down of luminance		
		(Flat Type)	0	0	BOX_ BNDCOL [3:0]	Box off		
In	ner		1	0		Same as inner area		
			0	1		0~10:0, 10, 20, 30, 40, 50, 60, 70, 80, 90, 100 IRE Gra		
			1	1		15 : Same as plane color with 20IRE up of luminance		
	Left		0	0	BOX_ BNDCOL [7:6]	Box off		
	&	1	0	1		Boundary off		
	Тор		1	0		0~3 : 90, 80, 70, 60 IRE Gray		
Outer			1	1		0~3:0, 10, 20, 30 IRE Gray		
	Right & Bottom		0	0	BOX_ BNDCOL [5:4]	Box off		
			0	1		Boundary off		
			1	0		0~3:0, 10, 20, 30 IRE Gray		
			1	1		0~3 : 90, 80, 70, 60 IRE Gray		
	Left	(3D Type)	0	0		Box off		
	&		0	1	BOX_ BNDCOL	Boundary off		
	Тор		1	0	[3:2]	Same as inner area		
Inner			1	1		0~3 : 30, 40, 50, 60 IRE Gray		
	Right		0	0	BOX_ BNDCOL [1:0]	Box off		
	&		0	1		Boundary off		
	Bottom		1	0		0~3 : 30, 40, 50, 60 IRE Gray		
			1	1		0~3 : 70, 60, 50, 40 IRE Gray		

For the box plane, luminance level can be controlled through the BOX\_IBND register when BOX\_EMP (2x03) register = '1". BOX\_IBND = "1" makes luminance level of plane down by 20IRE and BOX\_IBND = "0" makes up by 20IRE. The each box plane can be mixed with video data via the BOX\_PLNMIX (2x07 + 5N, N =  $0\sim15$ ) register. The BOX\_PATH (2x07 + 5N, N =  $0\sim15$ ) register determines the boxes to be displayed on X or Y path because box overlay is supported by only one path.

In case that more than 2 boxes have same region, there will be confliction how to display for that region. Generally TW2824 defines that box 0 has priority over box 15. So if a conflicting happens between more than 2 boxes, box 0 will be displayed first as top layer and box 1 to box 15 are hidden beneath that are not supported for pop-up attribute unlike channel display.

# 2Dimensional Arrayed Box

The TW2824 supports 4 2D arrayed boxes that have programmable cell size up to 16x16. The 2D arrayed box is useful to make a table or display motion detection result for analog input.

The 2DBOX\_HNUM and 2DBOX\_VNUM (2x66, 2x6D, 2x74, 2x7B) registers define the number of row and column cells. For each 2D arrayed box, the horizontal location of left-top for 2D box is defined by the 2DBOX\_HL (2x63, 2x6A, 2x71, 2x78) register with 2 pixels step and the vertical location of left-top is defined by the 2DBOX\_VT (2x62, 2x69, 2x70, 2x77) register with 1 line step. The vertical size of each cell is defined by the 2DBOX\_VW (2x64, 2x6B, 2x72, 2x79) register with 1 line step and the horizontal size is defined by the 2DBOX\_HW (2x65, 2x6C, 2x73, 2x7A) register with 2 pixel step. So the whole size of 2D arrayed box is same as the sum of cells in row and column.

The boundary of 2D arrayed box can be enabled by the 2DBOX\_BNDEN (2x61, 2x68, 2x6F, 2x76) register and its color is controlled via the 2DBOX\_BNDCOL (2x60) register which selects one of 4 colors such as 0% black, 25% gray, 50% gray and 75% white.

The plane of 2D arrayed box can be enabled by the 2DBOX\_PLNEN (2x61, 2x68, 2x6F, 2x76) register and its color is controlled by the 2DBOX\_PLNCOL (2x60) register which selects one of 16 colors as described in character color and plane color of single box section. The plane can be mixed with video data by the 2DBOX\_MIX (2x61, 2x68, 2x6F, 2x76) register.

Specially, the TW2824 provides the function to indicate cursor cell inside 2D arrayed box. The cursor cell can be enabled by 2DBOX\_CUREN (2x61, 2x68, 2x6F and 2x76) register and its location to be displayed is defined by 2DBOX\_CUR\_HP and 2DBOX\_CUR\_VP (2x67, 2x6E, 2x75 and 2x7C) registers. Its color is a reverse color of cell boundary. It is useful function to control motion mask region.

Even though 2D arrayed box is available for drawing a table, its function is used mainly to display motion information. 2D arrayed box can be selected to work in table mode or motion display mode through the 2DBOX\_MODE (2x61, 2x68, 2x6F, 2x76) register. When 2D arrayed box is working in motion display mode, the plane of 2D arrayed box shows the mask information according to the MD\_MASK register automatically. For the motion display mode, additional narrow boundary of each cell is provided to display motion detection result for each cell and its color is a reverse color of cell boundary like cursor cell.

The TW2824 has 4 2D arrayed boxes so that 4 video channels can have its own 2D arrayed box for motion display mode. To overlay mask information and motion result on video data properly, the scaling ratio of video should be matched with 2D arrayed box size.

Each 2D arrayed box can be displayed in only one path that is defined by the 2DBOX\_PATH (2x61, 2x68, 2x6F and 2x76) register. The following Fig 41 shows the 2D arrayed box in table mode and Fig 42 shows 2D arrayed box in motion display mode.

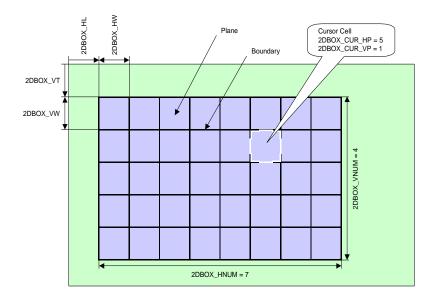


Fig 41 2D arrayed box in table mode

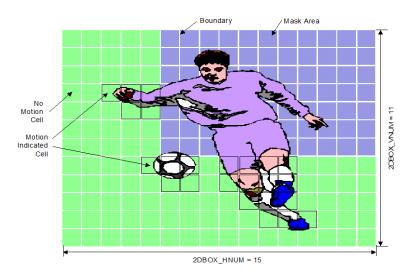


Fig 42 2D arrayed box in motion display mode

In case that more than 2 2D arrayed boxes have same region, there will be confliction how to display for that region. Generally TW2824 defines that 2D arrayed box 0 has priority over 2D arrayed box 3. So if a conflicting happens between more than 2 2D arrayed boxes, 2D arrayed box 0 will be displayed first as top layer and 2D arrayed box 1, box 2, box 3 are hidden beneath that are not supported for pop-up attribute like single box.

# **MOUSE POINTER**

The TW2824 supports two kinds of mouse pointer that has attributes such as pointer enable, pointer location, blink enable and sub-layer enable. Mouse pointer can be overlaid on both X and Y path independently even though all attributes are applied to both paths in common.

The mouse pointer is located in the full screen according to the CUR\_HP (2x01) register with 2 pixel step and CUR\_VP (2x02) register with 1 line step. Two kinds of mouse pointer are provided through the CUR\_TYPE (2x00) register. The CUR\_SUB (2x00) register determines a pointer inside area to be filled with 100% white or to be transparent and CUR\_BLINK (2x00) register controls a blink function of mouse. Actually the CUR\_ON (2x00) register enables or disables mouse pointer for X and Y path independently. The following Fig 43 describes the parameters of mouse pointer.

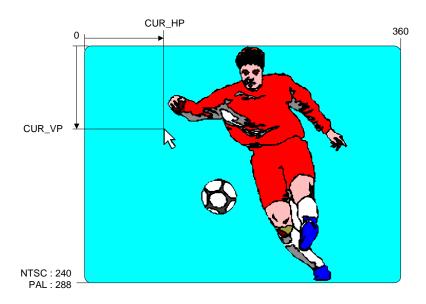


Fig 43 Parameters of mouse pointer

# **Video Output**

The TW2824 supports dual digital video outputs with ITU-R BT.656 format and 2 analog video outputs with built-in video encoder at the same time. Dual video controllers described above generate 4 kinds of video data, X path video data with or without OSD and Y path video data with or without the OSD. CCIR\_IN (1x70) register selects one of 4 video data for the digital video output and ENC\_IN (1x70) register selects one of 4 video data for the analog video output as shown in Fig 44.

The TW2824 supports all NTSC and PAL standards for analog output which can be composite or S-video video for both X and Y path. All outputs can be operated as master mode to generate timing signal internally or slave mode to be synchronized with external timing.

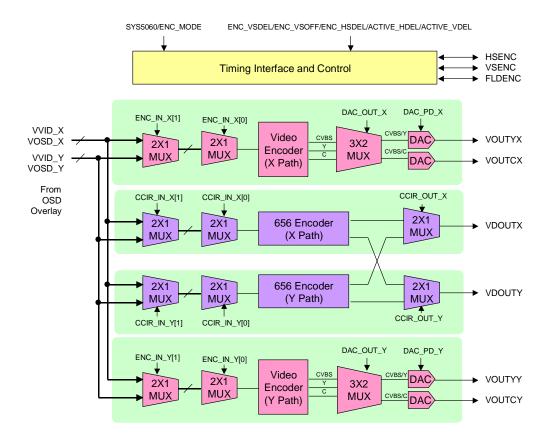


Fig 44 Video output selection

The TW2824 has device option for dual output such as TW2824MS and TW2824QS. These devices have a limitation for output selection. That is, the value of CCIR\_IN\_X [1], CCIR\_IN\_Y [1] and ENC\_IN\_Y [1] is equal to ENC\_IN\_X [1] so that only one path is available for output selection.

# **ANALOG VIDEO OUTPUT**

The TW2824 supports analog video output using built-in video encoder which generates composite or S-video with 10 bits dual DAC for both X and Y path. The incoming digital video are adjusted for gain and offset according to NTSC or PAL standard. Both the luminance and chrominance are band-limited and interpolated to 27MHz sampling rate for digital to analog conversion. The NTSC output can be selected to include a 7.5IRE pedestal. The TW2824 also provides internal test color bar generation.

# **Output Standard Selection**

The TW2824 supports various video standard outputs via the SYS5060 (1x00) and ENC\_FSC, ENC\_PHALT, ENC\_PED (1x77) registers as described in the following Table 5.

Table 5 Analog output video standards

Format		Specification	<u> </u>	Register					
Format	Line/Fv (Hz)	Fh (KHz)	Fsc (MHz)	SYS5060	ENC_FSC	ENC_PHALT	ENC_PED		
NTSC-M	525/59.94	15.734	3.579545	0	0	0	1		
NTSC-J	525/59.94						0		
NTSC-4.43	525/59.94 15.734		4.43361875	0	1	0	1		
NTSC-N	NTSC-N 625/50 15.625 3.5795		3.579545	1	0	0	0		
PAL-BDGHI	625/50	15.625	4.43361875	1	1	1	0		
PAL-N	625/50						1		
PAL-M	525/59.94	15.734	3.57561149	0	2	1	0		
PAL-NC	625/50	15.625	3.58205625	1	3	1	0		
PAL-60	525/59.94	15.734	4.43361875	0	1	1	0		

If the ENC\_ALTRST (1x77) register is set to "1", phase alternation can be reset every 8 field so that phase alternation keeps same phase every 8 field.

# **Luminance Filter**

The band of luminance signal can be selected as shown in the following Fig 45.

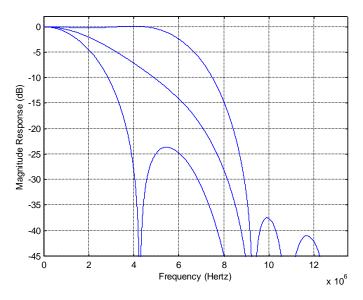


Fig 45 Characteristics of luminance filter

# **Chrominance Filter**

The band of chrominance signal can be selected as shown in the following Fig 46.

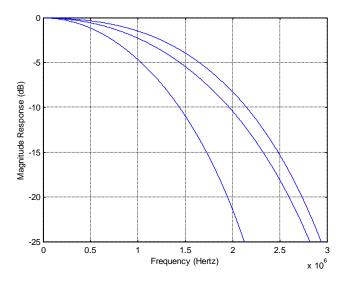


Fig 46 Characteristics of chrominance Filter

# **Digital-to-Analog Converter**

Digital video data from video encoder is converted to analog video signal by DAC (Digital to Analog Converter). Analog video signal format can be selected for both X and Y path independently via the DAC\_OUT (1x71) register as dual composite when DAC\_OUT = "1" and S-video when DAC\_OUT = "0". Each DAC can be disabled independently to save power by the DAC\_PD (1x71) register.

A simple reconstruction filter is required externally to reject noise as shown in Fig 47.

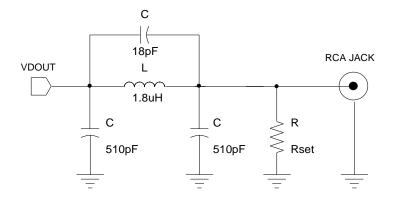


Fig 47 Example of reconstruction filter

The frequency responses of above reconstruction filters are shown in the following Fig 48.

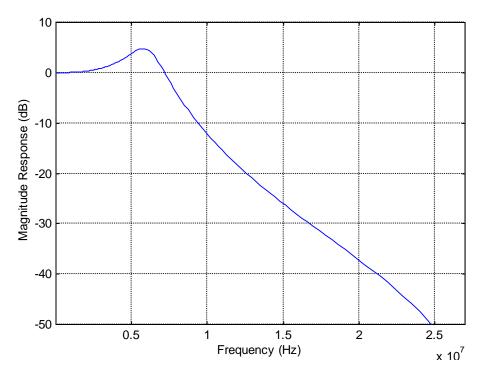


Fig 48 Frequency response of reconstruction filter

# **DIGITAL VIDEO OUTPUT**

The digital output data with ITU-R BT.656 format is synchronized with CLK27ENC pin which is 27MHz for single output or 54MHz for dual output. Each digital data of X and Y path can be output through VDOUTX and VDOUTY pin respectively on single output mode. For the dual output mode, both X and Y path output can come out through only one VDOUTX or VDOUTY. The level of active video of ITU-R BT.656 can be limited to 16 ~ 235 level by the CCIR\_LMT (1x73h) register.

Table 6 ITU-R BT.656 SAV and EAV code sequence

	Line		Condition			FVH			SAV/EAV Code Sequence			
	From	То	Field	Vertical	Horizontal	F	٧	Н	First	Second	Third	Fourth
	523	3	EVEN	Blank	EAV	4	1	1			0x00	0xF1
		3			SAV	1		0	0xFF	0x00		0xEC
	4	19	ODD	Blank	EAV	0	1	1				0xB6
					SAV			0				0xAB
(sət	20	259	ODD	Active	EAV	0	0	1				0x9D
60Hz (525Lines)	20	239	ODD	Active	SAV		U	0				0x80
1z (5)	260 2	265	ODD	Blank	EAV	0	1	1				0xB6
409	200	200	ODD	DIATIK	SAV	U	ı	0				0xAB
	266 28	282	EVEN	Blank	EAV	1	1	1				0xF1
		202			SAV			0				0xEC
	283 522	522	EVEN	Active	EAV	1	0	1				0xDA
	203	200 022	LVLIV		SAV			0				0xC7
	1 22	22	ODD	Blank	EAV	0	1	1				0xB6
		ODD	Diank	SAV	Ů	'	0				0xAB	
	23 310	310	ODD	Active	EAV	0	0	1	0xFF	0x00	0x00	0x9D
		310	ODD		SAV			0				0x80
(sət	311 312	312	2 ODD	Blank	EAV	0	1	1				0xB6
25Lir	311	312			SAV			0				0xAB
50Hz (625Lines)	313 335	335	335 EVEN	Blank	EAV	1	1	1				0xF1
50H		333			SAV			0				0xEC
	336	336 623 I	EVEN	Active	EAV	1	0	1				0xDA
	330				SAV			0				0xC7
	624 625	625	20E EVEN	Blank	EAV	1		1				0xF1
		25 EVEN	DIATIK	SAV	1	1	0			-	0xEC	

# **Single Output Mode**

For the single output mode, each digital output data in X and Y path can be output at 27MHz through VDOUTX and VDOUTY pin that are synchronized with CLK27ENCX and CLK27ENCY respectively. The polarity and frequency of CLK27ENCX and CLK27ENCY can be controlled independently by ENCCLK\_X, ENCCLK\_Y, ENCCLKP\_X and ENCCLKP\_Y (1x5F) registers. The data to be output is selected by the CCIR\_OUT (1x72) register which selects X path data for "0" and Y path data for "1". The timing diagram of single output mode is shown in following Fig 49.

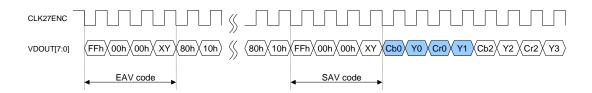


Fig 49 Timing diagram of single output mode

#### **Dual Output Mode**

The TW2824 also supports dual output mode that is time-multiplexed with X and Y path data at 54MHz clock rate. The sequence is related with the CCIR\_OUT (1x72) register that X path data precedes Y path for CCIR\_OUT = "2" and Y path data precedes X path for CCIR\_OUT = "3". The data to be output is synchronized with 54MHz CLK27ENCX and CLK27ENCY pins. The polarity and frequency of CLK27ENCX and CLK27ENCY can be controlled independently by ENCCLK\_X, ENCCLK\_Y, ENCCLKP\_X and ENCCLKP\_Y (1x5F) registers. The timing diagram of dual output mode is illustrated in Fig 50. The dual output mode is useful to reduce number of pins for interface with other devices.

