bq76PL536A and bq76PL536A-Q1 EVM Quick Start Guide

1 Scope

This document covers the initial connection and installation of the Texas Instruments bq76PL536A and bq76PL536A-Q1 Evaluation Module (EVM), supplied in kit form including the EVM board, the Aardvark USB-SPI adapter, and the connectors to make cells-to-EVM connection. While the EVM includes only bq76PL536A devices, given the very small difference in features between the bq76PL536A and the bq76PL536A-Q1, the EVM can also be used to evaluate the bq76PL536A-Q1. The bq76PL536 EVM Quick Start Guide is not meant as a comprehensive guide to using the bq76PL536A and bq76PL536A-Q1 integrated circuits (ICs) and their features. See the corresponding device data sheets for details (SLUSAD3 and SLUSAM3).

2 Software Installation

2.1 PC Requirements

1. Pentium® 1.66GHz (Core™2 or better recommended)
2. Windows® .NET™ 2.0 or later, with updates
3. Available USB powered-port (hub OK, if wall adapter used)

2.2 Installing the Aardvark Driver

CAUTION

The Aardvark driver must be installed before attaching the adapter for the first time.

The Aardvark driver should be installed prior to installing the TI supplied bq76PL536A and bq76PL536A-Q1 Evaluation software.

1. Download the *USB Drivers - Windows* from the Aardvark web site, http://www.totalphase.com/downloads#aardvark.
2. Select *USB Drivers - Windows*.
3. A window will open, then select the *USB Drivers - Windows vXXX* link under *Download Software Here*. A registration may be necessary.
4. Go to the location where the file was downloaded and run the file "Tools/Aardvark/Drivers/TotalPhaseUSB-v2.xx.exe" to install the drivers.
5. If prompted to do so, plug in the Aardvark to an available USB port using the supplied cable. The port must be a powered-port, typically directly from a PC. Use of a USB non-powered hub may not provide sufficient operating current for the Aardvark or the EVM to operate correctly.

2.3 Installing the bq76PL536A and bq76PL536A-Q1 Evaluation Software

Download the bq76PL536A and bq76PL536A-Q1 Evaluation Software from the tool folder on TI.com located here: http://www.ti.com/tool/BQ76PL536EVM-3-SW.

Run the file "Software/bq76PL536 Evaluation Software x_x_x.msi" to install, where the "x_x_x" indicates the current build number. Installation is automatic. This process installs the GUI (Graphical User Interface) software for Windows. As new versions are released, this process may install over the existing version.

3 EVM Assembly and Configuration

3.1 Configure the Isolated Communications Interface

3.1.1 5-V Versus 3.3-V Selection

In the ISO-COMMS section of the PCB, there are two jumpers. JP5 selects 5-V or 3.3-V I/O operation across the isolation boundary. The Aardvark adapter supplied with the EVM uses 3.3-V logic, but is 5-V tolerant. JP5 should be configured for 3.3-V operation with the supplied Aardvark interface adapter, although either position will work correctly. For connection to a user supplied microcontroller, select the appropriate voltage.

3.1.2 Use USB Power from Aardvark

JP1 selects power from the USB connection through the Aardvark when installed in the “USB” position.

3.2 Configure the EVM Board

3.2.1 Use with Cells

Remove jumpers JP1-18 (18) located near the black battery connectors P1-P3 to reduce the current draw of the board. It is OK to leave the jumpers in place; they connect a 1K precision resistor between each adjacent pair of cell inputs and are supplied to use the EVM with power supplies in place of cells (see Use with ~12-26-VDC Power Supply).

Connect cells to the supplied mating connectors with screw terminals BEFORE plugging the connector into the EVM at P1, the large black connector on the left edge of the board. The most negative cell connects to the most bottom of the black connector (P1).

The bottom-most pin of the battery connector is the most negative connection to the board from the battery stack. This is the negative terminal of cell 1. The next pin in the connector is the positive terminal of cell 1 (and the negative terminal of cell 2). The connections proceed in this fashion up the connector to pin 7, which is the most positive terminal from the battery stack connected to each IC. Pin 7 of P1 (P1.7) is connected to P2.1 on the board. The same is true of P2.7 and P3.1. P3.7 is connected to the top of the PCB (most positive voltage), while P1.1 is connected to the bottom of the PCB (most negative voltage).

The battery connections should be made secure. A loose connection may result in device destruction. Ideally, the cells are connected to one another by secure means such as welding, and only tap points are brought over to the EVM from each cell-to-cell interconnection.

Although the device is immune to the effects of a random connection sequence, the ideal connection sequence is from pin P1.1 to pin 3.7 in order.

TI recommends that users unfamiliar with the EVM and/or li-ion cells begin by using power supplies as outlined in the next section.

3.2.2 Use with ~12-26-VDC Power Supply

Important: Install jumpers JP1-18 (18) located near the black battery connectors P1-P3 before connecting power supplies. These jumpers connect a precision 0.1% resistor divider network between cell connections.

Connect an appropriate power supply capable of supplying 12-26-VDC to connector P1, then plug P1 into the EVM connector. Any voltage that meets the IC requirements will work; a voltage of 18-24 V is typical of most six-cell systems. Plug additional supplies into P2 and P3. The supplies must be isolated from each other and from earth ground to avoid unintentional short circuits. **A separate supply is required for each IC (each cell-connection plug)**.

The supply negative connection is made to pin 1 of the mating connector, the pin that will connect to the bottom-most pin of the mating connector. The positive connection is made to pin 7, the top-most on the connector. It is not necessary to connect to the intermediate pins due to the resistive divider on the EVM which was enabled when JP1-18 were installed

CAUTION

Do not remove any of the jumpers JP1-18 while using the EVM in this configuration. Lethal DC voltages may be present for these configurations. Contact with these voltages may result in serious injury or death. Use appropriate safety precautions.

External Power Supply Requirements:

- Nominal Voltage: 18 VDC
- Maximum Current: 50 mA
- Efficiency Level V

NOTE: TI recommends using an external power supply that complies with applicable regional safety standards such as (by example) UL, CSA, VDE, CCC, PSE, etc.

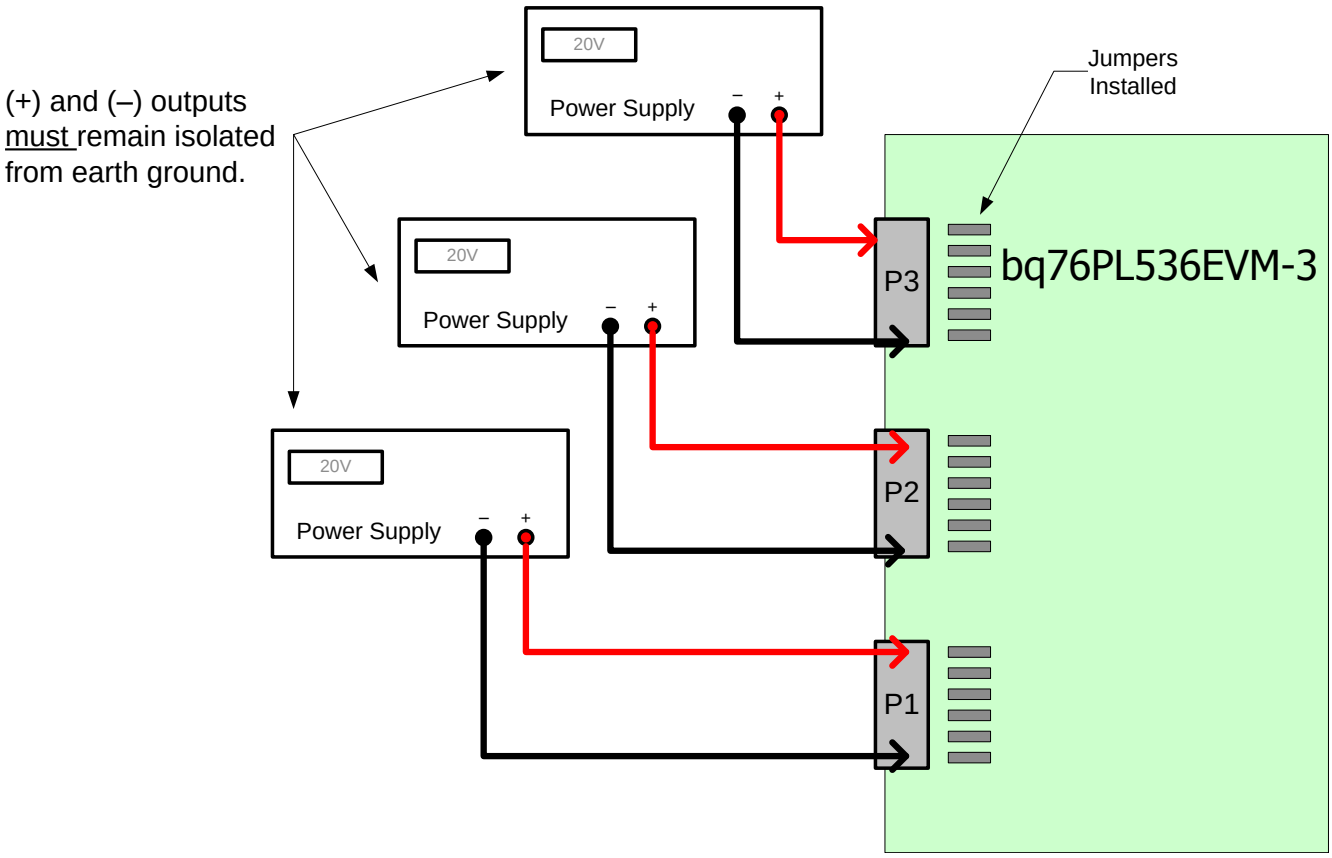


Figure 1. Correct Connection of Three ~20-V Power Supplies to bq76PL536EVM-3

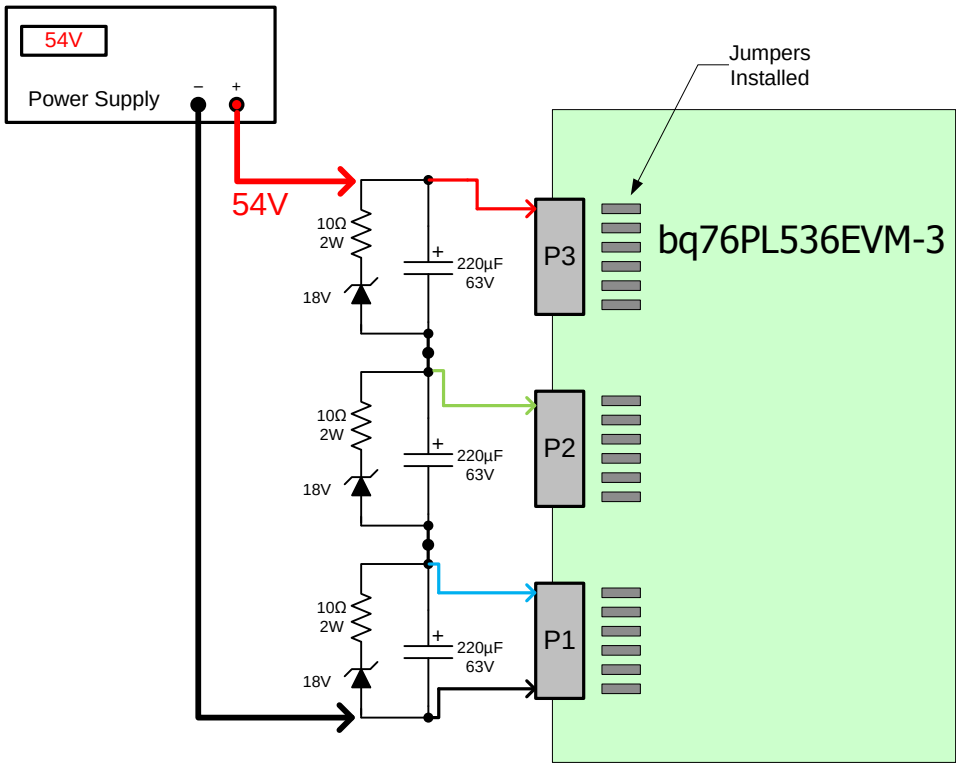


Figure 2. Alternate Connection for a Single 54-V Supply

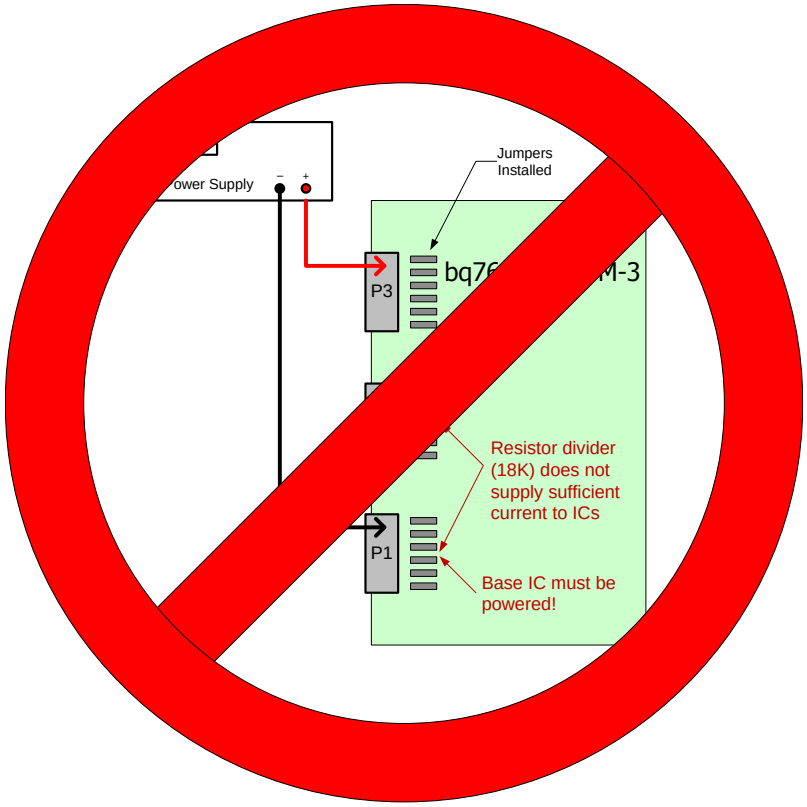


Figure 3. Incorrect Connections, Base IC Not Powered

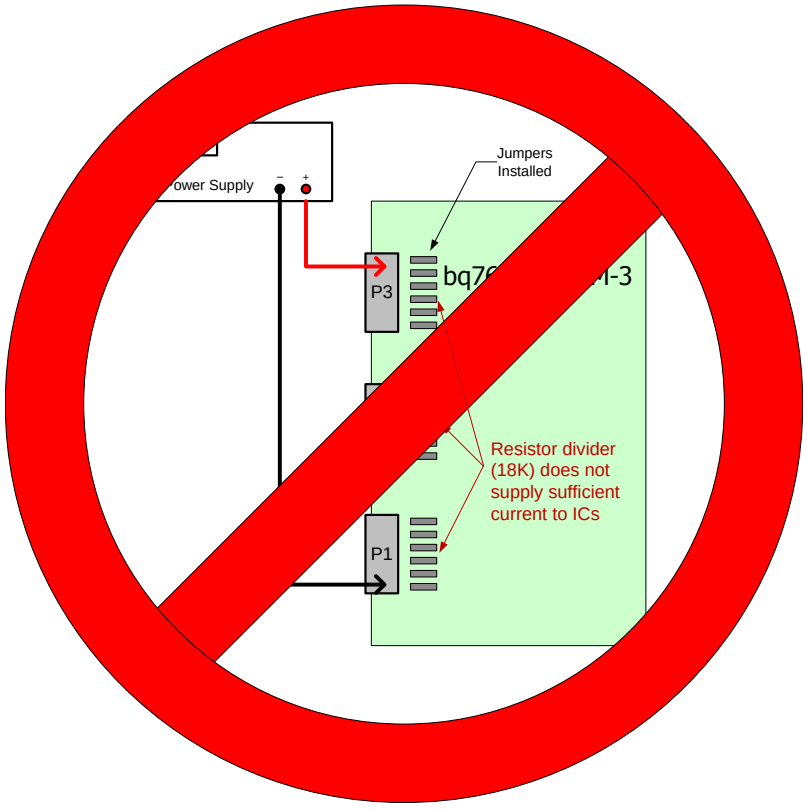


Figure 4. Incorrect Connections, Insufficient V_{BAT} Per IC

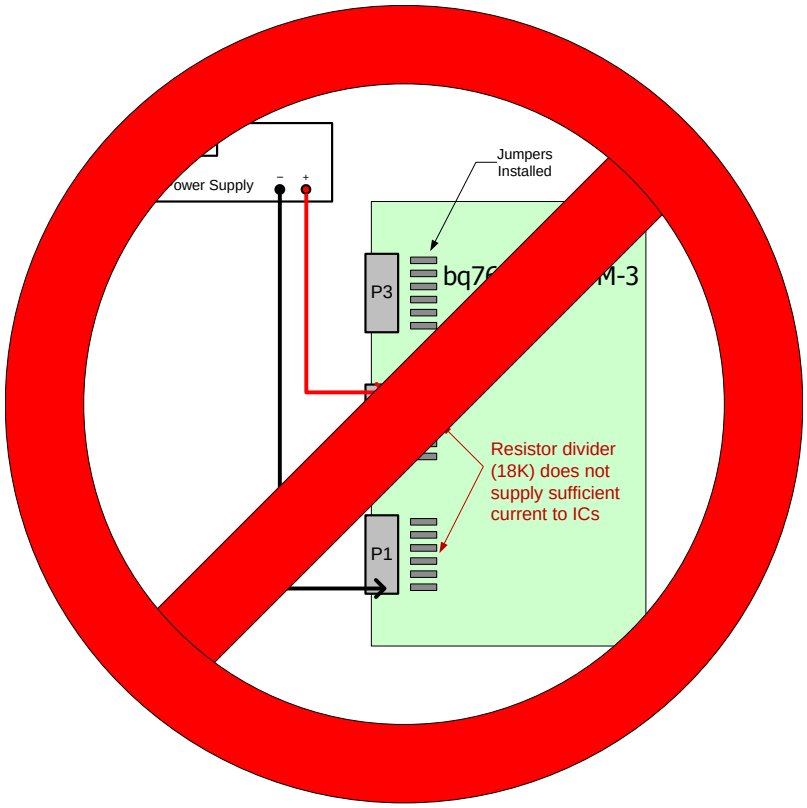


Figure 5. Incorrect Connections, Top IC Not Powered, IC1, 2 Insufficient V_{BAT}

3.3 Non-Critical Hardware Testing or Firmware Development

3.3.1 Stacking EVMs

For casual testing, one or two devices may be powered (in order from negative to positive) in lieu of powering all three devices. Due to poor termination of the unpowered devices in this configuration, detailed testing or critical hardware evaluations should not be undertaken. Any odd behavior or unexpected fault conditions should be ignored until verified with the EVM correctly powered by three isolated supplies.