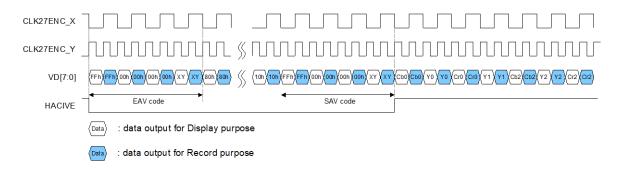


Fig 50 Timing diagram of dual output mode

# TIMING INTERFACE AND CONTROL

The TW2824 can be operated in master mode or slave mode via the ENC\_MODE (1x73) register. In master mode, TW2824 can generate all of timing signals internally while TW2824 receives all of timing signals from external device in slave mode.

The polarity of horizontal, vertical sync and field flag can be controlled by the ENC\_HSPOL, ENC\_VSPOL and ENC\_FLDPOL (1x73) register respectively for both master and slaver mode. The TW2824 can detect field polarity from vertical sync and horizontal sync via the ENC\_FLD (1x73) register or can detect vertical sync from the field flag via the ENC\_VS (1x73) register.

The TW2824 provides or receives timing signal through the HSENC, VSENC and FLDENC pins. To adjust the timing of those pins, the TW2824 has the ENC\_HSDEL (1x75), ENC\_VSDEL and ENC\_VSOFF (1x74) registers which control only the related signal timing regardless of analog and digital video output. Likewise, by controlling the ACTIVE\_VDEL (1x76) register and ACTIVE\_HDEL (1x76) registers, only active video period can be shifted on horizontal and vertical direction independently. The shift of active video period produces the cropped video image because the timing signal is not changed even though active period is moved. So this feature is restricted to adjust video location in monitor for example. The active video data period of analog video output is same as digital video output so that the video timing of both outputs can be controlled in common. The detailed timing diagram is illustrated in the following Fig 51.

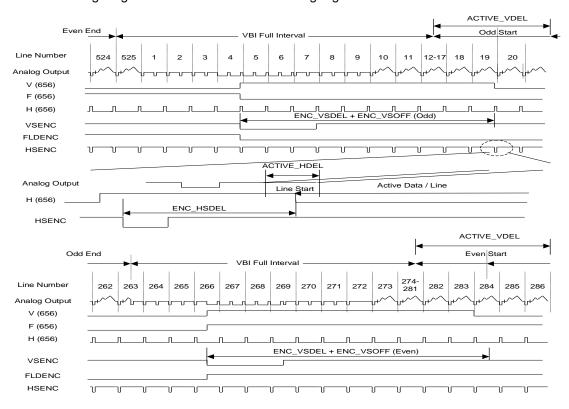


Fig 51 Horizontal and vertical timing control

# **Host Interface**

The TW2824 provides serial and parallel interfaces that can be selected by HSPB pin. When HSPB is low, the parallel interface is selected, the serial interface for high. Some of the interface pins serve a dual purpose depending on the working mode. The pins HALE and HDAT [7] in parallel mode become SCLK and SDAT pins in serial mode and the pins HDAT [6:1] and HCSB0 in parallel mode become slave address in serial mode respectively. Each interface protocol is shown in the following figures.

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Table 7 Pin assignment for serial and parallel interface

Pin Name	Serial Mode	Parallel Mode		
HSPB	HIGH	LOW		
HALE	SCLK	AEN		
HRDB	Not Used (VSSO)	RENB		
HWRB	Not Used (VSSO)	WENB		
HCSB0	Slave Address[0]	CSB0		
HCSB1	Not Used (VSSO)	CSB1		
HDAT[0]	Not Used (VSSO)	PDATA[0]		
HDAT[1]	Slave Address[1]	PDATA[1]		
HDAT[2]	Slave Address[2]	PDATA[2]		
HDAT[3]	Slave Address[3]	PDATA[3]		
HDAT[4]	Slave Address[4]	PDATA[4]		
HDAT[5]	Slave Address[5]	PDATA[5]		
HDAT[6]	Slave Address[6]	PDATA[6]		
HDAT[7]	SDAT	PDATA[7]		

# **Serial Interface**

HDAT [6:1] and HCSB0 pins define slave address in serial mode. Therefore, any slave address can be assigned for full flexibility. The Fig 52 shows an illustration of serial interface for the case of slave address (7bit) = "0x42".

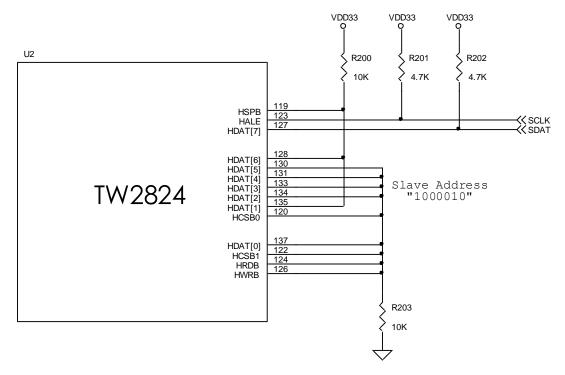


Fig 52 An illustration of serial interface for the case of slave address (7bit) = "0x42".

The TW2824 has total 3 pages for registers (1 page can contain 256 registers) so that the page index [1:0] is used for selecting page of registers. Page 0 is assigned for video decoder, Page 1 is for video controller / OSD / encoder and Page 2 is for motion detector / Box / Mouse pointer. The detailed timing diagram is illustrated in Fig 53 and Fig 54.

The TW2824 also supports automatic index increment so that it can read or write continuous multibytes without restart. Therefore, the host can read or write multiple bytes in sequential order without writing additional slave address, page index and index address. The data transfer rate on the bus is up to 400 Kbits/s.

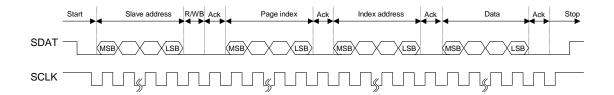
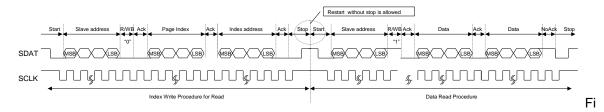


Fig 53 Write timing of serial interface



g 54 Read timing of serial interface

# **Parallel Interface**

In parallel interface, page of registers can be selected by CSB0 and CSB1 pins which are working as page index [1:0] in serial interface. Page number 0 is selected by CSB1 = "0" and CSB0 = "0", page number 1 is by CSB1 = "0" and CSB0 = "1", and page number 2 is by CSB1 = "1" and CSB0 = "0". The TW2824 also supports automatic index increment for parallel interface. The writing and reading timing is shown in Fig 55 and Fig 56 respectively. The detail timing parameters are in Table 8.

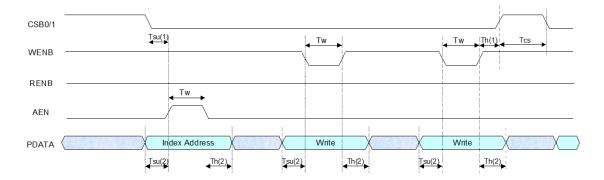


Fig 55 Write timing of parallel interface with auto index increment mode

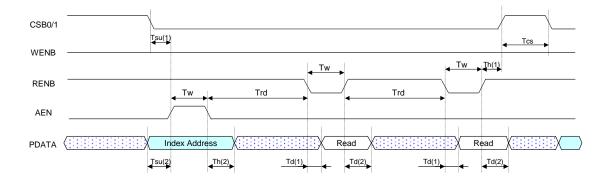


Fig 56 Read timing of parallel interface with auto index increment mode

Table 8 Timing parameters of parallel interface

Parameter	Symbol	Min	Тур	Max	Units
CSB setup until AEN active	Tsu(1)	10			ns
PDATA setup until AEN,WENB active	Tsu(2)	10			ns
AEN, WENB, RENB active pulse width	Tw	40			ns
CSB hold after WENB, RENB inactive	Th(1)	60			ns
PDATA hold after AEN,WENB inactive	Th(2)	20			ns
PDATA delay after RENB active	Td(1)			12	ns
PDATA delay after RENB inactive	Td(2)	60			ns
CSB inactive pulse width	Tcs	60			ns
RENB active delay after AEN inactive RENB active delay after RENB inactive	Trd	60			ns

## **Interrupt Interface**

The TW2824 provides the interrupt request function via an IRQ pin. Any video loss, motion or blind detection will make the IRQ pin low until cleared via the register. Writing high to the corresponding bit of the interrupt clear register IRQCLR\_NOVID, IRQCLR\_MDBD (0x38) will clear the interrupt request. The host can distinguish what event makes interrupt request to IRQ pin by reading the status of IRQCLR\_NOVID, IRQCLR\_MDBD (0x38) registers before clearing. Then, the host has to read another status of DET\_NOVID, DET\_MOTION, DET\_BLIND (0x39, 0x3A) registers to find out whether the event is generated by video loss or video detection, or whether it is made by motion or blind detection. To disable each interrupt, the interrupt status also has its own mask register such as IRQENA\_NOVID, IRQENA\_MOTION (0x37), and IRQENA\_BLIND (0x3A) register. An illustration of the interrupt sequence is shown in the following Fig 57.

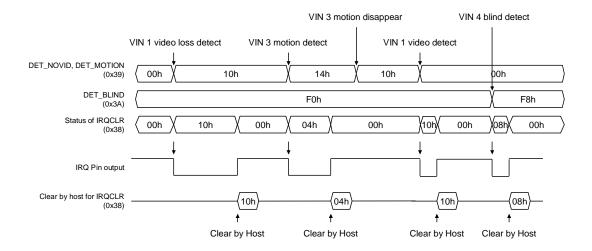


Fig 57 Timing Diagram of Interrupt Interface

The TW2824 also provides the status of video loss, motion detection or the strobe acknowledge for individual channel through MPPDEC pins with the control of the MPPSET (0x7C) register.

# **Control Register**

## **REGISTER MAP**

## For Video Decoder

	Add	ress		DITT	DITO	DITE	DIT 4	DITO	DITO	DITA	DITO		
VIN0	VIN1	VIN2	VIN3	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0		
0x00	0x40	0x80	0xC0		DET_FORMAT *		DET_COLOR *	LOCK_COLOR *	LOCK_GAIN *	LOCK_OFST *	LOCK_PLL *		
0x01	0x41	0x81	0xC1	IFMTMAN		IFORMAT	_	0	1	DET_NONSTD *	DET_FLD60 *		
0x02	0x42	0x82	0xC2	AGC	PEDEST	1	0	GNT	IME	OST	IME		
0x03	0x43	0x83	0xC3				HDELA'	Y_X [7:0]					
0x04	0x44	0x84	0xC4				HACTIV	E_X [7:0]					
0x05	0x45	0x85	0xC5				HDELA'	Y_Y [7:0]					
0x06	0x46	0x86	0xC6				HACTIV	E_Y [7:0]					
0x07	0x47	0x87	0xC7	HACTIV	E_Y [9:8]	HDELA'	Y_Y [9:8]	HACTIVI		HDELAY	′_X [9:8]		
0x08	0x48	0x88	0xC8	(	)			HSW	IDTH				
0x09	0x49	0x89	0xC9				VDELA'	Y_X [7:0]					
0x0A	0x4A	0x8A	0xCA				VACTIV	E_X [7:0]					
0x0B	0x4B	0x8B	0xCB				VDELA'	Y_Y [7:0]					
0x0C	0x4C	0x8C	0xCC		VACTIVE_Y [7:0]								
0x0D	0x4D	0x8D	0xCD	HPLLMAN		HPLLTIME		VACTVE_Y [8]	VDELAY_Y [8]	VACTVE_X [8]	VDELAY_X [8]		
0x0E	0x4E	0x8E	0xCE	FLDN	MODE	VSMODE	FLDPOL	VSPOL	1	0			
0x0F	0x4F	0x8F	0xCF				HUE						
0x10	0x50	0x90	0xD0				Si	SAT					
0x11	0x51	0x91	0xD1				CC	NT					
0x12	0x52	0x92	0xD2				BI	RT					
0x13	0x53	0x93	0xD3	IFC	OMP	CL	CLPF ACCTIME APCTIME						
0x14	0x54	0x94	0xD4	YPE/	AK_Y	YPE	AK_X	(	)	CKIL			
0x15	0x55	0x95	0xD5	VSFI			LT_X	HSFI	LT_Y	HSFI	_T_X		
0x16	0x56	0x96	0xD6	YBWI_X	COME	BMD_X			0				
0x17	0x57	0x97	0xD7	YBWI_Y	COME	BMD_Y			0				
0x18	0x58	0x98	0xD8	•			VSCALE	_X [15:8]					
0x19	0x59	0x99	0xD9				VSCALE	E_X [7:0]					
0x1A	0x5A	0x9A	0xDA					_Y [15:8]					
0x1B	0x5B	0x9B	0xDB					E_Y [7:0]					
0x1C	0x5C	0x9C	0xDC					_X [15:8]		<del></del>			
0x1D	0x5D	0x9D	0xDD				HSCALE						
0x1E	0x5E	0x9E	0xDE				HSCALE	_Y [15:8]					
0x1F	0x5F	0x9F	0xDF				HSCALE			<del></del>			
0x20	0x60	0xA0	0xE0	0	VFLT_MD_X		N_X	PAL_DLY_X	ODD_EN_X	EVEN_EN_X	1		
0x21	0x61	0xA1	0xE1	0	VFLT_MD_Y	VB\	N_Y	PAL_DLY_Y	ODD_EN_Y	EVEN_EN_Y	1		
0x22	0x62	0xA2	0xE2	BLKEN	BLKCOL 0		LMTOUT	SW_RESET	ANA_SW	(	)		
0x23	0x63	0xA3	0xE3	0	0	0	1	0	0	0	1		

Address VIN0 VIN1 VIN2 VIN3	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
0x37		IRQENA	NOVID			IRQENA_	MOTION	
0x38		IRQCLR				IRQCLR		
0x39		DET_N				DET_M		
0x3A			_BLIND			DET_E		
0x3B	1	0		0	0	0	IRQPOL	IRQRPT
0x3C					GAIN			
0x3D					GAIN			
0x3E					OFF			
0x3F				V_0	OFF			
0x78	0	0 0		0		ADC_I	PWDN	
0x79	1	0	0	0	0	0	0	0
0x7A	0	0	0	0	0	0	0	0
0x7B	TST_FLDLY4Y	TST_FLDLY4X	TST_FLDLY3Y	TST_FLDLY3X	TST_FLDLY2Y	TST_FLDLY2X	TST_FLDLY1Y	TST_FLDLY1X
0x7C	0		MPPSET1		0		MPPSET0	
0x7D	0	0	0	0	0	0	0	0
0xB8	0	0	0	0	0	0	0	0
0xF8	HAV_VALID	CKILCOMB	0	0	C_C	ORE	Y_H_	CORE
0xF9	0		CDEL		0	0	0	0
0xFA	0	0	1	1	1	1	0	0
0xFB	0	0	0	1	0	0	0	0
0xFC	1	1	1	1	0	0	0	0
0xFD	0	0	0	0	0	0	0	0
0xFE			·	0x	(08			·

Notes 1. "\*" stand for read only register

2. VINO ~ VIN3 stand for video input 0 ~ video input 3.

## For Video Controller

Add	dress	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	
X	Y	DIII	DIIO	ыю	D114	ыз	DIIZ	DIII	ыш	
1:	x00	SYS_5060	OVERLAY_X	OVERLAY_Y	LINK_LAST	LINK_EN_X	LINK_EN_Y	LINK_	NUM	
1:	x30		MCLKI	DEL_Y			MCLK	DEL_X		
1x01	1x31	0	FRAME_OP	FRAME_FLD	DIS_MODE		DIV	VD	NV	
1x02	1x32	0/1				SAVE_ADDR				
1x03	1x33	RECALL_FLD	0	SAVE_FLD	SAVE_HID			_REQ		
1x04	1x34	TBLINK		S_FLD	DUAL_PAGE			STRB_REQ		
1x05	1x35	MUX_MODE	TRIG_MODE	EXT_TRIG	INTR_REQ			INTR_CH		
1x06	1x36	QUE_PE	RIOD[9:8]				_SIZE			
1x07	1x37				QUE_PE	RIOD[7:0]				
1x08			_FLD	INT_CNT_RST   QUE_POS_RST   QUE_CH						
1x09	1x39	QUE_WR	0 QUE_ADDR							
1x0A	1x3A	NOVID	_MODE	QUE_POS *						
1x0B	1x3B	0	0	0	0		MUX_O			
1x0C	1x3C	ZMENA	0	ZMBNDCOL		ZMBNDEN	ZMAREAEN	ZMA	REA	
1x0D	1x3D					OMH				
1x0E	1x3E					OMV				
1x0F	1x3F	FRZ_	_FLD	BND	COL	BGD	COL	BLK	COL	
	x2C	0	0	0	0	0	0	0	0	
	x2D	0	0	0	0	0	0	0	0	
	x2E	0	0	0	0	0	0	0	0	
	x2F	0	0	0	0	0	0	0	0	
	x5C	0	0	0	0	1	0	0	0	
	x5D	0	0	0	0	0	0	0	0	
	x5E	0	0	0	0	0	0	0	0	
1:	x5F	MEM_INIT	ENCCLK_Y	ENCCLK_X	0	0	ENCCLKP_Y	ENCCLKP_X	0	

Notes 1. "\*" stand for read only register

2. X, Y stand for X path and Y path.

#### For Channel Size

			Add	ress											
CI	H0	CH	<del> </del> 1	CH	<del>1</del> 2	CH	<del>1</del> 3	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0
Χ	Υ	Χ	Υ	Χ	Υ	Χ	Υ								
1x10	1x40	1x17	1x47	1x1E	1x4E	1x25	1x55	CH_EN	DMCH_EN	DMCH_PATH	FUNC_	_MODE		DEC_PATH	
1x11	1x41	1x18	1x48	1x1F	1x4F	1x26	1x56	0	FREEZE	MIRROR	ENHANCE	POP_UP	BLANK	BOUND	BLINK
1x12	1x42	1x19	1x49	1x20	1x50	1x27	1x57								
1x13	1x43	1x1A	1x4A	1x21	1x51	1x28	1x58								
1x14	1x44	1x1B	1x4B	1x22	1x52	1x29	1x59				PIC	HR			
1x15	1x45	1x1C	1x4C	1x23	1x53	1x2A	1x5A				PIC	CVT			
1x16	1x46	1x1D	1x4D	1x24	1x54	1x2B	1x5B				PIC	CVB			
1x	60	1x	64	1x	68	1x(	O3				DMP	ICHL			
1x	œ1	1x	65	1x	69	1x	6D	DMPICHR							
1x	62	1x	66	1x(	6A	1x	6E			•	DMP	ICVT	•	•	
1x	63	1x	67	1x(	6B	1x	6F		DMPICVB						

Notes 1. X, Y stand for X path and Y path.