4 Connecting the EVM

4.1 Connection Order

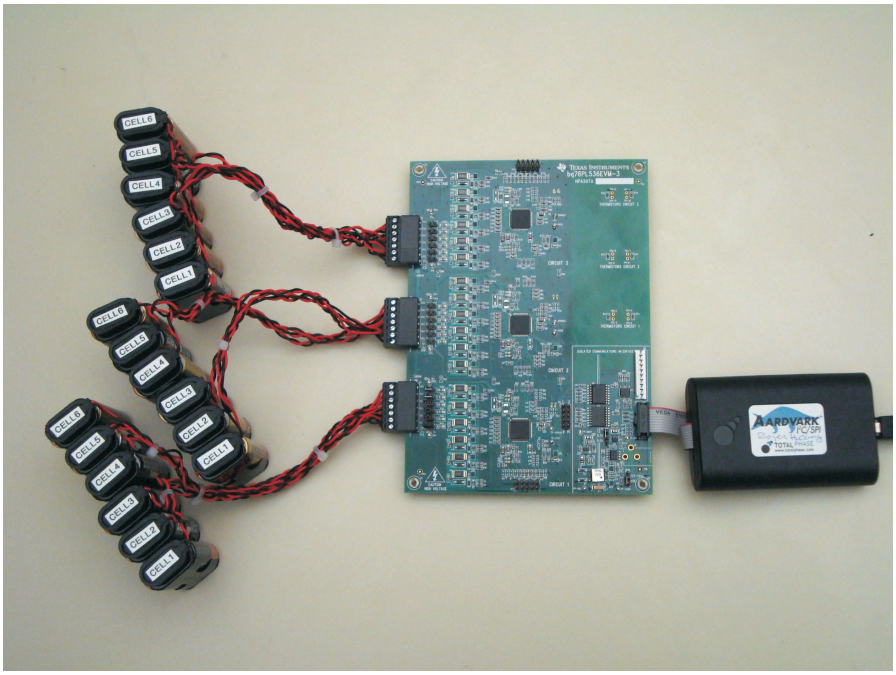


Figure 6. bq76PL536EVM-3

(a) Configure the EVM jumpers per Section 3.1.

(b) Connect the EVM to the Power Supplies or cells, turn on the supplies at ~12-to-24 V is recommended. The Absolute Maximum voltage per IC is 36 V and should not be exceeded, 30 V is the recommended maximum continuous voltage.

(c) Connect the USB cable to the Aardvark and your PC.

(d) Connect the Aardvark ribbon cable to the 10-pin header on the EVM board.

(e) Start the WinGUI User Interface software supplied with the EVM and installed earlier.

4.2 Connection Notes

The ISO-COMMS section of the EVM board isolates the EVM side voltages completely from the PC side. It isolates all power, ground, and signal lines to the EVM. Caution must still be taken when using the EVM as part of a stack, where lethal voltages may be present. The galvanic isolation provided by the ISO-COMMS section does not eliminate the need for safe handling procedures, proper High-Voltage equipment, and protective clothing. Proper safety procedures should always be followed.

Because the ISO-COMMS circuit section fully isolates the PC, Aardvark, and wall adapter from the EVM “battery” side, the Aardvark is insensitive to the powering of the EVM, which receives its power from the battery cells or power supply used for evaluation.

The grounds (VSS) are fully isolated; please keep this in mind when using an oscilloscope or meter. Do not inadvertently connect the EVM VSS to the PC/Aardvark VSS by connecting two probe grounds or otherwise forming a ground loop through external wiring, including the building wiring.

4.3 Quick Check

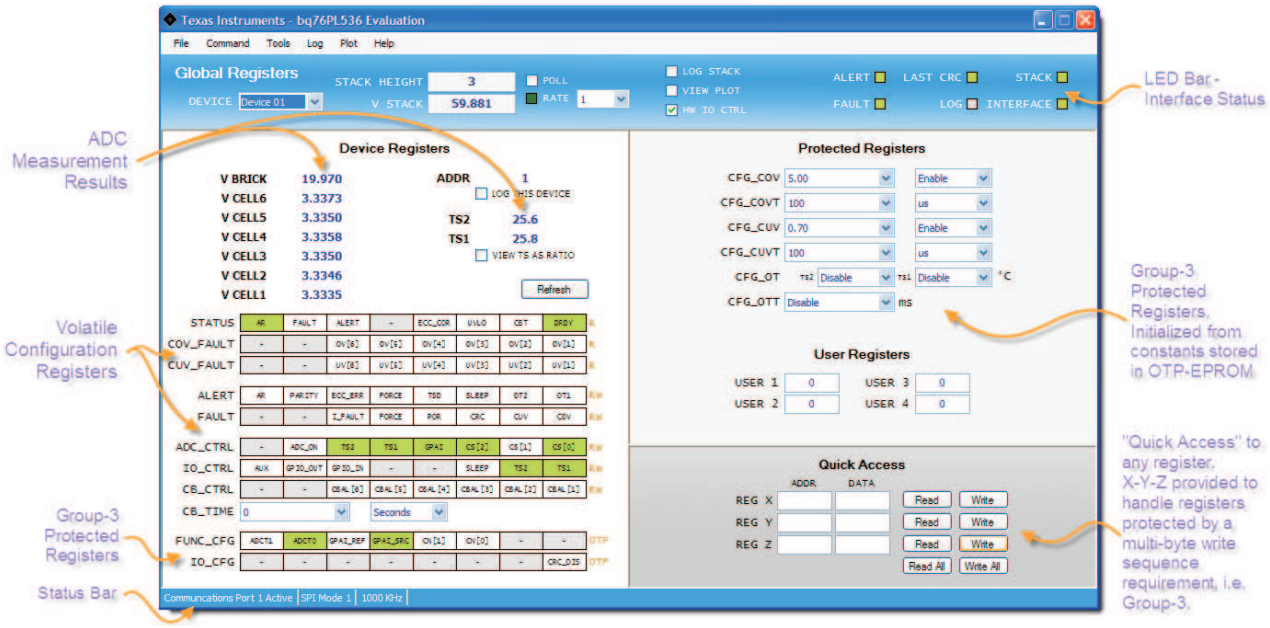
The first step in communicating with the bq76PL536A is to set a unique address for each device in a stack. This is required even if you are only using a single device. This occurs automatically when the Evaluation software is first started. To do this manually, select COMMAND | AUTO ADDRESS (shortcut key CTRL + A). This will cause the software to interrogate the stack of bq76PL536A devices, find all available devices, and assign each a unique address beginning with address 0x01. Address 0x00 is reserved for un-addressed devices.

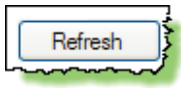
After addressing is complete, you should see the number of devices found and the total combined voltage of all cells being monitoring displayed in the STACK HEIGHT and V STACK windows.

5 Evaluation Software Details

5.1 Main Screen

The main screen is divided into four major areas, plus the menu and status bars. The software is referred to as the “Windows Graphical User Interface”, or abbreviated to WinGUI.