2. CH0 ~ CH3 stand for Channel 0 ~ Channel 3.

## **For Video Output**

Address	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	
1x70	ENC_	IN_X	ENC_	_IN_Y	CCIR	_IN_X	CCIR	_IN_Y	
1x71	0	DAC_	PD_X	DAC_OUT_X	0	DAC_	PD_Y	DAC_OUT_Y	
1x72	0	0 0		OUT_X	0	0	CCIR_	OUT_Y	
1x73	ENC_MODE	ENC_MODE CCIR_LMT		ENC_FLD	CCIR_FLDPOL	ENC_HSPOL	ENC_VSPOL	ENC_FLDPOL	
1x74	ENC_\	/SOFF			ENC_\	/SDEL			
1x75				ENC_I	HSDEL				
1x76			ACTIVE_HDEL			ACTIVE_VD			
1x77	ENC_	ENC_FSC		)	1 ENC_PHALT		ENC_ALTRST ENC_PED		
1x78	ENC_CBW_X		ENC_\	/BW_X	ENC_CBW_Y		N_Y ENC_Y		
1x79	ENC_BAR_X ENC_CKILL_X		ENC_BAR_Y ENC_CKILL_Y		ENC_VS_READ *		ENC_FLD_READ *		

Notes 1. "\*" stand for read only register

## For Character Overlay

Address	BIT7	BIT6	BIT5	BIT4	ВІТ3	BIT2	BIT1	BIT0			
1x7A				FONT_WR_							
1x7B				FONT_WR_							
1x7C				FONT_WR	_DATA[11:4]						
1x7D		FONT_WR	_DATA[3:0]			(	0				
1x7E	0				FONT_WR_INDEX						
1x7F	FONT_REQ_X	FONT_REQ_Y	FONT_WR_PAGE	FONT_WR_FLD			VR_LINE				
1x80	0	FONT_RD_PAGE_X	FONT_R		0	FONT_RD_PAGE_Y		D_FLD_Y			
1x81	0	0	RAMCLR_Y	RAMCLR_X	CLASSEN0_Y	CLASSEN0_X	PHIGH	PLOW			
1x82	CHAR_	VSIZE_Y		HSIZE_Y	CHAR_	VSIZE_X		HSIZE_X			
1x83		CHAR_\				CHAR_H					
1x84		CHAR_\				CHAR_I					
1x85		CHAR_\				CHAR_I					
1x86		CHAR_\				CHAR_I					
1x87		CHAR_				CHAR_					
1x88		CHAR_				CHAR_					
1x89		CLASS3				CLASS3					
1x8A		CLASS3				CLASS3					
1x8B		CLASS3				CLASS3					
1x8C		CLASS3				CLASS3					
1x8D 1x8E		CLASS2 CLASS1				CLASS2					
1x8E 1x8F		CLASS			CLASS1COL_B CLASS0COL B						
1x90		CLASSI	JCOL_C	CLLI	I T0 Y	CLASSI	UCUL_B				
1x90 1x91					TO_T						
1x92					CLUTO CR						
1x93					CLUT0_CR CLUT1 Y						
1x94					1 CB						
1x95					1_CR						
1x96					T2 Y						
1x97					2 CB						
1x98					2_0B 2 CR						
1x99					CLUT3 Y						
1x9A					CLUT3_CB						
1x9B					3 CR						
1x9C	CHAR PATH	0	0	020.		CHAR VLOC					
1x9D	0	0			CHAR	_HLOC					
	0 CHAR_ATTR [11:8]										
1x9E				CHAR_A	TTR [7:0]	_					

### **For Mouse Pointer**

Address	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	ВІТ0					
2x00	CUR_ON_X	CUR_ON_Y	CUR_TYPE	CUR_SUB	CUR_BLINK	0	CUR_HP [0]	CUR_VP [0]					
2x01		CUR_HP [8:1]											
2x02	CUR_VP [8:1]												

## For Single Box

			Add	ress				ВІТ7	BIT6	ВІТ5	BIT4	ВІТ3	BIT2	BIT1	ВІТ0	
			2>	<b>c</b> 03				BOX_TYPE	BOX_EMP	0	0		BOX_F	PLNEN		
			2>	<b>&lt;</b> 04							BOX_B	NDCOL				
			2)	<b>&lt;</b> 05					BOX_PI	LNCOL3			BOX_P	LNCOL2		
			2)	к06					BOX_PI	LNCOL1			BOX_P	LNCOL0		
			Add	ress				DITZ	DITE	DITE	DIT4	BIT3	DITO	DITA	DITO	
B0	B1	B2	В3	B4	B5	B6	B7	BIT7	BIT6	BIT5	BIT4	ыз	BIT2	BIT1	BIT0	
2x07	2x0C	2x11	2x16	2x1B	2x20	2x25	2x2A	BOX_PATH	BOX_OBND	BOX_IBND	BOX_PLNMIX	IX BOX_PLNSEL BOX_HL[0] BOX_VT[0]				
2x08	2x0D	2x12	2x17	2x1C	2x21	2x26	2x2B				BOX_I	_HL[8:1]				
2x09	2x0E	2x13	2x18	2x1D	2x22	2x27	2x2C				BOX	BOX_HW				
2x0A	2x0F	2x14	2x19	2x1E	2x23	2x28	2x2D				BOX_\	VT[8:1]				
2x0B	2x10	2x15	2x1A	2x1F	2x24	2x29	2x2E				BOX	_VW				
			Add	ress				DITT	DITO	DITE	DITA	DITO	DITO	DITA	DITO	
B8	B9	B10	B11	B12	B13	B14	B15	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	
2x2F	2x34	2x39	2x3E	2x43	2x48	2x4D	2x52	BOX_PATH	BOX_OBND	BOX_IBND	BOX_PLNMIX	BOX_P	LNSEL	BOX_HL[0]	BOX_VT[0]	
2x30	2x35	2x3A	2x3F	2x44	2x49	2x4E	2x53				BOX_I	HL[8:1]				
2x31	2x36	2x3B	2x40	2x45	2x4A	2x4F	2x54				BOX	_HW	•			
2x32	2x37	2x3C	2x41	2x46	2x4B	2x50	2x55				BOX_\	/T[8:1]				
2x33							2x56				BOX	_VW				

Notes 1. B0 ~ B15 stand for single box 0 to 15.

## For 2D Arrayed Box

	Add	ress		DITZ	DITC	DITE	DIT4	DITO	DITO	DITA	DITO	
2DB0	2DB1	2DB2	2DB3	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	
	2x	60		0	0	2DBOX_	BNDCOL		2DBOX_	PLNCOL		
2x61	2x68	2x6F	2x76	2DBOX_VT[0]	2DBOX_HL[0]	2DBOX_MODE	2DBOX_PATH	2DBOX_MIX	2DBOX_PLNEN	2DBOX_CUREN	2DBOX_BNDEN	
2x62	2x69	2x70	2x77		2DBOX_VT[8:1]							
2x63	2x6A	2x71	2x78				2DBOX	_HL[8:1]				
2x64	2x6B	2x72	2x79				2DBO	X_VW				
2x65	2x6C	2x73	2x7A		2DBOX_HW							
2x66	2x6D	2x74	2x7B	2DBOX_VNUM 2DBOX_HNUM								
2x67	2x6E	2x75	2x7C	2DBOX_CUR_HP 2DBOX_CUR_VP								

Notes  $1.2DB0 \sim 2DB3$  stand for 2D arrayed box 0 to 3.

## **For Motion Detector**

Address									DITO	BIT1	BIT0		
VIN0	VIN1	VIN2	VIN3	DII <i>I</i>	DIIO	БПЭ	DI14	ыз	DIIZ	DIII	БПО		
	2x	7E			MB_	DIS				0			
	2x	7F		0	0	BD_CE	LSENS		BD_L\	/SENS			
2x80	2xA0	2xC0	2xE0	MASK_MODE	0	MD_	FLD		MD_/	ALIGN			
2x81	2xA1	2xC1	2xE1	MD_CE	LSENS	0			MD_LVSENS				
2x82	2xA2	2xC2	2xE2	MD_REFFLD	0			MD_S	PEED				
2x83	2xA3	2xC3	2xE3		MD_TM	IPSENS			MD_S	PSENS			
2x84	2xA4	2xC4	2xE4										
2x86	2xA6	2xC6	2xE6										
2x88	2xA8	2xC8	2xE8										
2x8A	2xAA	2xCA	2xEA										
2x8C	2xAC	2xCC	2xEC										
2x8E	2xAE	2xCE	2xEE		MD_MASK[15:8]								
2x90	2xB0	2xD0	2xF0		MD_MASK[15:8]								
2x92	2xB2	2xD2	2xF2										
2x94	2xB4	2xD4	2xF4										
2x96	2xB6	2xD6	2xF6										
2x98	2xB8	2xD8	2xF8										
2x9A	2xBA	2xDA	2xFA										
2x85	2xA5	2xC5	2xE5										
2x87	2xA7	2xC7	2xE7										
2x89	2xA9	2xC9	2xE9										
2x8B	2xAB	2xCB	2xEB										
2x8D	2xAD	2xCD	2xED										
2x8F	2xAF	2xCF	2xEF				MD_MA	SK[7:0]					
2x91	2xB1	2xD1	2xF1				IVID_IVIA	O(\(\(\tau\))					
2x93	2xB3	2xD3	2xF3										
2x95	2xB5	2xD5	2xF5										
2x97	2xB7	2xD7	2xF7										
2x99	2xB9	2xD9	2xF9										
2x9B	2xBB	2xDB	2xFB										

Notes 1. VIN0 ~ VIN3 stand for video input 0 ~ video input 3.

## **RECOMMENDED VALUE**

For Video Decoder

	Add	ress			NT	SC			P	<b>AL</b>	
VIN0	VIN1	VIN2	VIN3	1 CH	4 CH	9 CH	16 CH	1 CH	4 CH	9 CH	16 CH
0x00	0x40	0x80	0xC0	8'h00				8'h00			
0x01	0x41	0x81	0xC1	C4				84			
0x02	0x42	0x82	0xC2	E5				A5			
0x03	0x43	0x83	0xC3	20				20			
0x04	0x44	0x84	0xC4	D0				D0			
0x05	0x45	0x85	0xC5	20				20			
0x06	0x46	0x86	0xC6	D0				D0			
0x07	0x47	0x87	0xC7	88				88			
0x08	0x48	0x87	0xC8	20				20			
0x09	0x49	0x89	0xC9	06				05			
0x0A	0x4A	0x8A	0xCA	F0				20			
0x0B	0x4A 0x4B	0x8B	0xCB	06				05			
0x0C	0x4C	0x8C	0xCC	F0				20			
0x0D	0x4C 0x4D	0x8D	0xCD	40				4A			
0x0E											
	0x4E	0x8E	0xCE	D2				D2			
0x0F	0x4F	0x8F	0xCF	80				80			
0x10	0x50	0x90	0xD0 0xD1	80				80			
0x11	0x51	0x91		80				80			
0x12	0x52	0x92	0xD2	80				80			
0x13	0x53	0x93	0xD3	2F	40			2F	40	00	00
0x14	0x54	0x94	0xD4	00	10			00	10	00	00
0x15	0x55	0x95	0xD5	00	21	22	33	00	20	22	33
0x16	0x56	0x96	0xD6	00				40	C0		
0x17	0x57	0x97	0xD7	00				40			
0x18	0x58	0x98	0xD8	FF	7F	55	3F	FF	7F	55	3F
0x19	0x59	0x99	0xD9	FF				FF			
0x1A	0x5A	0x9A	0xDA	FF				FF			
0x1B	0x5B	0x9B	0xDB	FF				FF			
0x1C	0x5C	0x9C	0xDC	FF	7F	55	3F	FF	7F	55	3F
0x1D	0x5D	0x9D	0xDD	FF				FF			
0x1E	0x5E	0x9E	0xDE	FF				FF			
0x1F	0x5F	0x9F	0xDF	FF				FF			
0x20	0x60	0xA0	0xE0	07	07	67	67	0F	07	67	67
0x21	0x61	0xA1	0xE1	07				0F			
0x22	0x62	0xA2	0xE2	00	00			00			
0x23	0x63	0xA3	0xE3	11	11			11			
	0x			00				00			
	0x39			00 FF				00			
	0x3A							FF			
	0x3B							82			
	0x3C							80			
	0x3D							80			
	0x3E							82			
	0x3F							82			
	0x78							00			
	0x	79		80				80			
	0x <sup>-</sup>	7A		00				00			

	Address			NT	SC			P	<b>AL</b>	
VINO VIN	I1 VIN2	VIN3	1 CH	4 CH	9 CH	16 CH	1 CH	4 CH	9 CH	16 CH
	0x7B		00				00			
	0x7C		00				00			
	0x7D		00				00			
	0xB8		00				00			
	0xF8		0A				0A			
	0xF9		42				42			
	0xFA		3C				3C			
	0xFB		10				10			
	0xFC	•	F0				F0			
	0xFD	•	00				00			

## For Video Controller

Add	Iress		NT	SC		PAL				
Х	Υ	1 CH	4 CH	9 CH	16 CH	1 CH	4 CH	9 CH	16 CH	
1)	(00	8'h00				8'h80				
1)	(30	AA				AA				
1x01	1x31	00				00				
1x02	1x32	00/80				00/80				
1x03	1x33	00				00				
1x04	1x34	00				00				
1x05	1x35	00				00				
1x06	1x36	00				00				
1x07	1x37	00				00				
1x08	1x38	00				00				
1x09	1x39	00				00				
1x0A	1x3A	00				00				
1x0B	1x3B	00				00				
1x0C	1x3C	20				20				
1x0D	1x3D	00				00				
1x0E	1x3E	00				00				
1x0F	1x3F	B7				B7				
1x10	1x40	80				80				
1x11	1x41	02				02				
1x12	1x42	00				00				
1x13	1x43	00	00	00	00	00	00	00	00	
1x14	1x44	B4	5A	3C	2D	B4	5A	3C	2D	
1x15	1x45	00	00	00	00	00	00	00	00	
1x16	1x46	78	3C	28	1E	90	48	30	24	
1x17	1x47	90				90				
1x18	1x48	02				02				
1x19	1x49	00				00				
1x1A	1x4A	00	5A	3C	2D	00	5A	3C	2D	
1x1B	1x4B	B4	B4	78	5A	B4	B4	78	5A	
1x1C	1x4C	00	00	00	00	00	00	00	00	
1x1D	1x4D	78	3C	28	1E	90	48	30	24	
1x1E	1x4E	A0				A0				
1x1F	1x4F	02				02				
1x10	1x50	00				00				
1x11	1x51	00	00	78	5A	00	00	78	5A	

Add	ress		NT	SC			P	AL	
Х	Y	1 CH	4 CH	9 CH	16 CH	1 CH	4 CH	9 CH	16 CH
1x12	1x52	B4	5A	B4	87	B4	5A	B4	87
1x13	1x53	00	3C	00	00	00	48	00	00
1x14	1x54	78	78	28	1E	90	90	30	24
1x15	1x55	A0				A0			
1x16	1x56	02				02			
1x17	1x57	00				00			
1x28	1x58	00	5A	00	87	00	5A	00	87
1x29	1x59	B4	B4	3C	B4	B4	B4	3C	B4
1x2A	1x5A	00	3C	28	00	00	48	30	00
1x2B	1x5B	78	78	50	1E	90	90	60	24
1x	1x2C					00			
1x	1x2D					00			
1x	2E	00				00			
1x	2F	00				00			
1x	5C	08				80			
1x	5D	00				00			
1x	5E	00				00			
1x	:5F	06				06			
1x	70	77				77			
1x	71	00				00			
1x	1x72					01			
1x	1x73					80			
1x	1x74					16			
1x	1x75					41			
1x	1x76					7C			
1x	:77	09				4C			
1x	78	AA				AA			

Notes 1. Blanks have the same value of 1 CH.

2. All values are Hex format.

## For Motion Detector

	Add	ress		NTSC	PAL
VIN0	VIN1	VIN2	VIN3	NISC	PAL
	2x	7E	-	8'h00	8'h00
	2x	7F		17	17
2x80	2xA0	2xC0	2xE0	07	07
2x81	2xA1	2xC1	2xE1	4A	4A
2x82	2xA2	2xC2	2xE2	07	07
2x83	2xA3	2xC3	2xE3	24	24

#### **REGISTER DESCRIPTION**

	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Ī	0	0x00								
Ī	1	0x40	6	ET EODMAT	- *	DET_	LOCK_	LOCK_	LOCK_	LOCK_
Ī	2	0x80	D	ET_FORMAT		COLOR *	COLOR *	GAIN *	OFST *	PLL *
Ī	3	0xC0								

Notes "\*" stand for read only register

DET\_FORMAT Status of video standard detection for analog input.