VBRICK	The voltage measured by the bq76PL536A between the BATx and VSS pins
VCELLn	The voltage measured between the pair of pins VCn – VCn-1 (that is, VCELL2 = VC2 – VC1).
ADDR	Displays the address of the device being monitored in the measurement result area.
LOG DEVICE	Checking this box will add the contents of the device at this address to the log file.
TSn	The voltage measured between the TSn+ and TSn- inputs, converted by the WinGUI to temperature based on the characteristics of the thermistor used in the EVM design. The EVM and WinGUI are configured to measure this voltage as a ratio of REG50, which removes any offset or gain errors introduced by drift in the REG50 output.
VIEW AS...	Shows the ratio of the measured input voltage to REG50 as a percentage.
	Refresh updates the displayed measurements for this device. The conversion is started by sending the register command CONVERT[CONV]=1, or hardware by toggling the CONV pin if the HW IO CONTROL box is checked.
	

5.1.1 Volatile RAM Configuration Registers –

The lower half of this area displays the volatile configuration registers shown as bit fields, see the bq76PL536A or bq76PL536A-Q1 data sheet for details on programming these registers. These registers display green for logic 0 and orange for logic 1. The two states may be toggled between by left-clicking on the bit

The STATUS, COV_FAULT, and CUV_FAULT bits are either white (logic 0) or red (logic 1) for asserted. In most cases, the asserted state indicates an error condition sensed by the bq76PL536A.

To clear a fault, first remove the physical condition causing the fault, then click on the ALERT or FAULT bit to reset the state of the bit. This writes a 1 to the bit, followed by a 0, which is the device's method for clearing the asserted bit state back to logic 0.

5.1.2 Group-3 Protected Registers –

The device is provided with many configuration options set by bits contained in a special set of registers protected against accidental writing. These RAM registers are initialized from OTP (One-Time Programmable) EPROM cells. The device is shipped with these EPROM locations un-programmed (blank). The Windows GUI interface hides the un-programmed nature of the device by setting defaults in the registers cells when the Evaluation software starts (this can be defeated by setting the TOOLS | OPTIONS defaults). The last settings are also automatically saved by the GUI and restored upon next use. These features are provided for ease of use and are implemented solely in the GUI. Users are responsible for programming OTP bits in parts correctly during manufacturing for correct operation in-circuit.

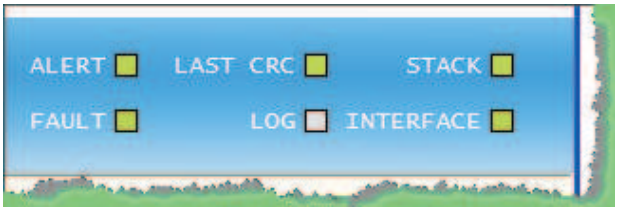
Some Group-3 registers are shown as registers at the bottom of the left side of the screen, the others in the top right section of the screen as listboxes and registers

5.1.3 Quick Access

The Quick Access register(s) provide R/W access to any location in the part. They are named arbitrarily in the GUI 'X', 'Y', and 'Z' – there are no XYZ registers in the part. Some registers, such as the MASTER register require multi-byte writes to "unlock" the target register for writing. To accomplish this, program the X register address/data with the first unlock key, the Y register with the second unlock key, and finally the Z register with the target address and data. Then use the "write all" button to send all three address/data bytes in the correct order and timing to accomplish the multi-byte write. (This is done automatically when using the Protected Registers window.)

5.1.4 LED Status Indicators

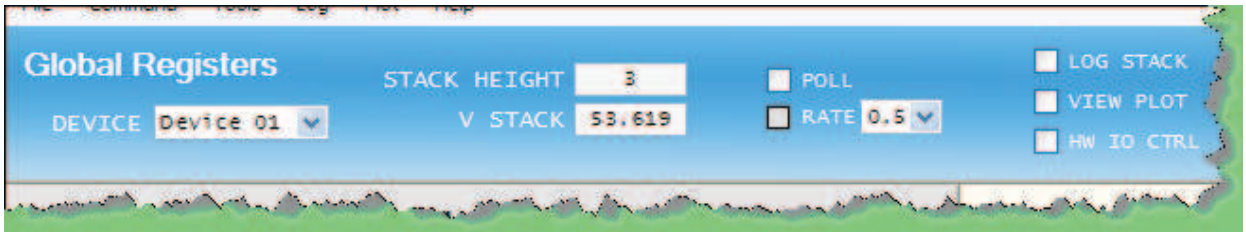
At the top right of the user interface screen are 8 status indicator "LED's". These provide a quick view of the status of the devices, and the interface, cable connections, etc. Green normally indicates a logic 0 condition, and red a logic one condition. Gray indicates undefined.



ALERT	A condition has been sensed that is causing the ALERT hardware pin to be asserted. This is also indicated by the ALERT bit being set (red) in the [DEVICE] STATUS register. The source of the ALERT condition is indicated in the ALERT register just below the STATUS register.
FAULT	Similar to the ALERT indicator, this LED indicates the FAULT bit, and FAULT hardware pin are asserted. The source is indicated in the FAULT register just below the ALERT register.

LAST CRC	The last CRC received by the GUI was incorrect for the contents of the packet. This usually indicates a communication error caused by improper connection, excessive cabling, etc. The cause of the communication error should be corrected before continuing.
LOG	Green if a log file is being written to. Logging is useful to capture information about cell or interface behavior over long periods of time
STACK	At least one device was found during auto-addressing or rebuild addresses. This indicates that the bottom device in the stack was found, is powered, not in POR, and the ribbon cable from the Aardvark to the EVM is connected correctly. This verifies the cabling and connection all the way to the IC.
INTERFACE	The Aardvark USB-SPI interface adapter was successfully found and communicated with. This verifies the cabling and driver to the adapter.