> 0 PAL-B/D

1 PAL-M

2 PAL-N

3 PAL-60

NTSC-M

NTSC-4.43

6 NTSC-N

DET\_COLOR Status of color detection for analog input.

> 0 Color is not detected

Color is detected

LOCK\_COLOR Status of locking for color demodulation loop.

> 0 Color demodulation loop is not locked

Color demodulation loop is locked

LOCK\_GAIN Status of locking for AGC loop.

AGC loop is not locked

AGC loop is locked

LOCK\_OFST Status of locking for clamping loop.

> 0 Claming loop is not locked

1 Claming loop is locked

LOCK\_PLL Status of locking for horizontal PLL.

Horizontal PLL is not locked

Horizontal PLL is locked

	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	0x01								
	1	0x41	IFMTMAN		IFORMAT		0	4	DET_	DET_
	2	0x81	IFIVITIVIAIN		IFORIVIAT		U	ı	NONSTD *	FLD60 *
Γ	3	0xC1								

Notes "\*" stand for read only register

#### **IFMTMAN** Setting video standard manually with IFORMAT.

- Detecting video standard of video input automatically (default)
- Video standard is selected with IFORMAT

#### **IFORMAT**

Force to operate in a particular video standard when IFMTMAN = "1" or to free-run in a particular video standard on no-video status when IFMTMAN = "0".

- PAL-B/D (default)
- 1 PAL-M
- 2 PAL-N
- 3 PAL-60
- 4 NTSC-M
- 5 NTSC-4.43
- NTSC-N

### DET\_NONSTD

Status of non-standard video detection.

- The incoming video source is standard
- 1 The incoming video source is non-standard

#### DET\_FLD60

Status of field frequency of incoming video.

- 50Hz field frequency
- 1 60Hz field frequency

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x02								
1	0x42	AGC	PEDEST	4	0	CNIT	IME	007	IME
2	0x82	AGC	PEDESI	ı	U	GIVI	IIVIE	031	IIVIE
3	0xC2								

AGC Control the AGC function for active video.

Disable the AGC (default)

Enable the AGC

**PEDEST** Control pedestal level by 7.5 IRE.

No pedestal level (0 IRE is ITU-R BT.601 code 16) (default)

7.5 IRE setup level (7.5 IRE is ITU-R BT.601 code 16)

**GNTIME** Control the time constant of gain tracking loop.

Slower

1 Slow (default)

2 Fast

3 Faster

**OSTIME** Control the time constant of offset tracking loop.

Slower

Slow (default)

2 Fast

3 Faster

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]		
	0	0x07								='		
	1	0x47							UDEL	AY[9:8]		
	2	0x87							HUEL	A1[9.0]		
X	3	0xC7										
	0	0x03										
	1	0x43				HDELA	∆V[7·∩]					
	2	0x83				HULL	11[7.0]					
	3	0xC3										
	0	0x07										
	1	0x47			HDELA	∆√[ <u>0</u> -8]						
	2	0x87			TIDEL	11[3.0]						
Y	3	0xC7										
'	0	0x05										
	1	0x45				HDELA	∆V[7·∩]					
	2	0x85				IIDEL	11[1.0]					
	3	0xC5										

## **HDELAY**

This 10 bit register defines the starting location of horizontal active pixel with 1 pixel unit. The default value is decimal 32.

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]				
	0	0x07												
	1	0x47					HACITI	VE[9:8]						
	2	0x87					HACH	V L[9.0]						
X	3	0xC7												
	0	0x04												
	1	0x44				HACTI	\/E[7·0]							
	2	0x84		HACTIVE[7:0]										
	3	0xC4												
	0	0x07												
	1	0x47	HACTI	VEI0-81										
	2	0x87	HACH	v <u>L[</u> 3.0]										
Y	3	0xC7												
'	0	0x06												
	1	0x46		HACTIVE[7:0]										
	2	0x86				HACH	v ∟[ <i>1</i> .0]							
	3	0xC6												

HACTIVE

This 10 bit register defines the number of horizontal active pixel with 1 pixel unit. The default value is decimal 720.

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	80x0								
1	0x48	0	0			LICIA	UDTI I		
2	0x88	U	U			почи	IDTH		
3	0xC8								

### **HSWIDTH**

This 6 bit register defines the width of horizontal sync output with 1 pixel unit. The default value is decimal 32.

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]				
	0	0x0D												
	1	0x4D								VDELAY[8]				
	2	0x8D								VDLLAT[0]				
X	3	0xCD												
	0	0x09												
	1	0x49				VDEL	AY[7:0]							
	2	0x89				VDLL	11[7.0]							
	3	0xC9												
	0	0x0D												
	1	0x4D						VDELAY[8]						
	2	0x8D						VDLLATIO						
Y	3	0xCD												
'	0	0x0B												
	1	0x4B				VDELA	AY[7:0]							
	2	0x8B				VDLL	11[1.0]							
	3	0xCB												

### **VDELAY**

This 9 bit register defines the starting location of vertical active with 1 line unit. The default value is decimal 6.

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]			
	0	0x0D											
	1	0x4D							VACTIVE[8]				
	2	0x8D							VACTIVE[0]				
X	3	0xCD											
	0	0x0A											
	1	0x4A				\/ACTI	\/E[7:0]						
	2	A8x0		VACTIVE[7:0]									
	3	0xCA											
	0	0x0D											
	1	0x4D					VACTIVE[8]						
	2	0x8D					VACTIVE[0]						
Y	3	0xCD											
'	0	0x0C											
	1	0x4C		VACTIVE[7:0]									
	2	0x8C				VACTI	v ∟[ <i>1</i> .∪]						
	3	0xCC											

**VACTIVE** 

This 9 bit register defines the number of vertical active lines with 1 line unit. The default value is decimal 240.

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x0D								
1	0x4D	HPLLMAN		HPLLTIME					
2	0x8D	HELLIVIAIN		HELLIIME					
3	0xCD								

**HPLLMAN** 

Setting horizontal PLL time constant with HPLLTIME.

- 0 Automatic horizontal tracking mode (default)
- 1 Horizontal PLL time constant is fixed with HPLLTIME

**HPLLTIME** 

Control the time constant of horizontal PLL when HPLLMAN = "1".

- 0 Slow
- : :
- 4 Typical (default)
- :
- 7 Fast

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x0E								
1	0x4E	רו הא	EL DMODE		FLDPOL	HSPOL	VSPOL	4	0
2	0x8E	FLDI	FLDMODE		FLDPOL	HSPUL	VSPOL	ı	U
3	0xCE								

**FLDMODE** Select the field flag generation mode.

- Field flag is detected from incoming video (default)
- 1 Field flag is generated from small accumulator of detected field
- 2 Field flag is generated from medium accumulator of detected field
- 3 Field flag is generated from large accumulator of detected field

**VSMODE** Control the VS and field flag timing.

VS and field flag is aligned with vertical sync (default)

VS and field flag is aligned with HS

**FLDPOL** Select the FLD polarity.

Odd field is high (default)

Even field is high

**HSPOL** Select the HS polarity.

Low for sync duration (default)

High for sync duration

**VSPOL** Select the VS polarity.

Low for sync duration (default)

High for sync duration

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x0F								
1	0x4F				HU	IC			
2	0x8F				п	JE			
3	0xCF								

HUE

Control the hue information. The resolution is 1.4° / step.

0 -180°

:

128 0° (default)

255 180°

'	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	0x10								
	1	0x50				C.	\ <del>T</del>			
	2	0x90				SA	41			
	3	0xD0								

SAT

Control the color saturation. The resolution is 0.8% / step.

0 0%

128 100% (default)

200% 255

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x11								
1	0x51				00	NT			
2	0x91				CO	INI			
3	0xD1								

CONT Control the contrast. The resolution is 0.8% / step.

> 0 0%

128 100% (default)

255 200%

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x12								
1	0x52				BF	)T			
2	0x92				Dr	<b>(1</b>			
3	0xD2								

Control the brightness. The resolution is 0.2IRE / step. **BRT** 

> 0 -25IRE

128 OIRE (default)

255 25IRE

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x13								
1	0x53	IFC	IFCOMP		CLPF		ACCTIME		TIME
2	0x93	IFC	IFCOMP		PF	ACC	I IIVIE	APC	TIME
3	0xD3								

**IFCOMP** 

Select the IF-compensation filter mode.

No compensation (default)

1 +1 dB/ MHz 2 +2 dB/ MHz

3 +3 dB/ MHz

**CLPF** 

Select the Color LPF mode.

550KHz bandwidth

1 750KHz bandwidth (default)

950KHz bandwidth 3 1.1MHz bandwidth

**ACCTIME** 

Control the time constant of auto color control loop.

Slower 0

1 Slow

2 Fast

3 Faster (default)

**APCTIME** 

Control the time constant of auto phase control loop.

0 Slower

Slow 1

2 Fast

3 Faster (default)

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x14								
1	0x54	VDE	AL V	VDE	AL V	0	0	CI	ZII
2	0x94	1PE	YPEAK_Y		YPEAK_X		0	CKIL	
3	0xD4								

**YPEAK** 

Control the luminance peaking for X and Y path.

- No peaking (default)
- 1 31.25%
- 2 62.5%
- 3 93.75%

**CKIL** 

Control the color killing mode.

- Auto detection mode (default)
- 1 Auto detection mode
- Color is always alive
- 3 Color is always killed

	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Ī	0	0x15								
Ī	1	0x55	VCE	TV	VCE	TV	LICE	IT V	LICE	T V
ſ	2	0x95	VSFI	VSFLT_Y		LT_X	HSF	LI_ĭ	ПЭГ	_T_X
Ī	3	0xD5								

**VSFLT** 

Select the vertical anti-aliasing filter mode for X and Y path.

- Full bandwidth (default)
- Full bandwidth 1
- 2 0.25 Line-rate bandwidth
- 3 0.18 Line-rate bandwidth

**HSFLT** 

Select the horizontal anti-aliasing filter mode for X and Y path.

- Full bandwidth (default)
- 1 2 MHz bandwidth
- 1.5 MHz bandwidth
- 3 1 MHz bandwidth

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	0x16								
X	1	0x56								
_ ^	2	0x96								
	3	0xD6	YBWI	COM	IBMD	0	0	0	0	0
	0	0x17	I DVVI	COIV	DIVID	U	U	U	U	U
	1	0x57								
'	2	0x97								
	3	0xD7								

**YBWI** 

Select the luminance trap filter mode.

- 0 Narrow bandwidth trap filter mode (default)
- Wide bandwidth trap filter mode 1

COMBMD

Select the adaptive comb filter mode.

- 0,1 Adaptive comb filter mode (default)
- 2 Force trap filter mode
- 3 Not supported

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]			
	0	0x18											
	1	0x58				VSCAL	E[4E.0]						
	2	0x98				VOCAL	.E[13.6]						
X	3	0xD8											
	0	0x19											
	1	0x59				VSCVI	E[7:0]						
	2	0x99		VSCALE[7:0]									
	3	0xD9											
	0	0x1A											
	1	0x5A				VSCAL	E[15·8]						
	2	0x9A				VOCAL	.L[13.0]						
Y	3	0xDA											
'	0	0x1B											
	1	0x5B				VSCAI	E[7:0]						
	2	0x9B				VSCAI	LL[1.0]						
	3	0xDB											

**VSCALE** 

The 16 bit register defines a vertical scaling ratio. The actual vertical scaling ratio is  $VSCALE/(2^16 - 1)$ . The default value is 0xFFFF.

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]			
	0	0x1C											
	1	0x5C				ПССИ	.E[15:8]						
	2	0x9C				HOCAL	.E[15.6]						
X	3	0xDC											
	0	0x1D											
	1	0x5D				ПССИ	E[7·0]						
	2	0x9D		HSCALE[7:0]									
	3	0xDD											
	0	0x1E											
	1	0x5E				HCCVI	.E[15:8]						
	2	0x9E				HOUAL	.E[13.6]						
Y	3	0xDE											
'	0	0x1F											
	1	0x5F				HSCAI	E[7:0]						
	2	0x9F				ПЭСАІ	_L[1.U]						
	3	0xDF											

**HSCALE** 

The 16 bit register defines a horizontal scaling ratio. The actual horizontal scaling ratio is  $HSCALE/(2^16 - 1)$ . The default value is 0xFFFF.

Path	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	0x20								
X	1	0x60								
_ ^	2	0xA0								
	3	0xE0	0	VFLT_MD	\/E	3W	PAL_DLY	ODD_EN	EVEN_EN	1
	0	0x21	U	VELI_IVID	VL	) V V	FAL_DLI	ODD_LIN	LVLIN_LIN	'
	1	0x61								
'	2	0xA1								
	3	0xE1								

VFLT\_MD

Select the additional vertical scaling filter mode.

- 0 Vertical poly-phase mode (default)
- 1 Additional vertical bandwidth reduction mode with VBW bits

**VBW** 

Control the vertical bandwidth when VSFLT\_MD = "1".

- Not Supported (default)
- 1 Not Supported
- Wide
- 3 Narrow

PAL\_DLY

Select the PAL delay line mode.

- 0 Vertical scaling mode is selected in chrominance path (default)
- PAL delay line mode is selected in chrominance path

ODD\_EN

Control valid signal in ODD field.

- 0 Valid signal is always disabled in ODD field
- Normal operation (default)

EVEN\_EN

Control valid signal in EVEN field.

- Valid signal is always disabled in EVEN field
- Normal operation (default)

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x22								
1	0x62	BLKEN	BLKCOL	0	LMTOUT	SW_	ANA SW	,	,
2	0xA2	DLNEN	BLRCOL	0	LIVITOOT	RESET	AINA_SW	(	,
3	0xE2								

BLKEN Control the blank output.

0 Blank color is disabled (default)

1 Blank color is enabled

BLKCOL Select the blank color when BLKEN = "1".

0 Blue color (default)

1 Black color

LMTOUT Control the range of output level.

0 Output ranges are limited to 2 ~ 254 (default)

1 Output ranges are limited to 16 ~ 239

SW\_RESET Reset the system by software except control registers.

This bit is cleared by itself in a few clocks after enabled

0 Normal operation (default)

1 Enable soft reset

ANA\_SW Select analog video input using switch.

0 VIN\_A channel is selected (default)

1 VIN\_B channel is selected

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	0x23								
1	0x63	0	0	_	4	0	0	0	4
2	0xA3	U	0	0	'	U	U		'
3	0xE3								

This is reserved register.

For normal operation, the above value should be set in this register.

	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Г	0x37		IRQENA	_NOVID			IRQENA_	MOTION	

IRQENA\_NOVID

Interrupt enable for corresponding video-loss detection.

IRQENA\_NOVID[3:0] stand for VIN3 to VIN0.

0 Interrupt is disabled (default)

Interrupt is enabled

IRQENA\_MOTION

Interrupt enable for corresponding motion detection.

IRQENA\_MOTION [3:0] stand for VIN3 to VIN0.

0 Interrupt is disabled (default)

1 Interrupt is enabled

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x38		IRQCLR	_NOVID			IRQCLR	_MDBD	

IRQCLR\_NOVID

Setting "1" to clear interrupt request for corresponding video-loss detection.

This bit is cleared by itself in a few clocks after setting "1".

IRQCLR\_NOVID [3:0] stand for VIN3 to VIN0.

IRQCLR\_MDBD

Setting "1" to clear interrupt request for corresponding motion and blind

detection. This bit is cleared by itself in a few clocks after setting "1".

IRQENA\_MD\_BD [3:0] stand for VIN3 to VIN0.

Ind	ex	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x3	9		DET_N	IOVID *			DET_M	OTION *	

Notes "\*" stand for read only register

DET\_NOVID Status of video loss detection.

DET\_NOVID[3:0] stand for VIN3 to VIN0.

0 Video is alive

Video loss is detected

**DET\_MOTION** Status of motion detection.

DET\_MOTION[3:0] stand for VIN3 to VIN0.

No motion

Motion is detected

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x3A		IRQENA	_BLIND			DET_E	SLIND *	

Notes "\*" stand for read only register

IRQENA\_BLIND Interrupt enable for corresponding blind detection.

IRQENA\_BLIND[3:0] stand for VIN3 to VIN0.

0 Interrupt is disabled (default)

Interrupt is enabled

**DET\_BLIND** Status of blind detection.

DET\_BLIND[3:0] stand for VIN3 to VIN0.

No blinded video

Blind video is detected

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x3B	1	0	0	0	0	0	IRQPOL	IRQRPT

IRQPOL Select the IRQ polarity.

0 Active high (default)

1 Active low

IRQRPT Select the IRQ mode.

IRQ pin maintains the state "1" until the interrupt request is cleared (default) Interrupt request is repeated with 5msec period via IRQ pin when interrupt is not cleared in long time.

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x3C				U_G	SAIN			

U\_GAIN Adjust gain for U (Cb) component of VIN0 ~ VIN3.

The resolution is 0.8% / step.

0 0%

: :

128 100% (default)

: :

255 200%

	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Ī	0x3D				V_G	SAIN			

V\_GAIN Adjust gain for V (Cr) component of VIN0 ~ VIN3.

The resolution is 0.8% / step.

0 0%

: :

128 100% (default)

.

255 200%

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x3E				U_(	OFF			

U\_OFF

U (Cb) offset adjustment register of VIN0 ~ VIN3.

The resolution is 0.4% / step.

0 -50%

128 0% (default)

255 50%

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x3F				V_0	OFF			

V\_OFF

V (Cr) offset adjustment register of VIN0 ~ VIN3.

The resolution is 0.4% / step.

0 -50%

128 0% (default)

255 50%

Inde	ex	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x7	8	0	0	0	0		ADC_	PWDN	

ADC\_PWDN

Power down the ADC of video input.

ADC\_PWDN [3:0] stand for VIN3 to VIN0.

- 0 Normal (default)
- 1 Power down

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x79	1	0	0	0	0	0	0	0
0x7A	0	0	0	0	0	0	0	0

This is reserved register.

For normal operation, the above value should be set in this register.

	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Γ	0x7B	FLDOS_							
	UX/D	4Y	4X	3Y	3X	2Y	2X	1Y	1X

**FLDOS** 

Remove the field offset between ODD and EVEN.

The numbers stand for VIN3 to VIN0 and X and Y stand for X and Y path.

- 0 Normal operation (default)
- 1 Remove the field offset between ODD and EVEN field

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x7C	0		MPPSET1		0		MPPSET0	

MPPSET1 MPPSET0 Output Selection for MPPDEC0[1] ~ MPPDEC3[1] pins.

Output Selection for MPPDEC0[0] ~ MPPDEC3[0] pins.

For the following 0~5 value, MPPDEC0 ~ MPPDEC3 data comes from VIN0 ~ VIN3 and comes from CH0 ~ CH3 for 6~7 value.

- 0 Vertical sync (default)
- 1 Field flag
- 2 Horizontal sync
- Vertical valid line
- Video loss
- 5 Motion detection
- 6 Strobe acknowledge of X path
- 7 Strobe acknowledge of Y path

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0x7D	0	0	0	0	0	0	0	0

This is reserved register.

For normal operation, the above value should be set in this register.

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0xB8	0	0	0	0	0	0	0	0

This is reserved register.

For normal operation, the above value should be set in this register.

	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
ſ	0xF8	HAV_VALID	CKILCOMB	0	0	C_CORE		Y_H_0	CORE

HAV\_VALID Select VALID output mode.

Valid data indicator only for active data (default)

Valid data indicator for both active data and ITU-R 656 timing codes

CKILCOMB Control the comb filter on/off whether color is or not.

Comb filter is always enabled (default)

1 Comb filter is disabled when color is killed

C\_CORE Coring to reduce the noise in the chrominance.

> 0 No coring

1 Coring value is within 128 +/- 1 range

2 Coring value is within 128 +/- 2 range (default)

3 Coring value is within 128 +/- 4 range

Y\_H\_CORE Coring to reduce the high frequency noise in the luminance.

No coring

1 Coring value is within +/- 1 range

2 Coring value is within +/- 2 range (default)

3 Coring value is within +/- 4 range

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0xF9	0		CDEL			0	0	0

**CDEL** 

Adjust the group delay of chrominance relative to luminance.

-2.0 pixel

1 -1.5 pixel

2 -1.0 pixel

3 -0.5 pixel

0.0 pixel (default)

5 0.5 pixel

6 1.0 pixel

1.5 pixel

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0xFA	0	0	1	1	1	1	0	0
0xFB	0	0	0	1	0	0	0	0
0xFC	1	1	1	1	0	0	0	0
0xFD	0	0	0	0	0	0	0	0

This is reserved register.

For normal operation, the above value should be set in this register.

Inde	X	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0xFI	Е			DEV_ID *				REV_ID *	

Notes "\*" stand for read only register

DEV\_ID The TW2824 product ID code is 00001.

REV\_ID The revision number

	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
ſ	1x00	SYS_5060	OVERLAY_X	OVERLAY_Y	LINK_LAST	LINK_EN_X	LINK_EN_Y	LINK_	NUM

SYS\_5060 Standard format selection for video controller.

0 60Hz, 525 line format (default)

1 50Hz, 625 line format

OVERLAY\_X Control overlay Y path on X path.

0 Disable overlay Y path on X path (default)

1 Enable overlay Y path on X path

OVERLAY\_Y Control overlay X path on Y path.

0 Disable overlay X path on Y path (default)

1 Enable overlay X path on Y path

LINK\_LAST Define last chip of slave in chip-to-chip cascade operation.

0 Master or not last of slave chip (default)

1 Last of slave chip

LINK\_EN Control chip-to-chip cascade connection for X and Y path.

0 Disable cascade operation (default)

1 Enable cascade operation

LINK\_NUM Define number of chip-to-chip cascade stage.

0 Master chip (default)

1 1st slave chip

2 2nd slave chip

3 3rd slave chip

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x30		MCLK	DEL_Y			MCLK	DEL_X	

MCLKDEL Control delay of clock to SDRAM for X and Y path.

The delay can be controlled by 1ns.

The default value is 0.

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Χ	1x01	0	EDAME OD	RAME_OP FRAME_ FLD	DIC MODE	HDIV		VDIV	
Υ	1x31	U	FRAIVIE_OP		DIS_MODE				

FRAME\_OP

Select frame operation mode.

- Normal operation mode (Default)
- 1 Frame operation mode

DIS\_MODE

Select display mode depending on FRAME\_OP.

When  $FRAME_OP = 0$ 

- Monitor Display Mode (Default)
- **DVR Display Mode** When  $FRAME_OP = 1$
- Frame Display Mode
- **DVR Frame Display Mode**

FRAME\_FLD

Select display field when FRAME OP = "1".

- 0 Odd field display (default)
- 1 Even field display

**HDIV** 

Horizontal picture size when DIS MODE = "1".

- Full scale size (720 pixels/H) (default)
- 1/2 scale size (360 pixels/H)
- 2 1/3 scale size (240 pixels/H)
- 3 1/4 scale size (180 pixels/H)

**VDIV** 

Vertical picture size,

In DVR display mode (FRAME\_FLD = "0", DIS\_MODE = "1")

- Full scale size (240 lines/V for 60Hz, 288 lines/V for 50Hz) (default) 0
- 1 1/2 scale size (120 lines/V for 60Hz, 144 lines/V for 50Hz)
- 2 1/3 scale size (80 lines/V for 60Hz, 96 lines/V for 50Hz)
- 3 1/4 scale size (60 lines/V for 60Hz, 72 lines/V for 50Hz)

In DVR frame display mode (FRAME\_FLD = "1", DIS\_MODE = "1")

- Not allowed (default)
- 1 Full scale size (240 lines/V for 60Hz, 288 lines/V for 50Hz)
- 2 2/3 scale size (160 lines/V for 60Hz, 192 lines/V for 50Hz)
- 3 1/2 scale size (120 lines/V for 60Hz, 144 lines/V for 50Hz)

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]	
Χ	1x02	0					,			
Υ	1x32	1	SAVE_ADDR							

SAVE\_ADDR Define address of SDRAM for saving picture.

Unit Address has 4Mbit Memory Space.

- 0-3 Reserved for normal operation. Do not use this address.
- 4-15 Possible address for 64M SDRAM
- 4-31 Possible address for 128M SDRAM
- 4-63 Possible address for 256M SDRAM
- 4-127 Possible address for 512M SDRAM

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Χ	1x03	RECALL_	0	SAVE_	SAVE_		S // / / E	_REQ	
Υ	1x33	FLD	U	FLD	HID		SAVL	_NEQ	

RECALL\_FLD Select field or frame data during recall picture.

- Recall frame data from SDRAM (default)
- 1 Recall field data from SDRAM

SAVE\_FLD Select field or frame data to save.

- 0 Save frame data to SDRAM (default)
- 1 Save field data to SDRAM

SAVE\_HID Control priority to save picture.

- O Save picture as shown in screen (default)
- 1 Save picture even though hidden by other picture

SAVE\_REQ Request to save for each channel.

SAVE\_REQ[3:0] stand for channel 3 to 0

- 0 None operation (default)
- 1 Request to start of save picture

	Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Ī	Χ	1x04	TBLINK	CTDD	EID	DUAL DACE		CTDD	DEO	
Ī	Υ	1x34	IDLINK	SIKE	3_FLD	DUAL_PAGE		SIKB	_REQ	

**TBLINK** Control blink period of channel boundary.

Blink for every 30 fields (default)

1 Blink for every 60 fields

STRB\_FLD Control capturing field for strobe operation.

> 0 Capture odd field only (default)

1 Capture even field only

2 Capture first field of any field

3 Capture frame

DUAL\_PAGE Set dual page mode.

Normal strobe operation for each channel (default)

1 Enable dual page operation

STRB\_REQ Request strobe operation.

STRB\_REQ[3:0] stand for channel 3 to 0

None operation (default)

Request to start strobe operation

	Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	Χ	1x05	MUX MODE	TRIC MODE	EVT TDIC	INTO DEO		INITE	R CH	
ĺ	Υ	1x35	INIOV_INIODE	I KIG_NIODE	EXI_IRIG	INTR_REQ		IIVI	K_UH	

MUX\_MODE Define MUX picture mode.

This bit is fixed to "1" for the TW2824Q and TW2824QS.

- Switch channel with still picture (default)
- Switch channel with live picture

TRIG\_MODE Define MUX trigger mode.

- MUX with external trigger from host (default) 0
- MUX with internal trigger

EXT\_TRIG Make trigger when TRIG\_MODE = "0".

- None operation (default)
- Request to start MUX with external trigger

INTR\_REQ Request interrupt MUX

- 0 None operation (default)
- 1 Request to start MUX with interrupt

INTR\_CH Channel number for interrupt MUX.

INTR\_CH[3:2] stand for order of linked chips for interrupt MUX.

- 0 Master chip (default)
- 1 1st slave chip
- 2 2nd slave chip
- 3rd slave chip

INTR\_CH[1:0] stand for channel number for interrupt MUX.

- 0 Channel 0 (default)
- Channel 1
- 2 Channel 2
- Channel 3

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Х	1x06					OUE	CIZE		
Υ	1x36					QUE_	_SIZE		

QUE\_SIZE

Define actual used queue size.

Queue size = 1 (default)

63 Queue size = 64

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Х	1x06	OHE DE	10·01 (O·10						
Υ	1x36	QUE_FEI	QUE_PERIOD [9:8]						
Х	1x07				OHE DE	מיבו מטוכ			
Υ	1x37				QUE_PEF	נט.זן עטוא			

QUE\_PERIOD

Trigger period for internal trigger mode.

Trigger period = 1 field (default)

Trigger period = 1024 fields 1023

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Χ	1x08	MIIV	ELD	QUE_CNT_	QUE_POS_		OUE	: CH	
Υ	1x38	IVIUA	MUX_FLD		RST		QUE	_CH	

MUX\_FLD

Control capturing field for MUX operation.

- Capture odd field only (default)
- 1 Capture even field only
- 2 Capture frame
- 3 Capture frame

INT\_CNT\_RST

Reset internal field counter to count queue period.

- None operation (default)
- 1 Reset field counter

QUE\_POS\_RST

Reset queue address.

- 0 None operation (default)
- 1 Reset queue address and restart address

QUE\_CH

Channel number to be written in internal queue of QUE\_ADDR.

QUE\_CH[3:2] stand for order of linked chips for MUX.

- 0 Master chip (default)
- 1 1st slave chip
- 2 2nd slave chip
- 3 3rd slave chip

QUE\_CH[1:0] stand for channel number for MUX.

- Channel 0 (default)
- Channel 1
- 2 Channel 2
- 3 Channel 3

Pat	h	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]		
Х		1x09	OHE WA	0			OUE	ADDB				
Υ		1x39	QUE_WR	U	QUE_ADDR							

QUE\_WR

Control to write internal queue data.

- None operation (default)
- 1 Request to start writing QUE\_CH in internal queue of QUE\_ADDR

QUE\_ADDR

Define queue address.

0 1st queue address (default)

63 64th queue address

	Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]	
Ī	Χ	1x0A	NOVID	MODE	QUE_POS *						
I	Υ	1x3A	NOVID.	NOVID_MODE			QUE_	PO3			

Notes "\*" stand for read only register

NOVID\_MODE

Channel operation when video loss is detected.

- Bypass (default)
- 1 Capture last image
- 2 Blanked with blank color
- 3 Capture last image and blink channel boundary

QUE\_POS

Information of queue address to be switched next.

- 0 1st queue address (default)
- 63 64th queue address

	Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Ī	Χ	1x0B	0	0	0	0		MUV O	IT CLL*	
Ī	Υ	1x3B	U	U	U	U		MUX_O	UT_CH *	

Notes "\*" stand for read only register

MUX\_OUT\_CH Information of number for current switched channel.

MUX\_OUT\_CH[3:2] stand for order of cascaded chips.

- 0 Master chip
- 1 1st slave chip
- 2 2nd slave chip
- 3 3rd slave chip

MUX\_OUT\_CH[1:0] stands for number of current channel.

- 0 Channel 0
- 1 Channel 1
- 2 Channel 2
- 3 Channel 3

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Χ	1x0C	ZMENA	0	ZMDN	DCOL	ZMBNDEN	ZMAREAEN	71.40	REA
Υ	1x3C	ZIVIEINA	U	ZMBNDCOL		ZIVIDINDEIN	ZIVIAKEAEN	ZIVIA	KEA

**ZMENA** Enable zoom function.

Disable zoom function (default)

1 Enable zoom function

**ZMBNDCOL** Define boundary color for zoom area

> 0 0% Black 1 25% Gray

75% Gray (default)

3 100% White

**ZMBNDEN** Enable boundary of zoom area.

> Disable boundary of zoom area (default) 0

1 Enable boundary of zoom area

**ZMAREAEN** Enable mark of zoom area

> Disable mark of zoom area (default) 0

Enable mark of zoom area

**ZMAREA** Control effect of zoom area.

10 IRE Bright up for inside of zoom area (default)

20 IRE Bright up for inside of zoom area 1

2 10 IRE Bright up for outside of zoom area

20 IRE Bright up for outside of zoom area

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Х	1x0D				700	OMH			
Υ	1x3D				200	JIVIITI			

ZOOMH

Define horizontal left point of zoom area. 4 pixels/step.

0 Left end value (default)

180 Right end value

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Х	1x0E				ZOC	)M/\/			
Υ	1x3E				200	JIVI V			

ZOOMV

Define vertical top point of zoom area. 2 lines/step.

0 Top end value (default)

120 Bottom end value for 60Hz, 525 lines system

144 Bottom end value for 50Hz, 625 lines system

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Χ	1x0F	ED7	רור	DND	001	DCD	100I	DLIZ	COL
Υ	1x3F	FRZ.	FRZ_FLD		BNDCOL		BGDCOL		COL

#### FRZ\_FLD

Select image for freeze function or last image capture on video loss.

- 0 Last image
- 1 Last image of 1 field before
- 2 Last image of 2 fields before (default)
- 3 Last image of 3 fields before

## **BNDCOL**

Define boundary color of channel.

- 0% Black
- 25% Gray 1
- 2 75% Gray
- 100% White (default)

Channel boundary color is changed according to this value when boundary is blinking.

- 100% White 0
- 100% White 1
- 0% Black 2
- 0% Black (default)

#### **BGDCOL**

Define background color.

- 0% Black
- 1 40% Gray (default)
- 2 75% Gray
- 3 Blue (100% Amplitude 100% Saturation)

#### **BLKCOL**

Define color for blanked channel.

- 0 0% Black
- 40% Gray 1
- 2 75% Gray
- Blue (100% Amplitude 100% Saturation) (default)

Path	СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	1x10								
X	1	1x17								
^	2	1x1E								
	3	1x25	CH_EN	DMCH_EN	DMCH_	FUNC	MODE		DEC_PATH	
	0	1x40	CH_EN	DIVICH_EIN	PATH	FUNC_	INIODE		DEC_PAIN	
	1	1x47								
1	2	1x4E								
	3	1x55								

CH\_EN

Control channel enable.

- 0 Channel disable (default)
- 1 Channel enable

DMCH\_EN

Control dummy channel enable when corresponding channel is enabled.

- Dummy channel disable (default)
- Dummy channel enable

DMCH\_PATH

Select real or dummy channel for channel input when dummy channel is enabled.

- 0 Real channel for channel input (default)
- 1 Dummy channel for channel input

FUNC\_MODE

Select operation mode.

- 0 Live mode (default)
- Strobe mode 1
- 2-3 Switch mode

DEC\_PATH

Select video input for each channel.

- Video input from internal video decoder on VINO pins (default)
- 1 Video input from internal video decoder on VIN1 pins
- 2 Video input from internal video decoder on VIN2 pins
- Video input from internal video decoder on VIN3 pins
- 4-7 Video input from external video decoder on PBIN pins

Path	СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	1x11								
X	1	1x18								
^	2	1x1F								
	3	1x26	0	FREEZE	MIDDOD	ENHANCE	POP_UP	BLANK	BOUND	BLINK
	0	1x41	U	FREEZE	WIIKKOK	LINITATIOE	FOF_UF	DLAINN	BOOND	DLINK
	1	1x48								
1	2	1x4F								
	3	1x56								

**FREEZE** Enable freeze function.

> 0 Normal operation (default)

Enable freeze function

**MIRROR** Enable horizontal mirroring function.

Normal operation (default)

Enable horizontal mirroring function

**ENHANCE** Enable image enhancement function.

Normal operation (default)

Enable image enhancement function

POP\_UP Enable pop-up.

Disable pop-up (default)

Enable pop-up

**BLANK** Enable Blank.

Disable blank (default)

Enable blank

**BOUND** Enable channel boundary.

> 0 Disable channel boundary

Enable channel boundary.