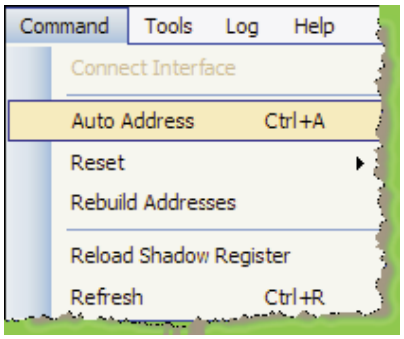
5.1.5 Global Registers



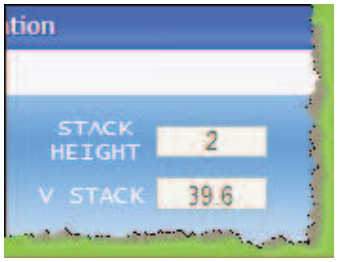
DEVICE	The Address of the device currently being communicated with. Change to access different devices in the stack. “BROADCAST” mode also available to send a single command to all devices in the stack. (In BROADCAST mode, no data are shown – the interface can only display data from one device at a time.
STACK HT.	The number of devices found during the last AUTO-ADDRESS or REBUILD-ADDRESS cycle.
POLL	Check or un-check this box to turn polling on or off. Note that many menu items are unavailable during polling – turn polling off to access them.
RATE	This list box allows choosing a polling rate between 100ms and 60s. The LED illuminates green each time the GUI polls the device stack. Useful as a heartbeat indicator when polling or logging is active. A setting “Fast” is also available. In this position, the WinGUI will poll as fast as possible, with only Windows operating system slowing it down. On most systems, this results in a poll every 10-20ms, but your results may vary depending on the speed of your CPU and other tasks that are running.
LOG STACK	Enables or disables data logging. Logging is to a file in comma-separated-values (.csv) format. Set up logging in the LOG | SETUP menu. Logging may also be started / stopped under the LOG menu. Data are captured each poll, set by the polling interval in TOOLS | INTERFACE.
VIEW PLOT	Check this box to view a dynamic plot of data collected during polling. See *PLOTTING* for further information on configuring the plotter.
HW I/O	Check this box to force the Evaluation software to use the hardware pins CONV and DRDY to initiate and monitor ADC conversion cycles, instead of sending commands to the CONVERT_CTRL[CONV] register bit. Similarly, it is monitoring the FAULT and ALERT hardware pin states to determine a FAULT and/or ALERT condition being present. Note that in HW I/O mode, the REFRESH button toggles the hardware CONV line, but the user may optionally use the CONVERT_CTRL[CONV] bit to force software initiated conversions by clicking on the bit.

5.2 Addressing

The first step in communicating with the bq76PL536A is to set a unique address for each device in the stack. This is required even if you are only using a single device. On the menu, select COMMAND | AUTO ADDRESS (shortcut key CTRL + A). This will cause the software to interrogate the stack of bq76PL536A devices, find all available devices, and assign each a unique address beginning with address 0x01. Address 0x00 is reserved for un-addressed devices.



After addressing is complete, the number of devices found and the total combined voltage of all cells being monitoring are displayed in the STACK HEIGHT and V STACK windows. In this example, two bq76PL536A devices are connected together monitoring 12 cells of about 3.3 V each.

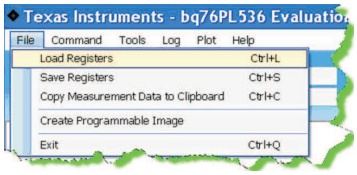


The screen automatically refreshes each time something changes. Addressing the device will cause all displayed values and registers to update. The user hould see all cell voltages displayed, along with registers showing FAULT and ALERT status, DEVICE STATUS, etc.

5.3 Menus and Commands

5.3.1 File Menu

This menu provides a way to save complex register settings between sessions. The settings are saved to a file on the local disk, selected using a dialog box that appears when the Load or Save command is selected. Multiple files, with different settings may be saved under different file names. Saved register settings are then re-loaded from the saved file. All registers – volatile and shadow – are saved or loaded, except the ADC measurements.

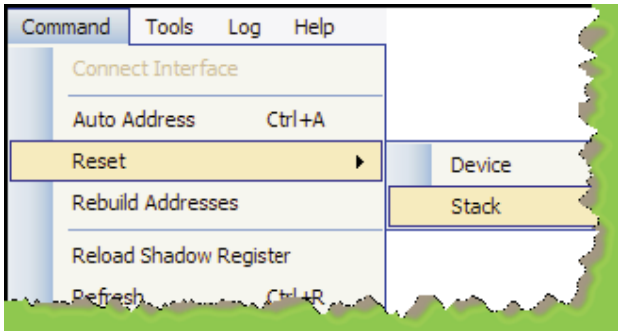


The **Copy Measurement Data to Clipboard** command allows copying the current measurement data (VCn, VBRICK, and TS1, TS2, in that order) to the clipboard, and subsequent copying to a document or spreadsheet. The command will also create EPROM programmable image for bq76PL536A OTP EPROM Programmer.

5.3.2 Command Menu

RESET allows resetting either the current device, or the entire stack with one command. (Note: The stack is reset using a BROADCAST command packet, whether Broadcast is selected as the current device or not.)

RELOAD SHADOW REGISTER will re-initialize the Group-3 Protected Registers from the OTP EPROM. This is useful to verify programming.

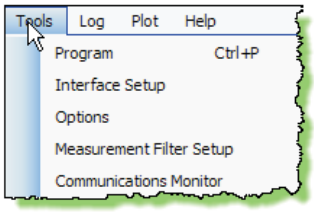


Because the part is shipped unprogrammed, reloading the shadow registers transfers all zeros to the shadow cells, which will usually result in many ALERTS and FAULTS being triggered. These ALERTS and FAULTS are normally hidden by the GUI per the OPTION menu settings (see *Startup Options Dialog*).

REFRESH updates the screen contents, and is equivalent to the large REFRESH button in the Volatile registers area.

5.3.3 Tools Menu

PROGRAM opens a dialog box that programs the contents of the shadow registers to the OTP EPROM cells in the bq76PL536A. The data contained in the equivalent address volatile registers are used as the data source. For example, the data in register CONFIG_OT[] are used to program the EPROM cells which will in turn initialize the CONFIG_OT[] register at the next RESET.



INTERFACE SETUP opens a dialog box that allows changing the SPI communications speed.

OPTIONS opens a dialog that sets program startup options. These are provided to make the GUI easier to use and to prevent a slew of alarms (FAULTS and ALERTS) at startup. Programmers wishing to check their code will want to disable most of these startup niceties during final code checkout. See *Packing List* for details of the startup Options.

MEASUREMENT FILTER SETUP opens a listbox that controls filtering of the measurement data. This is a simple LIFO buffer which is then averaged, producing a running average result. The default value is 1 (no filtering), but it can be set from 1 (no filtering) to 20 (heavy filtering).

COMMUNICATIONS MONITOR opens the SPI-spy text box. All SPI traffic to and from the bq76PL536A is copied into this box in an easy to read hex format shown below. When first opened, a warning message is displayed advising the user that the monitor should only be used for short periods to avoid consuming too much PC memory. If monitoring traffic for more than a few tens of seconds is needed, use the data logging feature built in to the WinGUI.

SDO data are data sent from the monitored stack to the PC. SDI are data sent from the PC (WinGUI) to the stack of bq76PL536As. The monitor displays all data sent to and from the stack.

The Communications Monitor box shown in Figure 7 displays an error found in communicating with a stack. The error shown is normally encountered by the AUTO_ADDRESS algorithm used by the WinGUI as it attempts to find all addressed devices – this error results from an attempted poll to a device that does not exist.