**BLINK** Enable boundary blink when boundary is enabled.

> 0 Disable boundary blink (default)

Enable boundary blink

Path	СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	1x12								
X	1	1x19								
^	2	1x20								
	3	1x27	RECALL_			DI		ND.		
	0	1x42	EN			KI	ECALL_ADD	,r		
V	1	1x49								
1	2	1x50								
	3	1x57								

RECALL\_EN Enable recall function.

- O Disable recall function (default)
- 1 Enable recall function

# RECALL\_ADDR Define address to recall.

- 0-3 Reserved address. Do not use this value
  4-15 Possible address for 64M SDRAM
  4-31 Possible address for 128M SDRAM
  4-63 Possible address for 256M SDRAM
- 4-127 Possible address for 512M SDRAM

Path	СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	1x13								
X	1	1x1A								
^	2	1x21								
	3	1x28				DIC	CHL			
	0	1x43				FIC	/I IL			
	1	1x4A								
ī	2	1x51								
	3	1x58								

**PICHL** 

Define horizontal left position of channel region when DIS\_MODE = "0". 1 step is 4 pixels.

Left end (default)

180 Right end

Only PICHL[7:6] defines horizontal channel position when DIS\_MODE = "1".

- 1st position of horizontal region defined by HDIV
- 1 2nd position of horizontal region defined by HDIV
- 2 3rd position of horizontal region defined by HDIV
- 3 4th position of horizontal region defined by HDIV

Path	СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	1x14								
X	1	1x1B								
_ ^	2	1x22								
	3	1x29				DIC	HR			
	0	1x44				FIC	ıπκ			
	1	1x4B								
, r	2	1x52								
	3	1x59								

**PICHR** 

Define horizontal right position of channel region when DIS\_MODE = "0". 1 step is 4 pixels.

Left end (default)

180 Right end

Path	СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	1x15								
X	1	1x1C								
^	2	1x23								
	3	1x2A				PIC	`\/T			
	0	1x45				FIC	, V I			
Y	1	1x4C								
ī	2	1x53								
	3	1x5A								

#### **PICVT**

Define vertical top position of channel region.

1 step is 2 lines when DIS\_MODE = "0" and FRAME\_OP = "0".

Top end (default)

120 Bottom end for 60Hz system

144 Bottom end for 50Hz system

1 step is 4 lines when DIS\_MODE = "0" and FRAME\_OP = "1".

Odd field top end (default)

60 Odd field bottom end for 60Hz system

72 Odd field bottom end for 50Hz system

120 Even field bottom end for 60Hz system

144 Even field bottom end for 50Hz system

Only PICVT[7:6] defines vertical channel position when DIS\_MODE = "1".

- 1st position of vertical region defined by VDIV
- 1 2nd position of vertical region defined by VDIV
- 2 3rd position of vertical region defined by VDIV
- 3 4th position of vertical region defined by VDIV

Path	СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	0	1x16								
X	1	1x1D								
_ ^	2	1x24								
	3	1x2B				DIC	CVB			
	0	1x46				FIC	,VD			
	1	1x4D								
T T	2	1x54								
	3	1x5B								

**PICVB** 

Define vertical bottom position of channel region.

1 step is 2 lines when DIS\_MODE = "0" and FRAME\_OP = "0".

0 Top end (default)

: :

120 Bottom end for 60Hz system

:

144 Bottom end for 50Hz system

1 step is 4 lines when DIS\_MODE = "0" and FRAME\_OP = "1".

0 Odd field top end (default)

: :

60 Odd field bottom end for 60Hz system

: :

72 Odd field bottom end for 50Hz system

: :

120 Even field bottom end for 60Hz system

:

144 Even field bottom end for 50Hz system

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x2C	0	0	0	0	0	0	0	0
1x2D	0	0	0	0	0	0	0	0
1x2E	0	0	0	0	0	0	0	0
1x2F	0	0	0	0	0	0	0	0
1x5C	0	0	0	0	1	0	0	0
1x5D	0	0	0	0	0	0	0	0
1x5E	0	0	0	0	0	0	0	0

This is reserved register.

For normal operation, the above value should be set in this register.

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x5F	MEM_INIT	ENCCLK_Y	ENCCLK_X	0	0	ENCCLKP_ Y	ENCCLKP_X	0

MEM\_INIT Initialize operation mode of SDRAM.

This is cleared by itself after setting "1".

0 None operation (default)

Request to start initializing operation mode of SDRAM

**ENCCLK** Control clock frequency of ENC\_CLK27 pins for digital video output data.

27MHz (default)

54MHz

**ENCCLKP** Control clock phase of ENC\_CLK27 pins.

Normal (default)

Inverted

СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	1x60								
1	1x64				DMD	ICIII			
2	1x68				DIVIP	ICHL			
3	1x6C								

## **DMPICHL**

Define horizontal left position of dummy channel region when DIS\_MODE = "0". 1 step is 4 pixels.

0 Left end (default)

. .

180 Right end

Only DMPICHL[7:6] defines horizontal channel position when DIS\_MODE = "1".

- 0 1st position of horizontal region defined by HDIV
- 2nd position of horizontal region defined by HDIV
- 2 3rd position of horizontal region defined by HDIV
- 3 4th position of horizontal region defined by HDIV

СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]					
0	1x61													
1	1x65		DMPICHR											
2	1x69				DIVIP	ICHK								
3	1x6D													

## **DMPICHR**

Define horizontal right position of dummy channel region when DIS\_MODE = "0". 1 step is 4 pixels.

0 Left end (default)

: :

180 Right end

СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	1x62								
1	1x66				DMP	ICV/T			
2	1x6A				DIVIP	ICVI			
3	1x6E								

## **DMPICVT**

Define vertical top position of dummy channel region.

1 step is 2 lines when DIS\_MODE = "0" and FRAME\_OP = "0".

0 Top end (default)

•

120 Bottom end for 60Hz system

: :

144 Bottom end for 50Hz system

1 step is 4 lines when DIS\_MODE = "0" and FRAME\_OP = "1".

0 Odd field top end (default)

: :

60 Odd field bottom end for 60Hz system

: :

72 Odd field bottom end for 50Hz system

: :

120 Even field bottom end for 60Hz system

: :

144 Even field bottom end for 50Hz system

Only DMPICVT[7:6] defines vertical channel position when DIS\_MODE = "1".

- 0 1st position of vertical region defined by VDIV
- 1 2nd position of vertical region defined by VDIV
- 2 3rd position of vertical region defined by VDIV
- 3 4th position of vertical region defined by VDIV

СН	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	1x63								
1	1x67				DMD	ICVB			
2	1x6B				DIVIP	ICVB			
3	1x6F								

## **DMPICVB**

Define vertical bottom position of dummy channel region.

1 step is 2 lines when DIS\_MODE = "0" and FRAME\_OP = "0".

0 Top end (default)

: :

120 Bottom end for 60Hz system

: :

144 Bottom end for 50Hz system

1 step is 4 lines when DIS\_MODE = "0" and FRAME\_OP = "1".

0 Odd field top end (default)

: :

60 Odd field bottom end for 60Hz system

: :

72 Odd field bottom end for 50Hz system

: :

120 Even field bottom end for 60Hz system

: :

144 Even field bottom end for 50Hz system

	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Γ	1x70	ENC_	_IN_X	ENC_IN_Y		CCIR_IN_X		CCIR_IN_Y	

ENC\_IN Select video data for input of video encoder.

- X path video data without character and mouse pointer overlay (default)
- 1 X path video data with character and mouse pointer overlay
- 2 Y path video data without character and mouse pointer overlay
- 3 Y path video data with character and mouse pointer overlay

CCIR\_IN Select video data for input of ITU-R BT 656 encoder.

- X path video data without character and mouse pointer overlay (default)
- X path video data with character and mouse pointer overlay
- 2 Y path video data without character and mouse pointer overlay
- Y path video data with character and mouse pointer overlay

For the TW2824MS and TW2824QS,

the selection of X and Y path is controlled by only the ENC\_IN\_X[1].

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x71	0	DAC_	PD_X	DAC_OUT _X	0	DAC_	PD_Y	DAC_OUT _Y

DAC\_PD Enable power down for DAC.

- Normal operation (default)
- Power down for DAC of VOUTY pin 1
- 2 Power down for DAC of VOUTC pin
- 3 Power down for both DAC of VOUTY and VOUTC pins

DAC\_OUT Define analog video format.

- S-Video output (default)
- CVBS output

I	ndex	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
	1x72	0	0	CCIR_0	X_TUC	0	0	CCIR_0	OUT_Y

CCIR\_OUT Define type for ITU-R BT.656 digital output.

The default value is "0" for CCIR\_OUT\_X, but "1" for CCIR\_OUT\_Y.

- X path video data with single output mode (27MHz)
- Y path video data with single output mode (27MHz)
- 2 X and Y path video data sequence with dual output mode (54MHz)
- 3 Y and X path video data sequence with dual output mode (54MHz)

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x73	ENC_ MODE	CCIR_ LMT	ENC_VS	ENC_FLD	CCIR_ FLDPOL	ENC_ HSPOL	ENC_ VSPOL	ENC_ FLDPOL

**ENC\_MODE** Define operation mode of video encoder.

Slave mode operation (default)

Master mode operation

CCIR\_LMT Control the data range of ITU-R BT 656 output.

Data range is limited to 1 ~ 254 code (default)

1 Data range is limited to 16 ~ 235 code

ENC\_VS Define vertical sync detection type.

> 0 Detect vertical sync from VSENC pin (default)

Detect vertical sync from combination of HSENC and FLDEN pins

ENC\_FLD Define field polarity detection type

Detect field polarity from FLDENC pin (default)

Detect field polarity from combination of HSENC and VSENC pins

CCIR\_FLDPOL Invert field polarity of ITU-R BT 656 output.

Normal (default)

Inverted 1

ENC\_HSPOL Control horizontal sync polarity.

Active low (default)

Active high

ENC\_VSPOL Control vertical sync polarity.

Active low (default)

Active high

**ENC\_FLDPOL** Control field polarity.

Even field is high (default)

Odd field is high

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x74	ENC_\	/SOFF			ENC_\	/SDEL		

**ENC\_VSOFF** 

Compensate field offset for first active video line.

- Applied same ENC\_VSDEL for odd and even field (default)
- 1 Applied {ENC\_VSDEL+1} for odd and ENC\_VSDEL for even field
- 2 Applied ENC\_VSDEL for odd and {ENC\_VSDEL +1} for even field
- Applied ENC\_VSDEL for odd and {ENC\_VSDEL +2} for even field

**ENC\_VSDEL** 

Control vertical delay of active video line from vertical sync by 1 line/step.

- 0 No delayed
- 32 32 lines delayed (default)
- 63 63 lines delayed

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x75				ENC_H	HSDEL			

ENC\_HSDEL

Control horizontal delay of active video pixel from horizontal sync by 2 pixels/step.

- 0 No delayed
- 32 64 pixels delayed (default)
- 255 510 pixels delayed

	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
Ī	1x76		,	ACTIVE_HDEL	_			ACTIVE_VDEL	_

ACTIVE\_HDEL Control horizontal delay only for active video with 2 pixels/step.

- 30 Pixels delayed

15 0 Pixel delayed (default)

31 + 32 Pixels delayed

ACTIVE\_VDEL Control vertical delay only for active video with 1 line/step.

- 4 Lines delayed

0 Line delayed (default)

+ 3 Lines delayed

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x77	ENC.	_FSC	0	0	1	ENC_ PHALT	ENC_ ALTRST	ENC_ PED

ENC\_FSC Set color sub-carrier frequency for video encoder.

3.57954545 MHz (default)

4.43361875 MHz

3.57561149 MHz 2

3.58205625 MHz 3

**ENC\_PHALT** Set phase alternation.

Disable phase alternation for line-by-line (default)

Enable phase alternation for line-by-line

ENC\_ALTRST Reset phase alternation for every 8 fields

Disable phase alternation reset for every 8 fields (default)

1 Enable phase alternation reset for every 8 fields

ENC\_PED Set 7.5IRE for pedestal level

Disable 7.5 IRE for pedestal level

Enable 7.5 IRE for pedestal level (default)

Inde	ex	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x7	8	ENC_C	CBW_X	ENC_Y	/BW_X	ENC_C	BW_Y	ENC_Y	/BW_Y

**ENC\_CBW** Control chrominance bandwidth of video encoder.

0 0.8 MHz

1 1.15 MHz 2 1.35 MHz (default)

3 Do not use

**ENC\_YBW** Control luminance bandwidth of video encoder.

0 Narrow bandwidth

1 More Narrow bandwidth

2 Wide bandwidth (default)

3 Do not use

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x79	ENC_	ENC_	ENC_	ENC_	ENC_		ENC_	
12/9	BAR_X	CKILL_X	BAR_Y	CKILL_Y	VS_READ *	FLD_READ *		

Notes "\*" stand for read only register

ENC\_BAR Enable test pattern output.

0 Normal operation (default)

1 Internal color bar with 100% amplitude 100 % saturation

**ENC\_CKILL** Color killer

0 Normal operation (default)

1 Color is killed

ENC\_VS\_READ Vertical sync can be read via this register.

ENC\_FLD\_READ Internal field counter can be read via this register.

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]				
1x7A		FONT_WR_DATA[27:20]										
1x7B	FONT_WR_DATA[19:12]											
1x7C		FONT_WR_DATA[11:4]										
1x7D	FONT_WR_DATA[3:0] 0 0 0 0											

FONT\_WR\_DATA Font data for 1 line of 1 font.

The default value is 0.

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x7E	0			FC	NT_WR_IND	ΞX		

0 Index 0 (default)

: :

127 Index 127

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x7F	FONT_ REQ_X	FONT_ REQ_Y	FONT_ WR_PAGE	FONT_ WR_FLD		FONT_V	VR_LINE	

FONT\_REQ Request to start writing font to SDRAM.

This bit is cleared by itself after a few clocks.

0 None operation (default)

1 Request to start writing font

FONT\_WR\_PAGE Define font page to be written.

0 Page 0 (default)

1 Page 1

FONT\_WR\_FLD Define font field to be written.

0 Odd field (default)

1 Even field

FONT\_WR\_LINE Define font line to be written.

0 1st Line (default)

15 16th Line

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x80 0	0	FONT_	FOI	_	0	FONT_	FOI	_
	_	RD_PAGE_X	RD_F	LD_X		RD_PAGE_Y	RD_F	LD_Y

FONT\_RD\_PAGE Define font page to be displayed.

0 Page 0 (default)

Page 1

FONT\_RD\_FLD Define font field to be displayed.

0 Character is not displayed (default)

- 1 Odd field font is used for both odd and even field
- 2 Even field font is used for both odd and even field

3 Both odd and even field font are used for frame display

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x81	0	0	RAMCLR _Y	RAMCLR _X	CLASSEN0 _Y	CLASSEN0 _X	PHIGH	PLOW

RAMCLR Clear display RAM.

This bit is cleared by itself after finishing display RAM clear.

None operation (default)

Request to start clearing display RAM

CLASSEN0 Enable class 0 in character mode.

> 0 Disable class 0 (default)

Enable class 0

**PHIGH** Select blink time for high.

0.5 second (default)

0.75 second

**PLOW** Select blink time for low.

> 0.5 second (default) 0

0.75 second

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x82	CH/ VSIZ		CH/ HSIZ		CH/ VSIZ	_	CH/ HSIZ	_

CHAR\_VSIZE

Vertical size of displayed character.

- 10 Lines (default)
- 12 Lines
- 2 14 Lines
- 3 16 Lines

CHAR\_HSIZE

Horizontal size of displayed character.

- 8 Dots (16 Pixels) (default)
- 10 Dots (20 Pixels)
- 2 12 Dots (24 Pixels)
- 3 14 Dots (28 Pixels)

Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]	
Х	1x83		СПУВ	VSPC		CHAR HSPC				
Υ	1x85		CHAR_	_V3PC		CHAR_HSPC				

CHAR\_VSPC

Vertical space between displayed characters.

No Space (default)

15 15 Lines space

CHAR\_HSPC

Horizontal space between displayed characters.

No space (default)

15 30 Pixels space

	Path	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]	
Ī	Χ	1x84		CHAR	VDEL		CHAR HDEI				
Ī	Υ	1x86		CHAR.	_VDEL		CHAR_HDEL				

CHAR\_VDEL Vertical offset to first displayed character.

No offset (default)

15 15 Lines offset

CHAR\_HDEL Horizontal offset to first displayed character.

> 0 No offset (default)

15 30 Pixels offset

Ind	ex	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x8	37		CHAR_	MIX_C			CHAR_	_MIX_B	

CHAR\_MIX\_C Control to be mixed with video data in character mode.

CHAR\_MIX\_C[3:0] stand for class 3 to 0.

0 Disable mix function (default)

1 Enable mix function

CHAR\_MIX\_B Control to be mixed with video data in bitmap mode.

CHAR\_MIX\_B[3:0] stand for class 3 to 0.

Disable mix function (default)

Enable mix function

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x88		CHAR_	BLK_C			CHAR_	BLK_B	

CHAR\_BLK\_C Control blink for character mode.

CHAR\_BLK\_C[3:0] stand for class 3 to 0.

Disable blink function (default)

Enable blink function

CHAR\_BLK\_B Control blink for bitmap mode.

CHAR\_BLK\_B[3:0] stand for class 3 to 0.

Disable blink function (default)

1 Enable blink function

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]		
1x89		CLASS3	COL1_C		CLASS 3COL0_C					
1x8A		CLASS3	COL3_C		CLASS 3COL2_C					
1x8B		CLASS3	COL1_B		CLASS 3COL0_B					
1x8C		CLASS3	COL3_B		CLASS 3COL2_B					
1x8D		CLASS2	COL_C		CLASS2COL_B					
1x8E		CLASS1	COL_C		CLASS1COL_B					
1x8F		CLASS	COL_C		CLASS0COL_B					

CLASS3COL0_C	Color selection 0 of class 3 for character mode
CLASS3COL1_C	Color selection 1 of class 3 for character mode
CLASS3COL2_C	Color selection 2 of class 3 for character mode
CLASS3COL3_C	Color selection 3 of class 3 for character mode
CLASS3COL0_B	Color selection 0 of class 3 for bitmap mode
CLASS3COL1_B	Color selection 1 of class 3 for bitmap mode
CLASS3COL2_B	Color selection 2 of class 3 for bitmap mode
CLASS3COL3_B	Color selection 3 of class 3 for bitmap mode
CLASS2COL_C	Color selection of class 2 for character mode
CLASS2COL_B	Color selection of class 2 for bitmap mode
CLASS1COL_C	Color selection of class 1 for character mode
CLASS1COL_B	Color selection of class 1 for bitmap mode
CLASS0COL_C	Color selection of class 0 for character mode
CLASS0COL_B	Color selection of class 0 for bitmap mode

# Color selection table

- 0 White (75% Amplitude 100% Saturation) (default)
- 1 Yellow (75% Amplitude 100% Saturation)
- 2 Cyan (75 % Amplitude 100 Saturation)
- 3 Green (75% Amplitude 100% Saturation)
- 4 Magenta (75% Amplitude 100% Saturation)
- 5 Red (75% Amplitude 100% Saturation)
- 6 Blue (75% Amplitude 100% Saturation)
- 7 0% Black
- 8 100% White
- 9 50% Gray
- 10 25% Gray
- 11 Blue (75% Amplitude 75% Saturation)
- 12 Defined by CLUT0
- 13 Defined by CLUT1
- 14 Defined by CLUT2
- 15 Defined by CLUT3

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]		
1x90	CLUT0_Y									
1x91	CLUT0_CB									
1x92		CLUT0_CR								
1x93		CLUT1_Y								
1x94		CLUT1_CB								
1x95		CLUT1_CR								
1x96		CLUT2_Y								
1x97		CLUT2_CB								
1x98		CLUT2_CR								
1x99		CLUT3_Y								
1x9A		CLUT3_CB								
1x9B	CLUT3_CR									

CLUT0_Y	Y component for user defined color 0 (default : 0)
CLUT0_CB	Cb component for user defined color 0 (default : 0)
CLUT0_CR	Cr component for user defined color 0 (default : 0)
CLUT1_Y	Y component for user defined color 1 (default : 0)
CLUT1_CB	Cb component for user defined color 1 (default : 0)
CLUT1_CR	Cr component for user defined color 1 (default : 0)
CLUT2_Y	Y component for user defined color 2 (default : 0)
CLUT2_CB	Cb component for user defined color 2 (default : 0)
CLUT2_CR	Cr component for user defined color 2 (default : 0)
CLUT3_Y	Y component for user defined color 3 (default : 0)
CLUT3_CB	Cb component for user defined color 3 (default : 0)
CLUT3_CR	Cr component for user defined color 3 (default : 0)

Inde	<b>x</b> [7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x9	CHAR_ PATH	0	0			CHAR_VLOC	;	

CHAR\_PATH

Select display RAM of X or Y path to write character's attributes.

Write into display RAM of X path (default)

Write into display RAM of Y path

CHAR\_VLOC

Define vertical position of displayed character.

1st character vertically (default)

28 29th character vertically

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x9D	0	0	CHAR_HLOC					

CHAR\_HLOC

Define horizontal position of displayed character.

1st character horizontally (default)

44 45th character horizontally

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
1x9E	0	0	0	0	CHAR_ATTR[11:8]			
IX9E	CHAR_ATTR[7:0]							

CHAR\_ATTR

Character's attributes to be written into display RAM with CHAR\_HLOC, CHAR\_VLOC and CHAR\_PATH.

Each character's attributes consist of 2 bytes so that it should be written in pairs.

CHAR\_ATTR has following information.

CHAR\_ATTR[11]

Mix enable

0 Disable mix

1 Enable mix with video data

CHAR\_ATTR[10]

Blink enable

0 Disable blink 1 Enable blink

CHAR\_ATTR[9:8]

Color of class3

0 CLASS3COL0 in register 1x89~1x8C

1 CLASS3COL1 in register 1x89~1x8C

2 CLASS3COL2 in register 1x89~1x8C

3 CLASS3COL3 in register 1x89~1x8C

CHAR\_ATTR[7]

Type

0 Character type

1 Bitmap type

CHAR\_ATTR[6:0]

Font index

0 1st index

127 128th index

Inde	<b>x</b> [7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
2x0	0 CUR_ ON_X	CUR_ ON_Y	CUR_ TYPE	CUR_ SUB	CUR_ BLINK	0		

CUR\_ON Enable mouse pointer.

Disable mouse pointer (default)

Enable mouse pointer

CUR\_TYPE Select mouse type

Small mouse pointer (default)

Large mouse pointer

CUR\_SUB Control inside style of mouse pointer.

> 0 Transparent (default) Filled with white color

CUR\_BLINK Enable blink of mouse pointer.

Disable blink (default)

Enable blink with 0.5 second period

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]				
2x00							CUR_HP[0]	CUR_VP[0]				
2x01		CUR_HP[8:1]										
2x02		CUR_VP[8:1]										

CUR\_HP Horizontal location of mouse pointer.

0 Pixel position (default)

360 720 Pixels position

CUR\_VP Vertical location of mouse pointer.

0 Line position (default)

288 288 Line position

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
2x03	BOX_TYPE	BOX_EMP	0	0	BOX_PLNEN			

BOX\_TYPE Select single box type.

0 Flat type (default)

1 3D type

BOX\_EMP Enable emphasis on box plane.

0 Disable emphasis (default)

1 Enable emphasis

BOX\_PLNEN Enable each box plane color.

BOX\_PLNEN[3] enables box plane color defined by BOX\_PLNCOL3
BOX\_PLNEN[2] enables box plane color defined by BOX\_PLNCOL2
BOX\_PLNEN[1] enables box plane color defined by BOX\_PLNCOL1
BOX\_PLNEN[0] enables box plane color defined by BOX\_PLNCOL0

0 Disable box plane color (default)

1 Enable box plane color

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
2x04	BOX_BNDCOL							

BOX\_BNDCOL Select box boundary color as the following table The default value is 0.

Б.		С	ontrol Regist	er		Color Description	
Bou	ndary	BOX_TYPE	BOX_OBND	BOX_IBND	Register	Color	
			0	0		Box off	
O	uter		0	1	BOX_ BNDCOL	Boundary off	
			1	0	[7:4]	0~10:0, 10, 20, 30, 40, 50, 60, 70, 80, 90, 100 IRE Gray 11~14: Selected by BOX_PLNCOL0 ~ BOX_PLNCOL3.	
		0	1	1		15 : Same as plane color with 20IRE down of luminance	
		(Flat Type)	0	0	BOX_ BNDCOL	Box off	
In	ner		1	0		Same as inner area	
			0	1	[3:0]	0~10: 0, 10, 20, 30, 40, 50, 60, 70, 80, 90, 100 IRE Gray 11~14: Selected by BOX_PLNCOL0~BOX_PLNCOL3.	
			1	1		15 : Same as plane color with 20IRE up of luminance	
	Left		0	0		Box off	
	&		0	1	BOX_ BNDCOL	Boundary off	
	Top Outer		1	0	[7:6]	0~3 : 90, 80, 70, 60 IRE Gray	
Outer			1	1		0~3:0, 10, 20, 30 IRE Gray	
	Right		0	0		Box off	
	&		0	1	BOX_ BNDCOL	Boundary off	
	Bottom		1	0	[5:4]	0~3:0, 10, 20, 30 IRE Gray	
		1	1	1		0~3 : 90, 80, 70, 60 IRE Gray	
	Left	(3D Type)	0	0		Box off	
	&		0	1	BOX_ BNDCOL	Boundary off	
	Тор		1	0	[3:2]	Same as inner area	
Inner			1	1		0~3 : 30, 40, 50, 60 IRE Gray	
	Right		0	0		Box off	
	&		0	1	BOX_	Boundary off	
	Bottom		1	0	BNDCOL [1:0]	0~3 : 30, 40, 50, 60 IRE Gray	
	Bottom		1	1		0~3 : 70, 60, 50, 40 IRE Gray	

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]	
2x05		BOX_PI	NCOL3		BOX_PLNCOL2				
2x06		BOX_PI	NCOL1			BOX_PI	_NCOL0		

BOX\_PLNCOL3 Define box plane color for BOX\_PLNSEL = 3 BOX\_PLNCOL2 Define box plane color for BOX\_PLNSEL = 2 BOX\_PLNCOL1 Define box plane color for BOX\_PLNSEL = 1 BOX\_PLNCOL0 Define box plane color for BOX\_PLNSEL = 0

## Color selection table

- 0 White (75% Amplitude 100% Saturation) (default)
- Yellow (75% Amplitude 100% Saturation)
- 2 Cyan (75 % Amplitude 100 Saturation)
- 3 Green (75% Amplitude 100% Saturation)
- Magenta (75% Amplitude 100% Saturation)
- 5 Red (75% Amplitude 100% Saturation)
- 6 Blue (75% Amplitude 100% Saturation)
- 7 0% Black
- 8 100% White
- 9 50% Gray
- 10 25% Gray
- 11 Blue (75% Amplitude 75% Saturation)
- 12 Defined by CLUT0
- 13 Defined by CLUT1
- 14 Defined by CLUT2
- 15 Defined by CLUT3

Box	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	2x07								
1	2x0C								
2	2x11								
3	2x16								
4	2x1B								
5	2x20								
6	2x25								
7	2x2A	BOX_	BOX_	BOX_	BOX_	ВС	X_		
8	2x2F	PATH	OBND	IBND	PLNMIX	PLN	ISEL		
9	2x34								
10	2x39								
11	2x3E								
12	2x43								
13	2x48								
14	2x4D								
15	2x52								

BOX\_PATH Select path for box to be displayed.

X path (default)

Y path

BOX\_OBND Enable outer boundary.

Refer to the box boundary color in 2x04.

The default value is 0

BOX\_IBND Enable inner boundary.

Refer to the box boundary color in 2x04.

The default value is 0

BOX\_PLNMIX Enable to mix box plane with video data.

> 0 Disable to mix (default)

Enable to mix

BOX\_PLNSEL Select box plane color.

> 0 Color defined by BOX\_PLNCOL0 and BOX\_PLNEN[0] (default)

1 Color defined by BOX\_PLNCOL1 and BOX\_PLNEN[1]

2 Color defined by BOX\_PLNCOL2 and BOX\_PLNEN[2]

Color defined by BOX\_PLNCOL3 and BOX\_PLNEN[3]

Box	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	2x07								
1	2x0C								
2	2x11								
3	2x16								
4	2x1B								
5	2x20								
6	2x25								
7	2x2A							BOX_	
8	2x2F							HL[0]	
9	2x34								
10	2x39								
11	2x3E								
12	2x43								
13	2x48								
14	2x4D								
15	2x52								
0	2x08								
1	2x0D								
2	2x12								
3	2x17								
4	2x1C								
5	2x21								
6	2x26								
7	2x2B				ВО				
8	2x30				HL[	8:1]			
9	2x35								
10	2x3A								
11	2x3F								
12	2x44								
13	2x49								
14	2x4E								
15	2x53								

BOX\_HL Define horizontal left location of box.

0 Left end (default)

: :

360 Right end

Box	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]				
0	2x09												
1	2x0E												
2	2x13												
3	2x18												
4	2x1D												
5	2x22												
6	2x27												
7	2x2C		BOX_HW										
8	2x31				BOX	_HVV							
9	2x36												
10	2x3B												
11	2x40												
12	2x45												
13	2x4A												
14	2x4F												
15	2x54												

BOX\_HW Define horizontal size of box.

0 0 Pixel width (default)

:

180 720 Pixels width

Box	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	2x07								
1	2x0C								
2	2x11								
3	2x16								
4	2x1B								
5	2x20								
6	2x25								
7	2x2A								BOX_
8	2x2F								VT[0]
9	2x34								
10	2x39								
11	2x3E								
12	2x43								
13	2x48								
14	2x4D								
15	2x52								
0	2x0A								
1	2x0F								
2	2x14								
3	2x19								
4	2x1E								
5	2x23								
6	2x28								
7	2x2D				ВО	X_			
8	2x32				VT[	8:1]			
9	2x37								
10	2x3C								
11	2x41								
12	2x46								
13	2x4B								
14	2x50								
15	2x55								

BOX\_VT Define vertical top location of box.

0 Vertical top (default)

: :

288 Vertical bottom

Box	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]				
0	2x0B												
1	2x10												
2	2x15												
3	2x1A												
4	2x1F												
5	2x24												
6	2x29												
7	2x2E		BOX_VW										
8	2x33				ВОХ								
9	2x38												
10	2x3D												
11	2x42												
12	2x47												
13	2x4C												
14	2x51												
15	2x56												

 $\mathsf{BOX}_\mathsf{VW}$ 

Define vertical size of box.

0 0 Lines height (default)

:

144 288 Lines height

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
2x60	0	0	2DBOX_	2DBOX_BNDCOL		2DBOX_	PLNCOL	

## 2DBOX\_BNDCOL

Define the color of 2D arrayed box boundary

- 0 0 % Black (default)
- 1 25% Gray
- 2 50% Gray
- 3 75% White

Define the displayed color for cursor cell and motion-detected region

- 0,175% White (default)
- 2,30% Black

## 2DBOX\_PLNCOL

Define the color of 2D arrayed box plane.

## Color selection table

- 0 White (75% Amplitude 100% Saturation) (default)
- 1 Yellow (75% Amplitude 100% Saturation)
- 2 Cyan (75 % Amplitude 100 Saturation)
- 3 Green (75% Amplitude 100% Saturation)
- 4 Magenta (75% Amplitude 100% Saturation)
- 5 Red (75% Amplitude 100% Saturation)
- 6 Blue (75% Amplitude 100% Saturation)
- 7 0% Black
- 8 100% White
- 9 50% Gray
- 10 25% Gray
- 11 Blue (75% Amplitude 75% Saturation)
- 12 Defined by CLUT0
- 13 Defined by CLUT1
- 14 Defined by CLUT2
- 15 Defined by CLUT3

2D Box	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	1	2x61								
1	2	2x68			2DBOX_	2DBOX_	2DBOX_	2DBOX_	2DBOX_	2DBOX_
2	3	2x6F			MODE	PATH	MIX	PLNEN	CUREN	BNDEN
3	4	2x76								

2DBOX\_MODE Define operation mode of 2D arrayed box.

0 Table mode (default)

1 Motion display mode

2DBOX\_PATH Define path for 2D arrayed box to be displayed.

0 X path (default)

1 Y path

2DBOX\_MIX Control to mix 2D arrayed box plane with video data.

Disable mix (default)

Enable mix

2DBOX\_PLNEN Enable plane of 2D arrayed box.

Disable plane of 2D arrayed box (default)

1 Enable plane of 2D arrayed box

Enable cursor cell inside 2D arrayed box. 2DBOX\_CUREN

Disable cursor cell (default)

Enable cursor cell

2DBOX\_BNDEN Enable boundary of 2D arrayed box.

0 Disable boundary (default)

1 Enable boundary

2D Box	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	1	2x61								
1	2	2x68	2DBOX_							
2	3	2x6F	VT[0]							
3	4	2x76								
0	1	2x62								
1	2	2x69				2DBOX	\/T[0:4]			
2	3	2x70				ZDBOX	_v [0.1]			
3	4	2x77								

2DBOX\_VT

Define vertical top location of 2D arrayed box.

0 Vertical top end (default)

120 Vertical bottom end for 60Hz system

144 Vertical bottom end for 50Hz system

2D Box	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	1	2x61								
1	2	2x68		2DBOX_						
2	3	2x6F		HL[0]						
3	4	2x76								
0	1	2x63								
1	2	2x6A				2DBOX	⊔I [0.4]			
2	3	2x71				ZDBOX	_⊓ <b>∟</b> [0.1]			
3	4	2x78								

2DBOX\_HL

Define horizontal left location of 2D arrayed box.

0 Horizontal left end (default)

360 Horizontal right end

2D Box	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]			
0	1	2x64											
1	2	2x6B				2000	V \/\/						
2	3	2x72		2DBOX_VW									
3	4	2x79											

2DBOX\_VW

Define vertical size of 2D arrayed box.

0 Line height (default)

255 255 Lines height

2D Box	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]			
0	1	2x65											
1	2	2x6C		2DBOX_HW									
2	3	2x73											
3	4	2x7A											

2DBOX\_HW

Define horizontal size of 2D arrayed box.

0 Pixel width (default)

255 510 Pixels width

2D Box	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	1	2x66								
1	2	2x6D		2DBOY	\			2DBQV	LINILINA	
2	3	2x74		ZDBOX	_VNUM			ZDBOX	_HNUM	
3	4	2x7B								

2DBOX\_VNUM

Define row number of 2D arrayed box.

For motion display mode, 11 is recommended.

0 1 Row

11 12 Row (default)

15 16 Rows

2DBOX\_HNUM

Define column number of 2D arrayed box.

For motion display mode, 15 is recommended.

0 1 Column

15 16 Columns (default)

2D Box	VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]	
0	1	2x67									
1	2	2x6E		2DBOY	CLID LID			2DDOV	CLID VD		
2	3	2x75		ZDBOX_	CUR_HP		2DBOX_CUR_VP				
3	4	2x7C									

2DBOX\_CUR\_HP

Define horizontal location of cursor cell within 2DBOX\_HNUM.