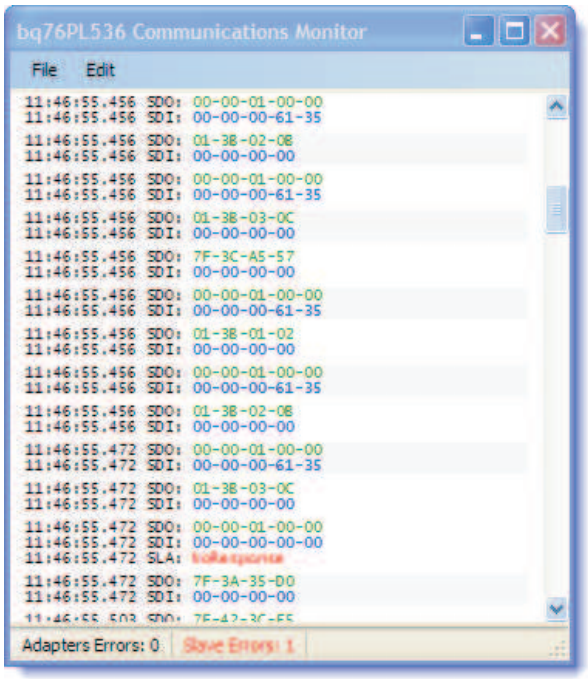
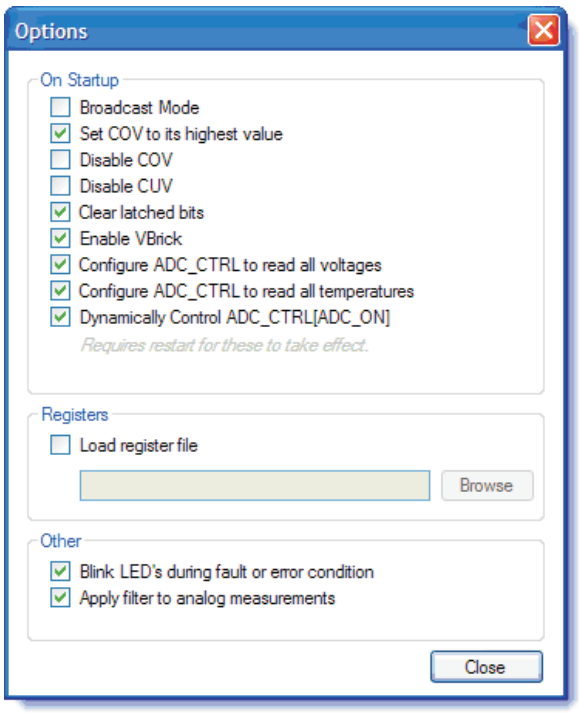


Figure 7. SPI Monitor Showing Communications Error

6 Startup Options Dialog

This dialog controls whether or not the WinGUI sets certain options and registers at startup. If a Group-3 register value is affected, the GUI will write a new value to the RAM register after the POR period; the value is not written to the OTP-EPROM. OTP-EPROM is normally shipped blank from the factory. Overwriting these RAM registers at startup prevents many FAULT and ALERT bits from triggering at startup, and it is done as a user convenience.

The option checkboxes are shown below in the state the WinGUI is shipped in. If the user changes any checkbox states, the new defaults are saved automatically when the WinGUI exits.



BROADCAST MODE, when checked, brings up the interface set to broadcast messages to all devices, no data are shown. In broadcast mode, the WinGUI does not know which device to read, so no register data are displayed.

If this box is not checked, the interface comes up ready to read/write device 1.

SET COV [...] sets the COV threshold to 5.0 V, its highest value

DISABLE COV sets the CONFIG_COV[DISABLE] bit, disabling COV FAULTs

DISABLE CUV sets the CONFIG_CUV[DISABLE] bit, disabling CUV ALERTs

CLEAR LATCHED BITS clears all FAULT and ALERT bits latched in the FAULT and ALERT registers, which may have otherwise normally been set by startup conditions, that is, Power-On-Reset

ENABLE VBRICK sets the ADC_CONTROL[GPAI] and FUNC_CONFIG[GPAI_SRC] bits. This causes the VBRICK value (BAT-VSS) to be measured on each conversion cycle.

READ ALL VOLTAGES sets the bits ADC_CTRL[CS2:0] to 101b to convert all VCn inputs at each conversion request

READ ALL TEMPERATURES sets the bits ADC_CTRL[TS2:1) to convert both thermistor TSn) inputs at each conversion cycle. It also sets the bits IO_CTRL[TS2:1] to turn on the thermistor power

DYNAMICALLY CONTROL ADC_ON sets the bits FUNC_CONFIG[ADCT1:0] to the value 01b, changing the conversion timing from the default 3 µs to 6 µs. The 6 µs setting is recommended for best accuracy. This checkbox also causes the GUI to set the ADC_CTRL[ADC_ON] bit before each conversion, convert, then set the ADC_ON bit back to 0. This is done around each conversion request, whether hardware or software

LOAD REGISTER FILE will cause the registers to be pre-loaded with the contents of the file named in the box. This file should be the one saved by the **File | Save Registers** menu selection. This feature can be used to quickly reload a specific configuration back to the devices under test.

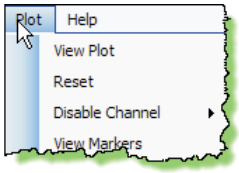
BLINK LED'S causes the LED indicators in the Global Registers area to blink. If not checked, they stay illuminated RED under error conditions.

APPLY FILTER must be checked for the filtering available in the **Tools** menu to be operable. When un-checked, the filter is off (set to 1). Newer versions of the WinGUI (2.1.12 and later) have deleted this option, the filter is controlled directly (and only) from the **Tools | Filter** menu.

7 PLOTTING

7.1 PLOT MENU

The plot menu allows setting up a simple strip-chart recorder for simple data captures. The data captured to the plot are not automatically captured in a log file. The data are available for use or saving in a variety of formats while the program is running. The plotted data are lost if the program is exited without saving. Logged data are preserved in a file.



VIEW PLOT replaces the registers display with the plotter view. It is identical to checking the "View Plot" checkbox in the GLOBAL REGISTERS / LED display area.

RESET completely resets the plotter interface, restoring display defaults and clearing all stored data.

DISABLE CHANNEL opens another menu level and allows removal of data channels from the plot.

VIEW MARKERS displays a tick at each poll, helping to distinguish polls which return invalid or corrupt data from successful polls.