0 1st Column (default)

15 16th Column

2DBOX\_CUR\_VP

Define vertical location of cursor cell within 2DBOX\_VNUM.

0 1st Row (default)

15 16th Row

Inde	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
2x7	:	MB_	_DIS			(	0	

MB\_DIS Disable motion and blind detection.

MB\_DIS [3:0] stand for VIN3 to VIN0.

- Enable motion and blind detection (default)
- Disable motion and blind detection

Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
2x7F	(	)	BD_CE	LSENS		BD_L\	/SENS	

**BD\_CELSENS** Define threshold of cell for blind detection.

Low threshold (More sensitive) (default)

3 High threshold (Less sensitive)

BD\_LVSENS Define threshold of level for blind detection.

Low threshold (More sensitive) (default)

15 High threshold (Less sensitive)

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	2x80								
1	2xA0	MASK_	0	MD			MD	VI CINI	
2	2xC0	MODE	U	_טועו	FLD		IVID_F	ALGIN	
3	2xE0								

MASK\_MODE Define mode of MD\_MASK register when reading.

Reading result of motion detection (default)

1 Reading mask information

MD\_FLD Select field for motion detection.

> 0 Detecting motion for only odd field (default)

1 Detecting motion for only even field

2 Detecting motion for both odd and even field

3 Detecting motion for both odd and even field

MD\_ALGIN Adjust horizontal region of motion detection.

0 Pixel shift (default)

15 15 Pixels shift

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	2x81								
1	2xA1	MD CE	LOENC	0			MD IVCENC		
2	2xC1	MD_CE	LSENS	U			MD_LVSENS	)	
3	2xE1								

## MD\_CELSENS

Define threshold of sub-cell number for motion detection.

- Motion detected for cell if 1 sub-cell has motion (More sensitive) (default)
- 1 Motion detected for cell if 2 sub-cells have motion
- 2 Motion detected for cell if 3 sub-cells have motion
- 3 Motion detected for cell if 4 sub-cells have motion (Less sensitive)

## MD\_LVSENS

Control the level sensitivity of motion detector.

- More sensitive 0
- Middle sensitive (default)
- 15 Less sensitive

VII	V	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0		2x82								
1		2xA2	MD_	0			MD S	DEED		
2		2xC2	REFFLD	U			טואו_5	PEED		
3		2xE2								

MD\_REFFLD

Control the updating time of reference field for motion detection.

- Update reference field at every field (default)
- Update reference field according to MD\_SPEED

MD\_SPEED

Control the velocity of motion detector.

Large value is suitable for detection of slow motion.

- Not supported (default)
- 2 field interval
- 61 62 field interval
- 62 Not supported
- 63 Not supported

VIN	Index	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]
0	2x83								
1	2xA3		MD TM	DOENIC		MD_SPSENS			
2	2xC3		MD_TM	PSENS			ואום_סו	SENS	
3	2xE3								

MD\_TMPSENS

Control the temporal sensitivity of motion detector.

- More Sensitive (default)
- 15 Less Sensitive

MD\_SPSENS

Control the spatial sensitivity of motion detector.

- More Sensitive (default)
- 15 Less Sensitive

<b>D</b>		Inc	lex				Motion De	etection N	lask Cont	rol for VIN			
Row	VIN0	VIN1	VIN2	VIN3	[7]	[6]	[5]	[4]	[3]	[2]	[1]	[0]	
1	2x84	2xA4	2xC4	2xE4									
2	2x86	2xA6	2xC6	2xE6									
3	2x88	2xA8	2xC8	2xE8									
4	2x8A	2xAA	2xCA	2xEA									
5	2x8C	2xAC	2xCC	2xEC									
6	2x8E	2xAE	2xCE	2xEE				MD MA	SK[15:8]				
7	2x90	2xB0	2xD0	2xF0				IVID_IVIA	SK[13.0]				
8	2x92	2xB2	2xD2	2xF2									
9	2x94	2xB4	2xD4	2xF4									
10	2x96	2xB6	2xD6	2xF6									
11	2x98	2xB8	2xD8	2xF8									
12	2x9A	2xBA	2xDA	2xFA									
1	2x85	2xA5	2xC5	2xE5									
2	2x87	2xA7	2xC7	2xE7									
3	2x89	2xA9	2xC9	2xE9									
4	2x8B	2xAB	2xCB	2xEB									
5	2x8D	2xAD	2xCD	2xED									
6	2x8F	2xAF	2xCF	2xEF				MD M/	\SK[7:0]				
7	2x91	2xB1	2xD1	2xF1				IVID_IVIA	λοιτ[7.0]				
8	2x93	2xB3	2xD3	2xF3									
9	2x95	2xB5	2xD5	2xF5									
10	2x97	2xB7	2xD7	2xF7									
11	2x99	2xB9	2xD9	2xF9									
12	2x9B	2xBB	2xDB	2xFB									

MD\_MASK

Motion Mask/Detection Cell for VIN

MD\_MASK[15] is right end and MD\_MASK[0] is left end of column.

## Writing mode

- 0 Non-masking cell for motion detection (default)
- 1 Masking cell for motion detection

Reading mode when MASK\_MODE = "0"

- 0 Motion is not detected for cell
- 1 Motion is detected for cell

Reading mode when MASK\_MODE = "1"

- 0 Non-masked cell
- 1 Masked cell

## **Parametric Information**

## **DC Electrical Parameters**

Table 9 Absolute Maximum Ratings

Parameter	Symbol	Min	Тур	Max	Units
VDDADC (measured to VSSADC)	VDD <sub>ADCM</sub>			3.5	V
VDDDAC (measured to VSSDAC)	VDD <sub>DACM</sub>			3.5	V
VDDI (measured to VSSI)	VDD <sub>IM</sub>			3.5	V
VDDO (measured to VSSO)	VDD <sub>OM</sub>			4.6	V
Voltage on Any Digital Data Pin (See the note below)	-	VSSO-0.5		6.0	V
Analog Input Voltage for ADC	•	VDD <sub>ADCM</sub> -0.5		VDD <sub>ADCM</sub> +0.5	V
Analog Input Voltage for DAC		VDD <sub>DACM</sub> -0.5		VDD <sub>DACM</sub> +0.5	V
Storage Temperature	Ts	- 65		150	°C
Junction Temperature	TJ	0		125	° C
Vapor Phase Soldering (15 Seconds)	$T_{VSOL}$		•	220	° C

**NOTE**: Long-term exposure to absolute maximum ratings may affect device reliability, and permanent damage may occur if operate exceeding the rating. The device should be operated under recommended operating condition.

Table 10 Recommended Operating Conditions

Parameter	Symbol	Min	Тур	Max	Units
VDDADC (measured to VSSADC)	VDD <sub>ADC</sub>	2.25	2.5	2.75	V
VDDDAC (measured to VSSDAC)	VDD <sub>DAC</sub>	2.25	2.5	2.75	V
VDDI (measured to VSSI)	VDDı	2.25	2.5	2.75	V
VDDO (measured to VSSO)	VDDo	3.0	3.3	3.6	V
Maximum  VDD <sub>I</sub> – VDD <sub>ADC</sub>				0.3	V
Maximum  VDD <sub>I</sub> – VDD <sub>DAC</sub>				0.3	V
Maximum  VDD <sub>ADC</sub> - VDD <sub>DAC</sub>				0.3	V
Maximum  VDD <sub>O</sub> – VDD <sub>ADC</sub>				1.05	V
Maximum  VDDo - VDDDAC				1.05	V
Maximum  VDDo - VDDı				1.05	V
Analog VIN Amplitude Range (AC coupling required)		0.5	1.0	2.0	V
Ambient Operating Temperature	T <sub>A</sub>	0		70	° C

Table 11 DC Characteristics

Parameter	Symbol	Min	Тур	Max	Units
Digital Inputs					
Input High Voltage (TTL)	VIH	2.0		5.5	V
Input Low Voltage (TTL)	VIL	-0.3		0.8	V
Input Leakage Current (@V <sub>I</sub> =2.5V or 0V)	7			±1	μA
Input Capacitance	C <sub>IN</sub>		6		pF
Digital Outputs					
Output High Voltage	Vон	2.4			V
Output Low Voltage	VoL			0.4	V
High Level Output Current (@VoH=2.4V)	Іон	5.7	11.6	18.6	mA
Low Level Output Current (@VoL=0.4V)	I <sub>OL</sub>	4.1	6.7	8.2	mA
Tri-state Output Leakage Current (@Vo=2.5V or 0V)	loz			±1	μA
Output Capacitance	Co		6		pF
Analog Pin Input Capacitance	CA		6		рF

Table 12 Supply Current and Power Dissipation

Parameter	Symbol	Min	Тур	Max	Units
Analog Supply Current (2.5V)	I <sub>DDA</sub>		200		mA
Digital Internal Supply Current (2.5V)	I <sub>DDI</sub>		630		mA
Digital I/O Supply Current (3.3V)	I <sub>DDO</sub>		20		mA
Total Power Dissipation	Pd		2.15		W

## **AC Electrical Parameters**

Table 13 Clock Timing Parameters

Parameter	Symbol	Min	Тур	Max	Units
Delay from CLK54I to CLK27ENC	1	4.7		12.5	ns
Hold from CLK27ENC (27MHz) to Data	2a	17			ns
Delay from CLK27ENC (27MHz) to Data	2b			21	ns
Hold from CLK54I to Data	3a	8			ns
Delay from CLK54I to Data	3b			12	ns
Setup from PBIN to PBCLK	4a	5			ns
Hold from PBCLK to PBIN	4b	5			ns

Note: Cload = 25pF.

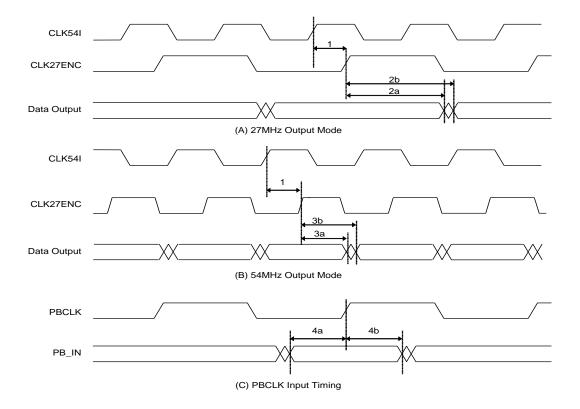


Fig 58 Clock Timing Diagram

Table 14. Serial Interface Timing

t and the state of									
Parameter	Symbol	Min	Тур	Max	Units				
Bus Free Time between STOP and START	t <sub>BF</sub>	1.3			us				
SDAT setup time	tssdat	100			ns				
SDAT hold time	thSDAT	0		0.9	us				
Setup time for START condition	tssta	0.6			us				
Setup time for STOP condition	tsstop	0.6			us				
Hold time for START condition	thSTA	0.6			us				
Rise time for SCLK and SDAT	t <sub>R</sub>			300	ns				
Fall time for SCLK and SDAT	t <sub>F</sub>			300	ns				
Capacitive load for each bus line	C <sub>BUS</sub>			400	pF				
SCLK clock frequency	fsclk			400	KHz				

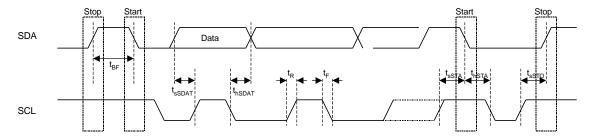


Fig 59. Serial Interface Timing Diagram

Table 15 Parallel Interface Timing Parameter

Parameter	Symbol	Min	Тур	Max	Units
CSB setup until AEN active	Tsu(1)	10			ns
PDATA setup until AEN,WENB active	Tsu(2)	10			ns
AEN, WENB, RENB active pulse width	Tw	40			ns
CSB hold after WENB, RENB inactive	Th(1)	60			ns
PDATA hold after AEN,WENB inactive	Th(2)	20			ns
PDATA delay after RENB active	Td(1)			12	ns
PDATA delay after RENB inactive	Td(2)	60			ns
CSB inactive pulse width	Tcs	60			ns
RENB active delay after AEN inactive RENB active delay after RENB inactive	Trd	60			ns

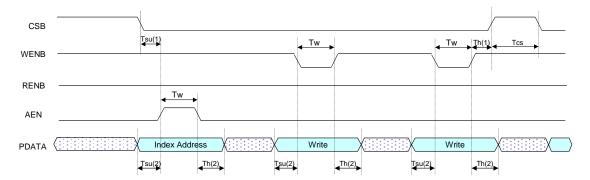


Fig 60 Write timing of parallel interface with auto index increment mode

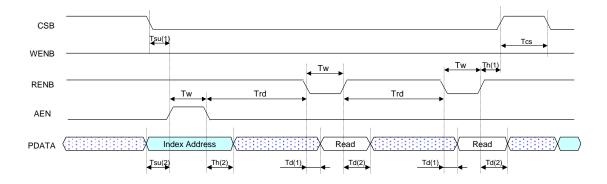


Fig 61 Read timing of parallel interface with auto index increment mode

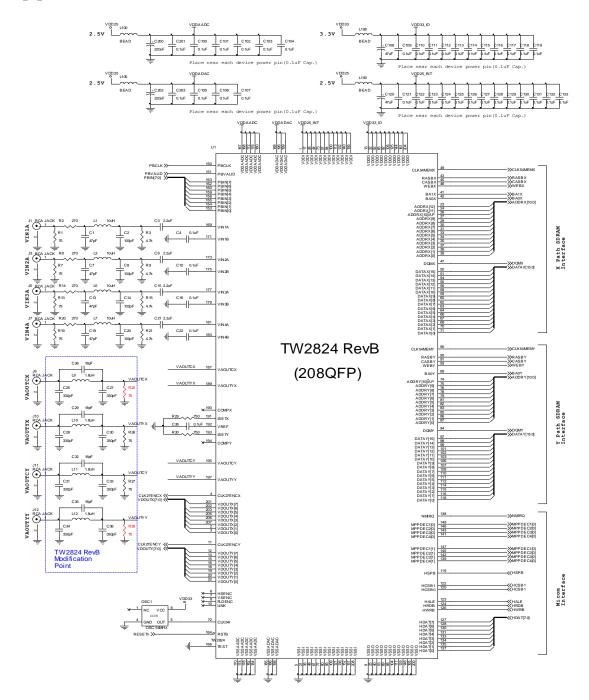
Table 16. Analog Performance Parameter

Parameter	Symbol	Min	Тур	Max	Units
ADC characteristics					
Differential gain	D <sub>G</sub> A			3	%
Differential phase	D <sub>pA</sub>			2	deg
Channel Cross-talk	α <sub>ct</sub> A			-50	dB
DAC characteristic					
Differential gain	D <sub>GD</sub>			3	%
Differential phase	D <sub>pD</sub>			2	deg
Channel Cross-talk	α <sub>ct</sub> A	•		-50	dB

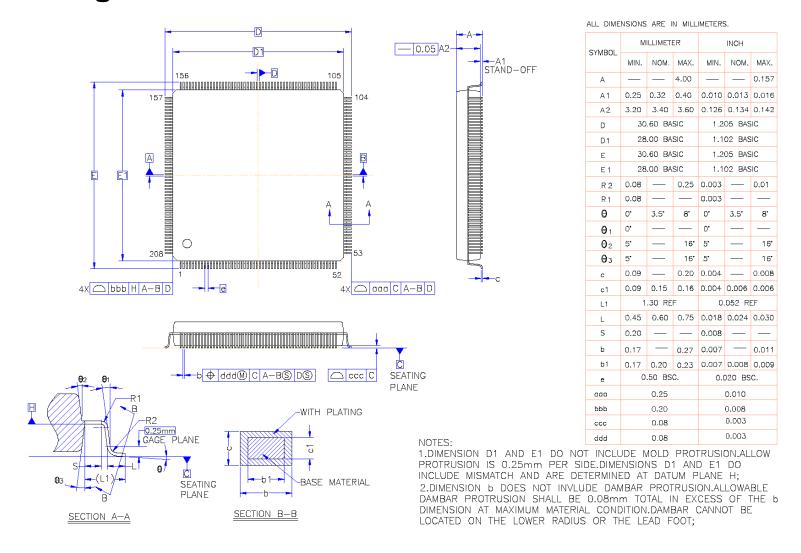
## Table 17.Decoder Performance Parameter

Parameter	Symbol	Min	Тур	Max	Units
Horizontal PLL permissible static deviation	$\Delta f_{H}$			±6	%
Color Sub-carrier PLL lock in range	$\Delta f_{SC}$	±800			Hz
Video level tracking range	AGC	-6		18	dB
Color level tracking range	ACC	-6		30	dB
Oscillator Input					
Nominal frequency	fosc		54		MHz
Permissible frequency deviation	Δfosc/fosc			±100	ppm
Duty cycle	dtosc			60	%

# **Application Schematic**



## **Package Dimension**



## **Revision History**

## Table 18 Datasheet Revision Histories

Revision	Date	Description	Product Code
FN7738.0	Feb. 2, 2011	Assigned file number FN7738 to datasheet as this will be the first release with an Intersil file number. Replaced header and footer with Intersil header and footer. No changes to datasheet content.	

#### Table 19 List of Revision Point in TW2824 RevB

No.	Issue	TW2824 RevA	TW2824 RevB
1	ADC Linearity	-	Improved ADC linearity more
2	DAC output gain mismatch	The termination resistances are not same among four DACs	Fixed the gain mismatch of DAC output. The termination resistances are same among four DACs.

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