7.2 Plot View

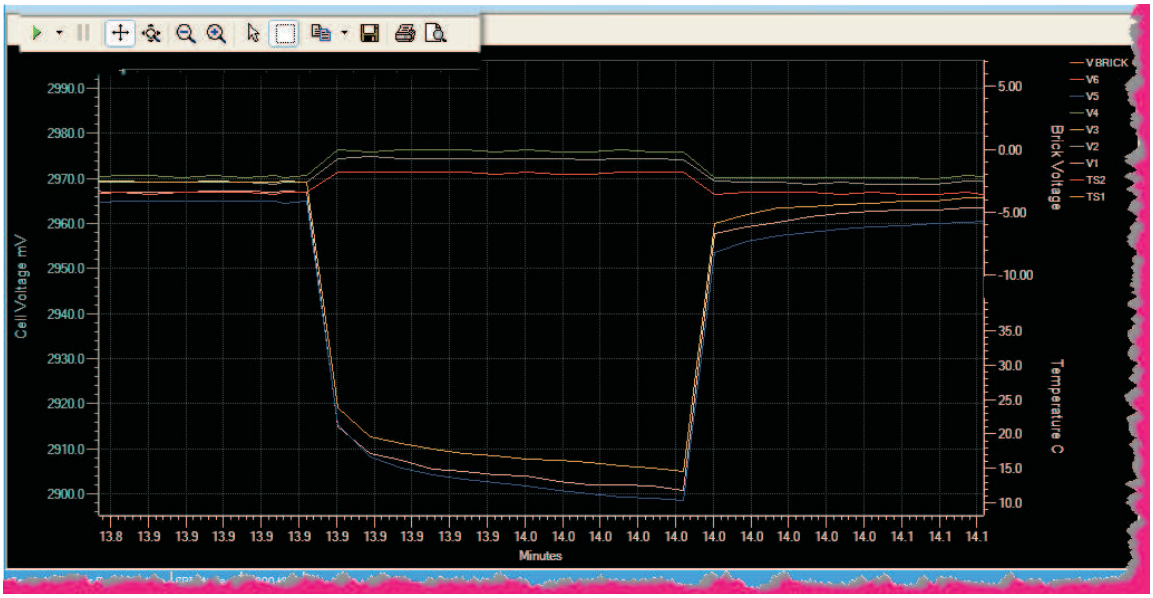
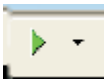


Figure 8. Magnified Window View of the Effect of Cell Balancing for Cells 1-3-5.

7.3 Plotter Controls

Plotter controls are shown slightly magnified in the upper left of the capture above. From the left, they control:



RESUME TRACKING - causes the strip-chart to resume automatically tracking changes in voltage, time, or temperature – in other words, resume auto-ranging. This green arrow is illuminated after manually zooming in or opening a window in the default view. The default is auto-ranging is enabled. The small black down-arrow opens a small menu of selections controlling the automatic tracking. Whether displayed or not, data are always captured on each poll refresh.

PAUSE DISPLAY – momentarily stops auto-tracking. To resume, use the RESUME TRACKING button described above.

SCROLL X-Y – After clicking this control, the display (data) window can be moved by left-clicking the mouse button in the display and moving the mouse. Use RESUME TRACKING to restore the display. Each data set (VCn voltages, VBRICK, temperature, time) scale can be individually moved by clicking and holding the left mouse button on the units field and scrolling up-down or left-right (time scale).

EXPAND X-Y – This control allows zooming in or out on the displayed scale. Choose this button, then click and hold the left mouse button to operate. Each data set (VCn voltages, VBRICK, temperature, time) scale can be individually zoomed by clicking and holding the left mouse button on the units field and scrolling up-down or left-right (time scale).

ZOOM OUT – click on a scale, then click this button to move out in incremental steps.

ZOOM IN – similar but opposite action to Zoom out, above.

SELECT – allows selecting data or scales (opposite of window mode, described next)

WINDOW – click this button, then drag a zoom box around an area in the display to zoom in. This mode is canceled by clicking on the SELECT arrow described above. The display is restored by using the TRACKING RESUME button, above.

COPY TO CLIPBOARD – the data are copied to the clipboard for inclusion in a document or spreadsheet. A small menu allows selecting the numeric data to copy, or the graphic.

SAVE – the graphic to a .PNG file

PRINT – the graphic to a printer

PRINT PREVIEW – see what the graphic will look like on your printer before printing.

8 Support

Contact the local TI sales office for technical support. Support is also available through the TI E2E™ community forum at http://e2e.ti.com/support/power_management/default.aspx

TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

9 Packing List

Line	Quantity	Each	Description
1	1	ea	bq76PL536EVM-3 RevX EVM PCB assembly (x = revision level)
2	1	ea	Aardvark adapter USB→SPI (FW Rev 3.41 or later required)
3	1	ea	USB cable, 1m
4	3	ea	Mating battery connector, 7 pos receptacle
7	20	ea	2 pin jumpers, .025” post, 0.10” cntr
8	1	ea	CD-ROM containing software and documentation

Revision History

Changes from B Revision (May 2011) to D Revision **Page**

- Revision C was deprecated 1
- Changed device from bq76PL536 to bq76PL536A 1
- Added device part numbers throughout document 1
- Changed literature number and added literature number for Q1 device 1
- Deleted Windows XP SP2 from PC Requirements 1
- Changed Aardvark driver download and installation procedure 1
- Changed Evaluation Software installation procedure 2
- Changed figure title 4
- Deleted requirement to connect Aardvark ribbon cable last 7

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

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EVM Warnings and Restrictions

It is important to operate this EVM within the input voltage range of 7V to 36V and the output voltage range of 7V to 35V .

Exceeding the specified input range may cause unexpected operation and/or irreversible damage to the EVM. If there are questions concerning the input range, please contact a TI field representative prior to connecting the input power.

Applying loads outside of the specified output range may result in unintended operation and/or possible permanent damage to the EVM. Please consult the EVM User's Guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative.

During normal operation, some circuit components may have case temperatures greater than 85°C. The EVM is designed to operate properly with certain components above 85°C as long as the input and output ranges are maintained. These components include but are not limited to linear regulators, switching transistors, pass transistors, and current sense resistors. These types of devices can be identified using the EVM schematic located in the EVM User's Guide. When placing measurement probes near these devices during operation, please be aware that these devices may be very warm to the touch.

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      3.1.1 *Notice applicable to EVMs not FCC-Approved:*

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      CAUTION

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      NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- *Reorient or relocate the receiving antenna.*
- *Increase the separation between the equipment and receiver.*
- *Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.*
- *Consult the dealer or an experienced radio/TV technician for help.*

3.2 *Canada*

3.2.1 *For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210*

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This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

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Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur

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2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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